

Unification and combination of a class of traversal strategies made with pattern matching and fixed-points [☆]

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ARTICLE INFO

Article history:

Received 15 May 2020

Received in revised form 14 December 2021

Accepted 14 December 2021

Available online 17 December 2021

Keywords:

Traversal strategies

Unification

Combination

Fixed-point

μ -Calculus

ABSTRACT

Motivated by an ongoing project on computer aided derivation of asymptotic models governed by partial differential equations, we introduce a class of term transformations that consists of traversal strategies and insertion of contexts. We define unification and combination operations on this class which amount to merging transformations in order to obtain more complex ones. We show that the unification and combination operations enjoy nice algebraic properties like associativity, congruence and the existence of neutral elements. The main part of this paper is devoted to proving that the unification and combination operations are correct.

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[☆] This work was supported by LABEX ACTION ANR-11-LABX-0001-01 and by the European Territorial Cooperation Programme INTERREG IV project OSCAR.

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1. Introduction

The general context of this article is the incremental design of complex models using a notion of extension. The models we are considering are described by abstract terms and subjected to symbolic transformations. The latter are assumed to rely on two fundamental operations: the operation of extension that transforms a reference object to a more complex one by enriching it, and the operation of combination that merges several extensions to produce a new one that incorporates all the characteristics and effects of those used for its generation. This process is guided by the semantics of the objects in question, namely the way the extensions operate.

We briefly recall the background of this work. Our motivation originates in an undergoing project for the modeling and simulation of complex systems in micro or nano-technologies, e.g. [1–3]. The systems under consideration are governed by Partial Differential Equations (PDEs) and are too complex to be simulated by straightforward numerical methods, unless at the time-scale of design engineering. In addition, asymptotic methods for PDEs have been an active domain of mathematics for more than seventy years whose main goal is to derive “simpler” PDEs from those which have small parameters in their geometry or their equations. These methods are called singular perturbation methods in physics.

They are developed in all fields where PDEs are used for modeling ranging from physics, biology, finance etc, see for instance the review paper [4].

The use of asymptotic methods for modeling and simulation leads to reduced computation times while retaining the essence of the models. Nevertheless, they suffer from a major drawback which limits their diffusion in the community of engineers which is that their derivation is done on a case by case basis. In other words, for each new problem, the entire process of deriving the model must be redone from scratch even if the new problem has many functionalities in common with one or more problems already modeled. It follows that despite the immense number of existing models, relatively few of them are used in general simulation software.

Our group has adopted an alternative approach by developing a software package called MEMSALab (for MEMS Array Lab) [5] whose function is to build asymptotic models by successive extensions which intend to take into account different characteristics such as scalar or vector forms of solutions, various a priori estimates on the solutions and the sources, thinness or periodicity of geometries, several nested substructures, etc.

Our approach takes advantage of the modularity and the algebraic nature of asymptotic methods by following the approach presented in [6]. It is also based on the so-called *combination of extensions* [3] method that we are now sketching.

- First, remember that the construction of an asymptotic model operates on a PDE comprising small parameters. The construction of an asymptotic model consists in passing to the limit to zero on the small parameters which requires several proof steps leading to a new PDE. The latter can be implemented in generic simulation software. Among all pairs of input PDEs and proofs of asymptotic models, the simplest one is chosen, which is the pair of *reference PDE* and *reference proof*, from which the others can be constructed by successive complexifications. Technically, a proof is implemented by a rewriting strategy, that is to say by a series of transformations made up of rewriting rules accompanied by strategies which specify the way in which the rewriting rules are applied to PDEs.

- Second, the reference proof is complexified, we say that it is extended, in several ways to take into account new functionalities giving new proofs. This is done by applying an extension to the reference proof in so far as an extension is another kind of rewriting strategies. This results in an *extended proof*. Then, applying an extended proof to a complexified PDE yields a new asymptotic model.

- Finally, to cover several new elementary functionalities, we merge several elementary extensions by an operation of *combination*. The extension resulting from a combination can itself be applied to the reference proof. It follows a new proof which applied to a complex PDE produces an asymptotic model benefiting from all the characteristics.

To illustrate the concept of combination of extensions, consider the input PDE of reference and the proof of reference both containing the term $\partial_x v(x)$, an extension that adds an index j on the variable x of derivation and a second extension which adds an index i on the derived function v . The application of each of these two extensions to the reference term yields the terms $\partial_x v_i(x)$ and $\partial_{x_j} v(x)$, respectively. The combination of these two extensions would be another extension that, when applied to the reference term, yields $\partial_{x_j} v_i(x)$.

In summary, there are three levels for PDEs, proofs and extensions. A proof can be applied to a PDE, an extension to a proof, and extensions can be combined to produce new extensions. Therefore, combining extensions related to several elementary features allows for building, in an incremental way, new proofs and therefore new asymptotic models.

Although the concepts of extension and combination were introduced for the first time in [1], in that earlier work the combination of extensions was done by composition, not allowing for conflicts between extensions. A conflict between two extensions arises when they modify the same part of a proof and when the application of one of them creates new possibilities for the application of the other one. In that restricted framework, the combination of non conflicting extensions simply amounts to their composition. The complete principle of the extension-combination method was introduced in [3] where a user language was defined for specifying proofs and extensions as rewriting strategies. We also have defined the combination on a small class of extensions. However, the question of the correctness of the combination formulas was left open.

When defining a new class of strategies with an operation of combination, there are many difficulties to overcome. A careful attention must be paid to the choice of the constructors out of which these strategies are built up. There are two extreme ways to proceed. One way is to build the strategies by means of the most rudimentary constructors, as in [7]. This makes the strategies hard to use in practice due to their huge size. But the advantage of such rudimentary constructors is to allow one to understand the mechanisms behind the combination operation and to define it correctly. Even more, to proceed in this way was inevitable and justifies our work [7].

The other extreme way is to rather design high level strategy constructors which are easy to use in practice. But this makes it hard to understand the mechanisms behind the combination operation since a high level constructor hides several rudimentary constructors. For instance, given a rule r , the translation of the high level strategy $\text{OuterMost}(r)$ into rudimentary constructors requires three rudimentary constructors since $\text{OuterMost}(r)$ can be written as $\mu X.(r \oplus \text{Most}(X))$, where “ μ ” stands for the fixed-point or the recursion constructor, “ \oplus ” stands for the left-choice constructor, and “ Most ” is the one-step constructor that accesses to all the children of a term if viewed as a tree. In this case, one has to define the combination of two high level constructors in just one step which is usually difficult or even impossible. Furthermore, this raises the question of the closure of such class of strategies under combination since, for instance, the combination of two OuterMost s is not an OuterMost . In earlier attempts, we figured out that the combination of extensions based on high-level strategies such as BottomUp or TopDown or OuterMost can not be expressed with high-level strategies, making such a class not closed under combination. We thus understood that more rudimentary strategy constructors were needed.

In [7] we followed the first way and introduced the large class of *context embedding strategies*, or CE-strategies for short, that involves elementary and, more importantly, an explicit handling of failures which are produced when an application of an extension fails.

We proved the correctness of the combination operation for a fragment of the class of CE-strategies. The drawback of working with this class is that the definition of the traversal navigation strategies such as OuterMost yields a CE-strategy whose size depends on the signature. Even worse, the size of the resulting combined CE-strategy can be exponential with respect to the size of the two input CE-strategies. In this paper we overcome these difficulties by pursuing a third way which is in between the two extreme ways exposed above. We introduce another class of strategies, called the T_μ -strategies, which is built up using both high level and rudimentary constructors inspired by the propositional modal μ -calculus [8,9] rather than strategy languages as in [10]. The μ -calculus-like approach involves natural and rudimentary strategy constructors, especially the jumping to a position and the recursion with the fixed-point operator. This makes tractable the question of language closure for combinations. Moreover, the procedure of combination of T_μ -strategies together with their verification is also much simplified. Although this new class of T_μ -strategies is less expressive than the class of CE-strategies of [7], the new class remains powerful enough to be used in practice and its closure is harder to achieve since it incorporates high level and rudimentary constructors, this makes this paper more complete than [7], since the CE-strategies of [7] can not be used in practice because of their huge size. Besides, we define a unification and combination operations for the class of T_μ -strategies. Roughly speaking, the unification of two T_μ -strategies amounts to construct a T_μ -strategy that captures the effect of both insofar as they are compatible, where the compatibility of two T_μ -strategies depends on each input term and is related to their successful application. The incompatible effects are covered by the combination. This class enjoys similar algebraic properties as CE-strategies with respect to unification and combination, like associativity, congruence and the

existence of a neutral and an absorbing element. The main result of this paper shows that the unification and combination operations of T_μ -strategies are correct with respect to a correctness criterion that we shall devise and that is guided by the semantics of T_μ -strategies, Subsection 5.1.

We notice that the size of the resulting combined T_μ -strategy is polynomial with respect of the size of the two input T_μ -strategies. The T_μ -strategies are reasonably easy to use in practice and they have been implemented and used in MEMSALab software in the previous years within a user specification language of mathematical expressions, proofs and extensions and their combination for asymptotic models where the first applications targeted micro and nanotechnology [1–3].

The concept of extension, sometimes called refinement in the literature, is developed in different contexts such as the parallel and concurrent systems, for example in [11–13] the refinement is done by replacement of components with more complex components. Combination principles are present in different areas of application, they involve different techniques but follow the same key idea that consists of the merging of structures or algorithms motivated mainly by the incremental design of complex systems by integration of simple and heterogeneous subsystems. For instance, the works in combination of logics [14,15], algorithms and verification methods [16], decision procedures [17], the composition and synthesis for service-oriented and agent-oriented computing [18,19] in which the synchronous and asynchronous product of automata and transition systems are a form of combination, and the unification of grammars in linguistics [20–24]. However, the integration of the two concepts of extension and combination seems to have not been addressed in the literature.

Organization of the paper

The paper is organized as follows.

Section 2 is devoted to a review of the useful concepts of rewriting theory, and to definitions and notations.

In Section 3 we introduce the position-based T_μ -strategies and their combination.

In Section 4 we introduce the larger class of T_μ -strategies together with their semantics.

In Section 5 we give the unification procedure.

In Section 6 we state the results of this paper without proof, namely the correctness of the unification and combination and their algebraic properties.

In Section 7 we expose a detailed outline of the proof of the main result, that is, the correctness of the unification of T_μ -strategies.

In Section 8 we construct a mapping that is needed in the formulation of the correctness criterion of the unification and combination of T_μ -strategies.

In Section 9 we prove the correctness of the unification of the fixed-point free fragment of T_μ -strategies, that is, the T_μ -strategies without the fixed-point constructor.

In Sections 10, 11 and 12 we develop the notions and tools as well as the intermediary results required in the proof of the main result. This is the technical core of the paper.

In Section 13 we sum up the results of the previous three sections and prove the correctness of the unification and combination for the full class of T_μ -strategies, from which we prove the important algebraic properties of the unification and combination.

In Section 14 we give a summary, few concluding remarks and we announce future work.

To improve the readability of the paper, some proofs are given in the Appendix.

2. Preliminaries: terms, substitution, notations, rewriting

We introduce preliminary definitions and notations.

Terms, contexts Let $\mathcal{F} = \cup_{n \geq 0} \mathcal{F}_n$ be a set of symbols called *function symbols*. The *arity* of a symbol f in \mathcal{F}_n is n and is denoted $ar(f)$. Elements of arity zero are called *constants* and often denoted by the letters a, b, c , etc. The set \mathcal{F}_0 of constants is always assumed to be not empty. Given a denumerable set \mathcal{X} of *variable symbols*, the set of *terms* $\mathcal{T}(\mathcal{F}, \mathcal{X})$ is the smallest set containing \mathcal{X} and such that $f(t_1, \dots, t_n)$ is in $\mathcal{T}(\mathcal{F}, \mathcal{X})$ whenever $ar(f) = n$ and $t_i \in \mathcal{T}(\mathcal{F}, \mathcal{X})$ for $i \in [1..n]$. Let $\square \notin \mathcal{X}$ be an extra variable, the set $\mathcal{T}_\square(\mathcal{F}, \mathcal{X})$ of contexts, denoted simply by \mathcal{T}_\square , is made with terms with symbols in $\mathcal{F} \cup \mathcal{X} \cup \{\square\}$ which always includes exactly one occurrence of \square . Evidently, $\mathcal{T}_\square(\mathcal{F}, \mathcal{X})$ and $\mathcal{T}(\mathcal{F}, \mathcal{X})$ are two disjoint sets. For a term t and a context τ , we shall write $\tau[t]$ for the term that results from the replacement of \square by t in τ . We shall write simply \mathcal{T} (resp. \mathcal{T}_\square) instead of $\mathcal{T}(\mathcal{F}, \mathcal{X})$ (resp. $\mathcal{T}_\square(\mathcal{F}, \mathcal{X})$). We denote by $Var(t)$ the set of variables occurring in t . We shall write $ar(t)$ to mean the arity of the symbol at the root of t .

Positions, prefix-order, substitution Let t be a term in $\mathcal{T}(\mathcal{F}, \mathcal{X})$. The position ε is called the root position of t , and the function or variable symbol at this position is called the root symbol of t . A position in a tree is a sequence of integers, i.e., an element in $\mathbb{N}_\varepsilon^\omega = \{\varepsilon\} \cup \mathbb{N} \cup (\mathbb{N} \times \mathbb{N}) \cup \dots$. In particular we shall write \mathbb{N}_ε for $\{\varepsilon\} \cup \mathbb{N}$, such positions are called unitary positions. Given two positions $p = p_1 p_2 \dots p_n$ and $q = q_1 q_2 \dots q_m$, the *concatenation* of p and q , denoted by pq , is the position $p_1 p_2 \dots p_n q_1 q_2 \dots q_m$. We notice that in the examples, when we write, for instance, the position 12, we mean the concatenation of 1 and 2, and not the twelfth position.

The set of positions of the term t , denoted by $\mathcal{Pos}(t)$, is a set of positions of positive integers such that, if $t \in \mathcal{X}$ is a variable or $t \in \mathcal{F}_0$ is a constant, then $\mathcal{Pos}(t) = \{\varepsilon\}$. If $t = f(t_1, \dots, t_n)$ then $\mathcal{Pos}(t) = \{\varepsilon\} \cup \bigcup_{i=1,n} \{ip \mid p \in \mathcal{Pos}(t_i)\}$.

The prefix order defined as $p \leq q$ iff there exists p' such that $pp' = q$, is a partial order on positions. If $p' \neq \varepsilon$ then we obtain the strict order $p < q$. We write $(p \parallel q)$ iff p and q are incomparable with respect to \leq . The binary relations \sqsubset and \sqsubseteq defined by $p \sqsubset q$ iff $(p < q \text{ or } p \parallel q)$ and $p \sqsubseteq q$ iff $(p \leq q \text{ or } p \parallel q)$, are total relations on positions.

For any $p \in \mathcal{Pos}(t)$ we denote by $t|_p$ the subterm of t at position p , that is, $t|_\varepsilon = t$, and $f(t_1, \dots, t_n)|_{iq} = (t_i)|_q$. For a term t , we shall denote by $\delta(t)$ the depth of t , defined by $\delta(t_0) = 1$, if $t_0 \in \mathcal{X} \cup \mathcal{F}_0$ is a variable or a constant, and $\delta(f(t_1, \dots, t_n)) = 1 + \max(\delta(t_i))$, for $i = 1, \dots, n$. For any position $p \in \mathcal{Pos}(t)$ we denote by $t[s]_p$ the term obtained by replacing the subterm of t at position p by s : $t[s]_\varepsilon = s$ and $f(t_1, \dots, t_n)[s]_{iq} = f(t_1, \dots, t_i[s]_q, \dots, t_n)$.

A substitution is a mapping $\sigma : \mathcal{X} \rightarrow \mathcal{T}(\mathcal{F}, \mathcal{X})$ such that $\sigma(x) \neq x$ for only finitely many x 's. The finite set of variables that σ does not map to themselves is called the domain of σ : $\text{Dom}(\sigma) \stackrel{\text{def}}{=} \{x \in \mathcal{X} \mid \sigma(x) \neq x\}$. If $\text{Dom}(\sigma) = \{x_1, \dots, x_n\}$ then we write σ as: $\sigma = \{x_1 \mapsto \sigma(x_1), \dots, x_n \mapsto \sigma(x_n)\}$.

A substitution $\sigma : \mathcal{X} \rightarrow \mathcal{T}(\mathcal{F}, \mathcal{X})$ uniquely extends to an endomorphism $\widehat{\sigma} : \mathcal{T}(\mathcal{F}, \mathcal{X}) \rightarrow \mathcal{T}(\mathcal{F}, \mathcal{X})$ defined by: $\widehat{\sigma}(x) = \sigma(x)$ for all $x \in \text{Dom}(\sigma)$, $\widehat{\sigma}(x) = x$ for all $x \notin \text{Dom}(\sigma)$, and $\widehat{\sigma}(f(t_1, \dots, t_n)) = f(\widehat{\sigma}(t_1), \dots, \widehat{\sigma}(t_n))$ for $f \in \mathcal{F}$. In what follows we do not distinguish between a substitution and its extension.

For two terms $t, t' \in \mathcal{T}$, we say that t matches t' , written $t \ll t'$, iff there exists a substitution σ , such that $\sigma(t) = t'$. It turns out that if such a substitution exists, then it is unique. A substitution σ' is subsumed by a substitution σ iff $\sigma'(t)$ matches $\sigma(t)$ for any term t .

A most general unifier of the two terms t and t' is a substitution γ such that $\gamma(t) = \gamma(t')$ and, for any other substitution γ' satisfying $\gamma'(t) = \gamma'(t')$, we have that γ' is subsumed by γ . The most general unifier is unique up to a variable renaming.

The composition of functions will be denoted by “ \circ ”. The set of all subsets of a set S will be denoted by $\wp(S)$. For a finite set S , we write $|S|$ for the number of elements of S . For a finite set S of integers, the maximum (resp. minimum) of S will be denoted by $\max(S)$ (resp. $\min(S)$).

Lexicographic ordering A lexicographic ordering, denoted by “ $<$ ”, on the Cartesian product $\mathbb{N}^n = \mathbb{N} \times \dots \times \mathbb{N}$ (n -times), where $n \geq 1$, is inductively defined for any (a_1, \dots, a_n) and (b_1, \dots, b_n) in \mathbb{N}^n such that $(a_1, \dots, a_n) < (b_1, \dots, b_n)$ iff either $n = 1$, and in this case $a_1 < b_1$. Or $n \geq 2$, and in this case either i.) $a_1 < b_1$ or ii.) $a_1 = b_1$ and $(a_2, \dots, a_n) < (b_2, \dots, b_n)$.

3. Position-based \mathbb{T}_μ -strategies and their combination

The operation of combining \mathbb{T}_μ -strategies requires an abstract operation of merging contexts, a concrete example of which will be provided. The algebraic properties of the combination will be presented in the general case.

Definition 1 (Merging of contexts). Any associative binary operation

$$\cdot : \mathcal{T}_\square \times \mathcal{T}_\square \rightarrow \mathcal{T}_\square$$

is called *merging of contexts*.

Example 2 (Merging of contexts by composition). We give an example of the operation of merging of contexts, denoted by “ \cdot ”, as follows:

$$\tau \cdot \tau' = \tau[\tau']_{\mathcal{Pos}(\tau, \square)}$$

where $\mathcal{Pos}(t, \square)$ is the position of \square in t . This kind of merging has been introduced in [25] and implemented in MEMSALab software. For instance, the merging of the two contexts $\tau_1 = \text{Index}(\square, i)$ and $\tau_2 = \text{Index}(\square, j)$, used for inserting indices to mathematical variables or functions, is given by

$$\tau_1 \cdot \tau_2 = \tau_1[\tau_2]_1 = \text{Index}(\text{Index}(\square, j), i),$$

where i and j are terms.

To define the position-based \mathbb{T}_μ -strategies, we introduce two particular position-based strategies as follows. Firstly, for a position p and a context τ , we define the jump strategy $@p.\tau$ that, when applied to a term t , it inserts τ at the position p of t . Secondly, we define the failing strategy \mathfrak{f} that fails when applied to any term. Their precise semantics are given in Definition 5 of the semantics of position-based \mathbb{T}_μ -strategies.

Definition 3 (Position-based \mathbb{T}_μ -strategies). Let p_1, \dots, p_n be positions in \mathcal{Pos} and τ_1, \dots, τ_n be contexts in \mathcal{T}_\square with $n \geq 1$. A position-based \mathbb{T}_μ -strategy is either the failing strategy \mathfrak{f} or the ordered conjunction

$$\bigwedge_{i=1,n} @p_i.\tau_i.$$

The set of position-based T_μ -strategies is denoted by \mathcal{E} .

Notice that the order of positions in $\bigwedge_{i=1,n} @p_i.\tau_i$ matters. We impose that the position-based T_μ -strategies follow some constraints regarding the positions of insertions to avoid conflicts: the order of context insertions must go up from the leaves to the root. Formally,

Definition 4 (Well-founded position-based T_μ -strategy). Let p_1, \dots, p_n positions in \mathcal{Pos} and τ_1, \dots, τ_n be contexts in \mathcal{T}_\square with $n \geq 1$. A position-based T_μ -strategy E

$$E = \bigwedge_{i=1,n} @p_i.\tau_i$$

is well-founded iff

- i.) every position occurs at most once in E , i.e. $p_i \neq p_j$ for all $i \neq j$, and
- ii.) lower positions appear earlier in E , i.e. $i < j$ if $p_i \sqsubset p_j$, for all $i, j \in [1, n]$.

Moreover, the position-based T_μ -strategy f is well-founded.

In all what follows we work only with the set of well-founded position-based T_μ -strategies, still denoted by \mathcal{E} . For two position-based T_μ -strategies E and E' , we shall abuse of notation and write $E = E'$ to mean that they are equal up to a permutation of their parallel positions. For a position p , we let

$$@p. \bigwedge_{i=1,n} @p_i.\tau_i = \bigwedge_{i=1,n} @pp_i.\tau_i.$$

We next define the semantics of a position-based T_μ -strategy as a function in $\mathcal{T} \cup \{\mathbb{F}\} \rightarrow \mathcal{T} \cup \{\mathbb{F}\}$, with the idea that if the application of a position-based T_μ -strategy to a term fails, the result is \mathbb{F} . Besides, we adopt a stronger version of failure, that is, $\bigwedge_{i=1,n} @p_i.\tau_i$ fails when each of $@p_i.\tau_i$ fails. To formalize this notion of failure we need to introduce an intermediary function

$$\eta : (\mathcal{T} \cup \{\mathbb{F}\} \rightarrow \mathcal{T} \cup \{\mathbb{F}\}) \rightarrow \mathcal{T} \cup \{\mathbb{F}\} \rightarrow \mathcal{T} \cup \{\mathbb{F}\},$$

that stands for the *fail as identity*. It is defined for any function f in $\mathcal{T} \cup \{\mathbb{F}\} \rightarrow \mathcal{T} \cup \{\mathbb{F}\}$ and any term $t \in \mathcal{T} \cup \{\mathbb{F}\}$ by

$$(\eta(f))(t) = \begin{cases} f(t) & \text{if } f(t) \neq \mathbb{F}, \\ t & \text{otherwise.} \end{cases}$$

The semantics of position-based T_μ -strategies follows.

Definition 5 (Semantics of position-based T_μ -strategies). The semantics of a position-based T_μ -strategy E is a function $\llbracket E \rrbracket$ in $\mathcal{T} \cup \{\mathbb{F}\} \rightarrow \mathcal{T} \cup \{\mathbb{F}\}$ inductively defined by:

$$\begin{aligned} \llbracket f \rrbracket(t) &\stackrel{\text{def}}{=} \mathbb{F}, \\ \llbracket E \rrbracket(\mathbb{F}) &\stackrel{\text{def}}{=} \mathbb{F}, \\ \llbracket @p.\tau \rrbracket(t) &\stackrel{\text{def}}{=} \begin{cases} t[\tau[t|_p]]_p & \text{if } p \in \mathcal{Pos}(t) \\ \mathbb{F} & \text{otherwise,} \end{cases} \\ \llbracket \bigwedge_{i=1,n} @p_i.\tau_i \rrbracket(t) &\stackrel{\text{def}}{=} \begin{cases} \left((\eta(\llbracket @p_n.\tau_n \rrbracket)) \circ \dots \circ (\eta(\llbracket @p_1.\tau_1 \rrbracket)) \right)(t) & \text{if } \exists p_i \in \{p_1, \dots, p_n\} \text{ s.t. } p_i \in \mathcal{Pos}(t) \\ \mathbb{F} & \text{otherwise.} \end{cases} \end{aligned}$$

Two T_μ -strategies E and E' are said to be *semantically equivalent*, if and only if $\llbracket E \rrbracket(t) = \llbracket E' \rrbracket(t)$, for any term t .

Notice that two position-based T_μ -strategies are semantically equivalent iff they are equal up to a renaming of parallel positions.

Example 6. We illustrate with an example of position-based T_μ -strategies with their application to a term in MEMSALab. Consider the two contexts $\tau_1 = \text{Index}(\square, i)$ and $\tau_2 = \text{Index}(\square, j)$. Applying the position-based T_μ -strategy $@_{\varepsilon}.\tau_1$ to the term $t = \text{Var}(x, \Omega)$ gives the transformation of a space variable x defined on a domain Ω to its coordinate x_i . The procedure is given by

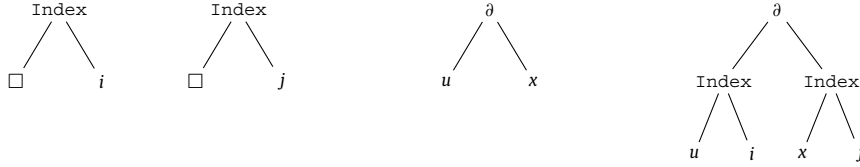


Fig. 1. The tree structure of the contexts $\tau_1 = \text{Index}(\square, i)$ and $\tau_2 = \text{Index}(\square, j)$, and the term $\partial_x u$. The term $\partial_{x_j} u_i$ results from the application of the position-based T_μ -strategy $@1.\tau_1 \wedge @2.\tau_2$ to $\partial_x u$, as discussed in Example 7.

$$\llbracket @_{\varepsilon}.\tau_1 \rrbracket(t) = t[\tau_1[t]_{\varepsilon}]_{\varepsilon} = t[\tau_1[t]_{\varepsilon}]_{\varepsilon} = \tau_1[t]_{\text{Pos}(\tau_1, \square)} = \text{Index}(\text{Var}(x, \Omega), i).$$

Let $\tau = \tau_1 \cdot \tau_2$, where “ \cdot ” stands for the operation of merging of contexts by composition as defined in Example 1. The application of the position-based T_μ -strategy $@_{\varepsilon}.\tau$ to the term t gives

$$\llbracket @_{\varepsilon}.\tau \rrbracket(t) = \tau[t]_{\text{Pos}(\tau_1[\tau_2], \square)} = \text{Index}(\text{Index}(\text{Var}(x, \Omega), j), i).$$

Example 7. We illustrate an application of a position-based T_μ -strategy on the derivative of a function represented by the term $t' = \partial_x u$, where u is the derived function, x is the mathematical variable and ∂_x the derivation operator with respect to x . Let $\tau_1 = \text{Index}(\square, i)$ and $\tau_2 = \text{Index}(\square, j)$ be contexts. The application of the position-based T_μ -strategy $@1.\tau_1 \wedge @2.\tau_2$ to t' yields the term $\partial_{x_j} u_i$. Since the positions 1 and 2 are parallel, this T_μ -strategy is well-founded and its application to t' yields

$$\llbracket @1.\tau_1 \wedge @2.\tau_2 \rrbracket(t') = (\llbracket @1.\tau_1 \rrbracket \circ \llbracket @2.\tau_2 \rrbracket)(t') = \llbracket @1.\tau_1 \rrbracket(\llbracket @2.\tau_2 \rrbracket(t')) = \partial_{x_j} u_i.$$

The tree structures of τ_1 , τ_2 , $\partial_x u$ and $\partial_{x_j} u_i$ are depicted in Fig. 1.

The unification of two position-based T_μ -strategies amounts to sort and merge their positions, and to merge their contexts if they are inserted at the same position. To simplify the following Definition 8, when unifying position-based T_μ -strategies E and E' in the general case (2), we can assume without loss of generality that each of them contains an insertion at the root position ε , because otherwise one can add to each of them the identity insertion $@_{\varepsilon}.\square$ that leaves unchanged any term to which it is applied.

Definition 8 (Unification of position-based T_μ -strategies). The unification of two position-based T_μ -strategies is the binary operation $\wedge : \mathcal{E} \times \mathcal{E} \longrightarrow \mathcal{E}$ defined as

1. (a) $\mathfrak{f} \wedge E = \mathfrak{f}$.
(b) $E \wedge \mathfrak{f} = \mathfrak{f}$.
2. If $E = \bigwedge_{p_i \in I} @p_i.\tau_i \wedge @_{\varepsilon}.\tau$ and $E' = \bigwedge_{q_j \in J} @q_j.\tau'_j \wedge @_{\varepsilon}.\tau'$, for two partially ordered sets I and J of positions, then

$$E \wedge E' = \bigwedge_{p_i \in I \cap J} @p_i.(\tau_i \cdot \tau'_i) \wedge R \wedge R' \wedge @_{\varepsilon}(\tau \cdot \tau'),$$

where

$$R = \bigwedge_{p_i \in I \setminus J} @p_i.\tau_i \quad \text{and} \quad R' = \bigwedge_{q_j \in J \setminus I} @q_j.\tau'_j.$$

Notice that since one can reorder the positions of $R \wedge R'$, then the unification of two well-founded position-based T_μ -strategies can be turned into an equivalent well-founded one, i.e. into a unique (up to a permutation of parallel positions) well-founded position-based T_μ -strategy.

Example 9. Consider position-based T_μ -strategies

$$E = @p_1.\tau_1 \wedge @p_2.\tau_2 \wedge @p_3.\tau_3 \quad \text{and} \quad E' = @p_1.\tau'_1 \wedge @q_1.\tau'_2 \wedge @q_2.\tau'_3,$$

and the sets of their positions are $P = \{p_1, p_2, p_3\}$ and $P' = \{p_1, q_1, q_2\}$, respectively. Hence $P \cup P' = \{p_1, p_2, p_3, q_1, q_2\}$ and $P \cap P' = \{p_1\}$. The unification of E and E' is

$$E \wedge E' = @p_1.(\tau'_1 \cdot \tau_1) \wedge @p_2.\tau_2 \wedge @p_3.\tau_3 \wedge @q_1.\tau'_2 \wedge @q_2.\tau'_3.$$

For practical reasons, we need to introduce the combination of two position-based T_μ -strategies in the same way as their unification apart that the combination of a position-based T_μ -strategy with the failure is the identity.

Definition 10 (Combination of two position-based T_μ -strategies). The combination of two position-based T_μ -strategies is a binary operation $\gamma : \mathcal{E} \times \mathcal{E} \longrightarrow \mathcal{E}$ defined for any E and E' in \mathcal{E} by

$$E \gamma E' = \begin{cases} E \wedge E' & \text{if } E \neq \mathfrak{f} \text{ and } E' \neq \mathfrak{f} \\ E & \text{if } E \neq \mathfrak{f} \text{ and } E' = \mathfrak{f} \\ E' & \text{if } E = \mathfrak{f}. \end{cases}$$

The algebraic properties of the unification and the combination of position-based T_μ -strategies are stated in the following Propositions 11 and 12, respectively.

Proposition 11. The set \mathcal{E} of position-based T_μ -strategies together with the unification operation enjoy the following properties.

1. The neutral element of the unification is $@\varepsilon.\square$,
2. The absorbing element of the unification is \mathfrak{f} ,
3. The unification is associative, i.e. $(E \wedge E') \wedge E'' = E \wedge (E' \wedge E'')$.
4. The unification of position-based T_μ -strategies is (non-)commutative if and only if the operation “ \cdot ” of merging of contexts is (non-)commutative.
5. The unification is idempotent if and only if the operation of merging of the contexts is idempotent, that is, $E \wedge E = E$ for any $E \in \mathcal{E}$ iff $\tau \cdot \tau = \tau$ for any contexts τ in \mathcal{T}_\square .

Proposition 12. The set \mathcal{E} of position-based T_μ -strategies together with the unification and combination operations enjoy the following properties.

1. The neutral element of the combination is \mathfrak{f} .
2. The combination is associative, i.e. $(E \gamma E') \gamma E'' = E \gamma (E' \gamma E'')$.
3. The combination of position-based T_μ -strategies is (non-)commutative if and only if the operation of merging of the contexts “ \cdot ” is (non-)commutative.
4. The combination is idempotent iff the operation “ \cdot ” of merging of contexts is idempotent.

The proof of these propositions does not provide any difficulties since the properties of associativity, (non-)commutativity, and idempotence of the unification and combination are inherited from their counterpart properties of the merging of contexts.

4. The class of T_μ -strategies

As far as the unification is concerned, designing a class of strategies faces the following challenging issues: 1.) finding the right class of extensions that is closed by combination: a less expressive class would not be closed under combination nor useful in practice, while very expressive extensions are impossible to combine, 2.) finding the right basic constructors of the extensions: very rudimentary constructors would make the size of the extensions very huge and non-practical, while more general constructors are very hard to combine, 3.) combining the “while” loops, or iterations, is the most difficult part and requires a special care, 4.) proving the correctness of the combination by taking into account the semantics of the extensions.

We introduced the position-based T_μ -strategies to clarify the ideas behind contexts, their insertion as well as their combination. However, position-based T_μ -strategies are not satisfactory for practical applications, since the positions are generally not flexible, not accessible and cannot be used on a regular basis in applications. So, we enrich this framework by supplementing position-based T_μ -strategies with navigation strategies to form a class of T_μ -strategies which is closed under combination.

Syntax and semantics of T_μ -strategies A T_μ -strategy is composed of two parts: a navigation of the input term without changing it, and an insertion of contexts at certain positions. The navigation part is built up using the left-choice constructor (\oplus), a conditional constructor “if-then”, a pattern-matching “ $u; S$ ” with a pattern u , the $\text{Most}(S)$ constructor that applies S to all the children of the input term, the jump constructor $@i.S$ to a position i as well as a conjunction of such jumps, and the fixed-point constructor (“ μ ”) allowing the recursion in the definition of strategies. The resulting class is called the class of T_μ -strategies, which stands for *traversal strategies with fixed-points*.

In what follows we assume that there is an enumerable set of *fixed-point variables* denoted by \mathcal{Z} . Fixed-point variables in \mathcal{Z} will be denoted by X, Y, Z, \dots

Definition 13 (Grammar of T_μ -strategies). The class of T_μ -strategies is defined by the following grammar:

$$S ::= \mathbf{f} \mid X \mid @_{\varepsilon}.\tau \mid u; S \mid S \oplus S \mid \mu X.S \mid @i.S \mid @i_1.S \wedge @i_2.S \mid \text{Most}(S) \mid \text{If } S \text{ Then } S$$

where X is a fixed-point variable in \mathcal{Z} , and τ is a context in \mathcal{T}_\square , and u is a term in \mathcal{T} , and i, i_1, i_2 are unitary positions in \mathbb{N}_ε . The set of T_μ -strategies will be denoted by \mathcal{C} . The subset of fixed-point free T_μ -strategies will be denoted by \mathcal{C}_0 .

Notations We shall write “**If** $S_1 \& S_2$ **Then** S ” instead of **If** S_1 **Then** (**If** S_2 **Then** S). If a set of positions I is empty, then the T_μ -strategy $\bigwedge_{i \in I} @i.S_i$ is just the failure \mathbf{f} .

We notice that extending the class of T_μ -strategies by allowing the position i of the jump constructor $@i.S$ to range over arbitrary positions in $\mathbb{N}_\varepsilon^\omega$ instead of unitary positions in \mathbb{N}_ε does not increase the expressiveness of the strategy language. This can be achieved by turning each T_μ -strategies $@p.S$, where p is a position in $\mathbb{N}_\varepsilon^\omega$ into $@q_1 \dots @q_n.S$, with $p = q_1 \dots q_n$ and each q_j is a unitary position in \mathbb{N}_ε .

The design of the class of T_μ -strategies is inspired by the μ -calculus formalism [8] since we need very rudimentary strategy constructors. In particular the jumping into the immediate positions of the term tree is morally similar to the diamond and box modalities $(\langle \cdot \rangle)$ and $([\cdot])$ of the propositional modal μ -calculus. And the fixed-point constructor is much finer than the iterate operator of e.g. [10]. Besides, we incorporate the left-choice strategy constructor and a pattern matching operation.

An occurrence of a fixed-point variable X is *bound* in a T_μ -strategy S if it is under the scope of a “ μX ”. Otherwise, it is said *free*. The set of bound variables of S will be denoted by $\text{Bound}(S)$. A T_μ -strategy is *closed* if all its fixed-point variables are bound. We shall sometimes write $S(X)$ to emphasize that the fixed-point variable X is free in $S(X)$.

Example 14. We informally illustrate the semantics of T_μ -strategies through an example. Consider the T_μ -strategy defined by $S(X) = (u; \tau) \oplus (@1.X)$ and its iteration $\mu X.S(X)$, where u is a term and τ is a context. When applied to a term t , the T_μ -strategy $\mu X.S(X)$ checks first whether u matches with t . If it is the case, then the context τ is inserted at the root of t and stops, yielding the term $\tau[t]$. Otherwise, the T_μ -strategy jumps to the position 1 of t , i.e. the left-most child of t , and reiterates the procedure by applying $\mu X.S(X)$ to this child. If it reaches the left-most leaf of t with which u does not match, then the T_μ -strategy $\mu X.S(X)$ fails on t . For instance, the application of $\mu X.S(X)$ to the term $f(v, f(u, f(u, a)))$ gives $f(v, f(\tau[u], f(u, a)))$, while it fails on $f(v, f(f(a, u), u))$.

Remark 15. Notice that a T_μ -strategy is composed of two parts: i.) a navigation part that consists of the navigation strategies that browse the input term without changing it. These strategies are the pattern matching, the left-choice, the iteration, the jump, the conjunction, the **Most**, and the “**if-then**”. And, ii.) an insertion part that modifies the input term and consists of an insertion of contexts.

Definition 16 (Unfolding). For any T_μ -strategy $S(X) \in \mathcal{C}$, and $n \geq 1$, we define the *unfolding* of $\mu X.S(X)$ which replaces the fixed-point operator on X by n -iterations as follows

$$\mu^0 X.S(X) \stackrel{\text{def}}{=} \mathbf{f} \quad \text{and} \quad \mu^n X.S(X) \stackrel{\text{def}}{=} S(\mu^{n-1} X.S(X)).$$

Example 17 (Unfolding). For a pattern $u \in \mathcal{T}$ and a context τ , let

$$S(X) = (u; @_{\varepsilon}.\tau) \oplus @1.X$$

be a T_μ -strategy. We give examples of the replacement of the fixed-point operator of $\mu X.S(X)$ by n -iterations, for $n = 0, 1, 2$, as follows:

$$\begin{aligned} \mu^0 X.S(X) &= \mathbf{f}. \\ \mu^1 X.S(X) &= S(\mu^0 X.S(X)) \\ &= S(\mathbf{f}) \\ &= (u; @_{\varepsilon}.\tau) \oplus @1.\mathbf{f}. \\ \mu^2 X.S(X) &= S(\mu^1 X.S(X)) \\ &= S((u; @_{\varepsilon}.\tau) \oplus @1.\mathbf{f}) \\ &= (u; @_{\varepsilon}.\tau) \oplus @1.((u; @_{\varepsilon}.\tau) \oplus @1.\mathbf{f}). \end{aligned}$$

The formal definition of the semantics of T_μ -strategies follows.

Definition 18 (Semantics of \mathbb{T}_μ -strategies). The semantics of a closed \mathbb{T}_μ -strategy S is the function $\llbracket S \rrbracket : \mathcal{T} \cup \mathbb{F} \rightarrow \mathcal{T} \cup \mathbb{F}$, which is defined inductively as follows.

$$\begin{aligned}
\llbracket f \rrbracket(t) &\stackrel{\text{def}}{=} \mathbb{F}. \\
\llbracket S \rrbracket(\mathbb{F}) &\stackrel{\text{def}}{=} \mathbb{F}. \\
\llbracket u; S \rrbracket(t) &\stackrel{\text{def}}{=} \begin{cases} \llbracket S \rrbracket(t) & \text{if } u \ll t, \\ \mathbb{F} & \text{otherwise.} \end{cases} \\
\llbracket @\varepsilon.\tau \rrbracket(t) &\stackrel{\text{def}}{=} \tau[t]. \\
\llbracket S_1 \oplus S_2 \rrbracket(t) &\stackrel{\text{def}}{=} \begin{cases} \llbracket S_1 \rrbracket(t) & \text{if } \llbracket S_1 \rrbracket(t) \neq \mathbb{F}, \\ \llbracket S_2 \rrbracket(t) & \text{otherwise.} \end{cases} \\
\llbracket \mu X.S(X) \rrbracket(t) &\stackrel{\text{def}}{=} \llbracket \mu^{\delta(t)} X.S(X) \rrbracket(t). \\
\llbracket \text{If } S_1 \text{ Then } S \rrbracket(t) &\stackrel{\text{def}}{=} \begin{cases} \llbracket S \rrbracket(t) & \text{if } \llbracket S_1 \rrbracket(t) \neq \mathbb{F}, \\ \mathbb{F} & \text{otherwise.} \end{cases} \\
\llbracket @p.S \rrbracket(t) &\stackrel{\text{def}}{=} \begin{cases} t[\llbracket S \rrbracket(t|_p)]_p & \text{if } \llbracket S \rrbracket(t|_p) \neq \mathbb{F} \text{ and } p \in \text{Pos}(t), \\ \mathbb{F} & \text{otherwise.} \end{cases} \\
\llbracket \bigwedge_{i=1,n} @p_i.S_i \rrbracket(t) &\stackrel{\text{def}}{=} \begin{cases} (\eta(\llbracket @p_n.S_n \rrbracket) \circ \dots \circ \eta(\llbracket @p_1.S_1 \rrbracket))(t) & \text{if } \exists i \in [1, n] \text{ s.t. } \llbracket @p_i.S_i \rrbracket(t) \neq \mathbb{F}, \\ \mathbb{F} & \text{otherwise.} \end{cases} \\
\llbracket \text{Most}(S) \rrbracket(t) &\stackrel{\text{def}}{=} \llbracket \bigwedge_{i=1, \text{ar}(t)} @i.S \rrbracket(t).
\end{aligned}$$

We shall refer to $\llbracket S \rrbracket(t)$ as the application of S to t .

Notice that when the application of $\bigwedge_{i=1,n} @p_i.S_i$ or of $\mu X.S(X)$ fails, it does not return the input term untouched (i.e. it does not behave as the identity), but fails as well. The reason is that we want a fine semantics that distinguishes between the identity that operates successfully and returns the input term (e.g. $@\varepsilon.\square$), and the failure that indicates that the \mathbb{T}_μ -strategy was not applied, which may launch other \mathbb{T}_μ -strategies. Notice also that $\bigwedge_{i=1,n} @p_i.S_i$ fails if and only if each $@p_i.S_i$ fails, and not just one of them fails. This is important because we want to make the semantics of \bigwedge_i compatible with that of Most in terms of failure, that is why we expressed the latter in terms of the former, and the only reason for that is to be able to unify \bigwedge_i with Most , see Section 5, and remaining in the same framework of \mathbb{T}_μ -strategies. Otherwise, a richer semantics in terms of handling the failure requires the framework [7] in which the failures are handled explicitly in the formalism, making it impractical.

The general definition of the semantics of the fixed-point constructor requires an unnecessary machinery involving Knaster-Tarski fixed-point theorem [26] and complete lattices. However, due to the particular nature of \mathbb{T}_μ -strategies, we gave an adhoc definition of the fixed-point \mathbb{T}_μ -strategy by $\llbracket \mu X.S(X) \rrbracket(t) \stackrel{\text{def}}{=} \llbracket \mu^{\delta(t)} X.S(X) \rrbracket(t)$, which is the same as that given by the least-fixed point. The justification of the iteration of $S(f)$ at most $\delta(t)$ times, the depth of t , is that the navigation part of a \mathbb{T}_μ -strategy does not change the input term t , see Remark 15 and Example 19. Therefore, either the \mathbb{T}_μ -strategy S progresses on the term t and will reach the leaves of t after at most $\delta(t)$ iterations, or S does not progress and in this case it fails after any iteration. Examples of \mathbb{T}_μ -strategies that do not progress are $\mu X.X$ and $\mu X.(u, X)$ for a term u . Technically, we show in Corollary 70 that, for every term t , the \mathbb{T}_μ -strategy $R = \mu^{\delta(t)} X.S(X)$ is a fixed-point of $S(X)$ in the sense that $\llbracket S(R) \rrbracket(t) = \llbracket R \rrbracket(t)$. Notice that any \mathbb{T}_μ -strategy of the form $\mu X.S(X, X)$, in which X occurs twice, can be turned into the equivalent \mathbb{T}_μ -strategy $\mu X.\mu Y.S(X, Y)$ in which X occurs once. This equivalence can be proved by induction on $S(X, X)$, and more generally it holds for any μ -calculus [8].

Example 19 (Semantics of \mathbb{T}_μ -strategies). We give two examples of \mathbb{T}_μ -strategies and their semantics. Let τ, τ' be contexts in \mathcal{T}_\square , and let $f(f(b))$ and $g(b, b', x)$ be terms in \mathcal{T} , where b, b' are constants, and x is a rewriting variable.

1. Consider the \mathbb{T}_μ -strategy

$$S(X) = (b; @\varepsilon.\tau) \oplus @1.X.$$

The \mathbb{T}_μ -strategy $\mu X.S(X)$ checks whether the constant b matches with an input term t , if it does then τ is inserted at the root of t (i.e. b) yielding $\tau[b]$, otherwise it jumps to the position 1 of t and iterates the same operation. We next

illustrate the application of $\mu X.S(X)$ to $f(f(b))$. Since the depth of $f(f(b))$ is $\delta(f(f(b))) = 3$, we need to compute $\mu^3 X.S(X)$, as we did for a similar T_μ -strategy in Example 17, thus we get:

$$\mu^3 X.S(X) = (b; @\varepsilon.\tau) \oplus @1.((b; @\varepsilon.\tau) \oplus @1.((b; @\varepsilon.\tau) \oplus @1.f)).$$

Hence the application of $\mu X.S(X)$ to $f(f(b))$ yields

$$\begin{aligned} \llbracket \mu X.S(X) \rrbracket(f(f(b))) &= \llbracket \mu^3 X.S(X) \rrbracket(f(f(b))) \\ &= \llbracket @1.((b; @\varepsilon.\tau) \oplus @1.((b; @\varepsilon.\tau) \oplus @1.f)) \rrbracket(f(b)) \\ &= \llbracket (b; @\varepsilon.\tau) \oplus @1.((b; @\varepsilon.\tau) \oplus @1.f) \rrbracket(b) \\ &= \llbracket b; @\varepsilon.\tau \rrbracket(b) \\ &= \llbracket @\varepsilon.\tau \rrbracket(b) \\ &= \tau[b]. \end{aligned}$$

2. Consider the T_μ -strategy

$$R(Y) = g(b, b', x); (@1.\tau \wedge @2.\tau' \wedge @3.Y).$$

The T_μ -strategy $\mu Y.R(Y)$ expects a term of the form $g(b, b', t')$, then it inserts τ on its first child (i.e. b), and inserts τ' on its second child (i.e. b'), then jumps to the third child (i.e. t') and iterates the same operation. Hence the application of $\mu Y.R(Y)$ to the term $g(b, b', g(b, b', b))$, which has depth 3, yields

$$\begin{aligned} \llbracket \mu Y.R(Y) \rrbracket(g(b, b', g(b, b', b))) &= \llbracket \mu^3 Y.R(Y) \rrbracket(g(b, b', g(b, b', b))) \\ &= \llbracket R(\mu^2 Y.R(Y)) \rrbracket(g(b, b', g(b, b', b))) \\ &= \llbracket g(b, b', x); (@1.\tau \wedge @2.\tau' \wedge @3.(\mu^2 Y.R(Y))) \rrbracket(g(b, b', g(b, b', b))) \\ &= \llbracket @1.\tau \wedge @2.\tau' \wedge @3.(\mu^2 Y.R(Y)) \rrbracket(g(b, b', g(b, b', b))) \\ &= g(\tau[b], \tau'[b'], \underbrace{\eta(\llbracket \mu^2 Y.R(Y) \rrbracket(g(b, b', b)))}_{t''}), \end{aligned}$$

hence

$$\begin{aligned} t'' &= \eta(\llbracket R(\mu^1 Y.R(Y)) \rrbracket(g(b, b', b))) \\ &= \eta(\llbracket g(b, b', x); (@1.\tau \wedge @2.\tau' \wedge @3.(\mu^1 Y.R(Y))) \rrbracket(g(b, b', b))) \\ &= g(\tau[b], \tau'[b'], \eta(\llbracket \mu^1 Y.R(Y) \rrbracket(b))) \\ &= g(\tau[b], \tau'[b'], \eta(\llbracket R(\mu^0 Y.R(Y)) \rrbracket(b))) \\ &= g(\tau[b], \tau'[b'], \eta(\llbracket R(f) \rrbracket(b))) \\ &= g(\tau[b], \tau'[b'], \eta(\llbracket g(b, b', x); (@1.\tau \wedge @2.\tau' \wedge @3.f) \rrbracket(b))) \\ &= g(\tau[b], \tau'[b'], b). \end{aligned}$$

Summing up, we get

$$\llbracket \mu Y.R(Y) \rrbracket(g(b, b', g(b, b', b))) = g(\tau[b], \tau'[b'], g(\tau[b], \tau'[b'], b)).$$

In the following example we show how to encode the two standard traversal strategies `OuterMost` and `InnerMost` in our formalism using the fixed-point constructor.

Example 20. In what follows we assume that S is a T_μ -strategy. We recall that, when applied to a term t , the T_μ -strategy `OuterMost`(S) tries to apply S to the maximum of the sub-terms of t starting from the root of t , it stops when it is successfully applied. And when applied to a term t , the T_μ -strategy `InnerMost`(S) tries to apply S to the maximum of the sub-terms of t starting from the leaves of t , it stops when it is successfully applied. Hence,

$$\text{OuterMost}(S) := \mu X.(S \oplus \text{Most}(X)) \quad \text{and} \quad \text{InnerMost}(S) := \mu X.(\text{Most}(X) \oplus S).$$

Definition 21. Let S, S' be \mathbb{T}_μ -strategies and $n \geq 1$ an integer. We shall write

- i) $S \equiv S'$ iff $\llbracket S \rrbracket = \llbracket S' \rrbracket$. In this case, S and S' are called *equivalent*.
- ii) $S \equiv_n S'$ iff $\llbracket S \rrbracket(t) = \llbracket S' \rrbracket(t)$ for any term t of depth $\delta(t) = n$. In this case, S and S' are called *n-equivalent*.

Notice that “ \equiv ” is an equivalence relation and that S and S' are equivalent iff they are n -equivalent for any $n \geq 1$.

5. Unification and combination of \mathbb{T}_μ -strategies

The problem now is to extend the operations of unification and combination of position-based \mathbb{T}_μ -strategies (i.e. Definitions 8 and 10) to the larger class of \mathbb{T}_μ -strategies. These two extensions must fulfill a correctness criterion that will be devised in Subsection 5.1. The subsequent subsections are devoted to the definition of the extension of unification (Definition 34) and the extension of the combination (Definition 35). Then we give an example of unification of \mathbb{T}_μ -strategies and comment it.

5.1. A correctness criterion for the extension of the unification and combination to \mathbb{T}_μ -strategies

Since there are many ways to define an extension of the unification operation from position-based \mathbb{T}_μ -strategies (i.e. the class \mathcal{E}) to \mathbb{T}_μ -strategies (i.e. the class \mathcal{C}), one needs a criterion that both guides the elaboration of a definition and ensures its correctness. Such a criterion should impose a compatibility between the unification operation upon \mathcal{E} and its extension to the larger class \mathcal{C} , in the sense that the former operation should stand as the basis for the latter.

For this purpose, out of a term in \mathcal{T} and a \mathbb{T}_μ -strategy in \mathcal{C} , we shall construct a unique (up to a permutation of parallel positions) position-based \mathbb{T}_μ -strategy in \mathcal{E} . That is, we shall define a mapping

$$\Psi : \mathcal{T} \longrightarrow \mathcal{C} \longrightarrow \mathcal{E}$$

that associates to any term t in \mathcal{T} and any closed \mathbb{T}_μ -strategy S in \mathcal{C} , a position-based \mathbb{T}_μ -strategy $(\Psi(t))(S)$ in \mathcal{E} , denoted simply by $\Psi_t(S)$, such that the semantic equivalence is preserved in the following sense:

$$\llbracket \Psi_t(S) \rrbracket(t) = \llbracket S \rrbracket(t). \quad (1)$$

Since the mapping Ψ takes into account the semantics, then the correctness criterion is nothing but the compatibility between the unification upon \mathcal{E} and its extension to \mathcal{C} , i.e. for any term t , the following two operations yield the same result:

- i.) the unification of two \mathbb{T}_μ -strategies in \mathcal{C} , followed by the mapping of the result to \mathcal{E} by Ψ_t , and
- ii.) the mapping of each of these two \mathbb{T}_μ -strategies to \mathcal{E} by Ψ_t , followed by the unification of the resulting position-based \mathbb{T}_μ -strategies.

This natural correctness criterion will be formalized in Definition 22 for both the unification and combination. However, to simplify the exposition we shall not define the mapping Ψ here but in Definition 46 of Section 8, since the statement of the main results does not require this definition. Furthermore, we shall show in Lemma 48 of Section 8 that the thus defined Ψ preserves the semantic equivalence in the sense of Eq. (1).

Definition 22 (Correctness criterion for the extension of \wedge and \vee). An extension $\wedge : \mathcal{C} \times \mathcal{C} \longrightarrow \mathcal{C}$ of the unification $\wedge : \mathcal{E} \times \mathcal{E} \longrightarrow \mathcal{E}$ is correct, if and only if, for every term $t \in \mathcal{T}$ and for every \mathbb{T}_μ -strategies S and R in \mathcal{C} , we have that

$$\Psi_t(S \wedge R) = \Psi_t(S) \wedge \Psi_t(R).$$

Similarly, an extension $\vee : \mathcal{C} \times \mathcal{C} \longrightarrow \mathcal{C}$ of the combination $\vee : \mathcal{E} \times \mathcal{E} \longrightarrow \mathcal{E}$ is correct, if and only if, for every term $t \in \mathcal{T}$ and for every \mathbb{T}_μ -strategies S and R in \mathcal{C} , we have that

$$\Psi_t(S \vee R) = \Psi_t(S) \vee \Psi_t(R).$$

That is, the following diagrams commute.

$$\begin{array}{ccc} \mathcal{C} \times \mathcal{C} & \xrightarrow{\wedge} & \mathcal{C} \\ \Psi_t \times \Psi_t \downarrow & & \downarrow \Psi_t \\ \mathcal{E} \times \mathcal{E} & \xrightarrow{\wedge} & \mathcal{E} \end{array} \quad \begin{array}{ccc} \mathcal{C} \times \mathcal{C} & \xrightarrow{\vee} & \mathcal{C} \\ \Psi_t \times \Psi_t \downarrow & & \downarrow \Psi_t \\ \mathcal{E} \times \mathcal{E} & \xrightarrow{\vee} & \mathcal{E} \end{array}$$

5.2. Sub- T_μ -strategies, memory and pre- T_μ -strategies

Since the unification of T_μ -strategies will be defined by induction, we need to define the notion of the set of sub- T_μ -strategies of a given T_μ -strategy. With a slight modification allowing $S(\mu X.S(X))$ to be in the set of such sub- T_μ -strategies of $\mu X.S(X)$, we also define the set of augmented sub- T_μ -strategies.

Definition 23 (Sub- T_μ -strategies of a T_μ -strategy). Given a T_μ -strategy S , we inductively define the finite set of sub- T_μ -strategies of S , denoted by $\Phi(S)$, as well as the finite set of augmented sub- T_μ -strategies of S , denoted by $\tilde{\Phi}(S)$, which are similar apart for the fixed-point T_μ -strategies:

$$\begin{aligned}
\Phi(f) &= \{f\}, & \tilde{\Phi}(f) &= \{f\}, \\
\Phi(X) &= \{X\}, & \tilde{\Phi}(X) &= \{X\}, \\
\Phi(@\varepsilon.\tau) &= \{@\varepsilon.\tau\}, & \tilde{\Phi}(@\varepsilon.\tau) &= \{@\varepsilon.\tau\}, \\
\Phi(u; S) &= \{u; S\} \cup \Phi(S), & \tilde{\Phi}(u; S) &= \{u; S\} \cup \tilde{\Phi}(S), \\
\Phi(@p.S) &= \{@p.S\} \cup \Phi(S), & \tilde{\Phi}(@p.S) &= \{@p.S\} \cup \tilde{\Phi}(S), \\
\Phi(S_1 \oplus S_2) &= \{S_1 \oplus S_2\} \cup \Phi(S_1) \cup \Phi(S_2), & \tilde{\Phi}(S_1 \oplus S_2) &= \{S_1 \oplus S_2\} \cup \tilde{\Phi}(S_1) \cup \tilde{\Phi}(S_2), \\
\Phi(\bigwedge_{i=1,n} S_i) &= \{\bigwedge_{i=1,n} S_i\} \cup \bigcup_{i=1,n} \Phi(S_i), & \tilde{\Phi}(\bigwedge_{i=1,n} S_i) &= \{\bigwedge_{i=1,n} S_i\} \cup \bigcup_{i=1,n} \tilde{\Phi}(S_i), \\
\Phi(\text{If } S_1 \text{ Then } S) &= \{\text{If } S_1 \text{ Then } S\} \cup \Phi(S_1) \cup \Phi(S), & \tilde{\Phi}(\text{If } S_1 \text{ Then } S) &= \{\text{If } S_1 \text{ Then } S\} \cup \tilde{\Phi}(S_1) \cup \tilde{\Phi}(S), \\
\Phi(\mu X.S(X)) &= \{\mu X.S(X)\} \cup \Phi(S(X)). & \tilde{\Phi}(\mu X.S(X)) &= \{\mu X.S(X)\} \cup \tilde{\Phi}(S(X)) \cup \Phi(S(\mu X.S(X))).
\end{aligned}$$

A T_μ -strategy R is said to be a sub- T_μ -strategy of S if R is in $\Phi(S)$.

Similarly, the set of all fixed-point sub- T_μ -strategies of S , denoted by $\Phi_\mu(S)$, as well as the set of all augmented fixed-point sub- T_μ -strategies of S , denoted by $\tilde{\Phi}_\mu(S)$, are defined similarly apart for the fixed-point T_μ -strategies:

$$\begin{aligned}
\Phi_\mu(f) &= \emptyset, & \tilde{\Phi}_\mu(f) &= \emptyset, \\
\Phi_\mu(X) &= \emptyset, & \tilde{\Phi}_\mu(X) &= \emptyset, \\
\Phi_\mu(@\varepsilon.\tau) &= \emptyset, & \tilde{\Phi}_\mu(@\varepsilon.\tau) &= \emptyset, \\
\Phi_\mu(u; S) &= \Phi_\mu(S), & \tilde{\Phi}_\mu(u; S) &= \tilde{\Phi}_\mu(S), \\
\Phi_\mu(@p.S) &= \Phi_\mu(S), & \tilde{\Phi}_\mu(@p.S) &= \tilde{\Phi}_\mu(S), \\
\Phi_\mu(S_1 \oplus S_2) &= \Phi_\mu(S_1) \cup \Phi_\mu(S_2), & \tilde{\Phi}_\mu(S_1 \oplus S_2) &= \tilde{\Phi}_\mu(S_1) \cup \tilde{\Phi}_\mu(S_2), \\
\Phi_\mu(\bigwedge_{i=1,n} S_i) &= \bigcup_{i=1,n} \Phi_\mu(S_i), & \tilde{\Phi}_\mu(\bigwedge_{i=1,n} S_i) &= \bigcup_{i=1,n} \tilde{\Phi}_\mu(S_i), \\
\Phi_\mu(\text{If } S_1 \text{ Then } S) &= \Phi_\mu(S_1) \cup \Phi_\mu(S), & \tilde{\Phi}_\mu(\text{If } S_1 \text{ Then } S) &= \tilde{\Phi}_\mu(S_1) \cup \tilde{\Phi}_\mu(S), \\
\Phi_\mu(\mu X.S(X)) &= \{\mu X.S(X)\} \cup \Phi_\mu(S(X)). & \tilde{\Phi}_\mu(\mu X.S(X)) &= \{\mu X.S(X)\} \cup \tilde{\Phi}_\mu(S(X)) \cup \Phi_\mu(S(\mu X.S(X))).
\end{aligned}$$

Clearly, $\Phi_\mu(S) \subset \Phi(S) \subset \tilde{\Phi}(S)$ and $\Phi_\mu(S) \subseteq \tilde{\Phi}_\mu(S)$ and $\tilde{\Phi}_\mu(S) \subseteq \tilde{\Phi}(S)$. Notice that if S is fixed-point free, then $\Phi(S) = \tilde{\Phi}(S)$ and $\Phi_\mu(S) = \tilde{\Phi}_\mu(S) = \emptyset$. Indeed, the set of augmented sub- T_μ -strategies $\tilde{\Phi}(S)$ is finite and this can be easily shown by induction on S . We illustrate the Definition 23 with the following example.

Example 24 (Of Φ , $\tilde{\Phi}$, Φ_μ and $\tilde{\Phi}_\mu$). For a given pattern $u \in \mathcal{T}$ and a context τ , let

$$S(X) = (u; @\varepsilon.\tau) \oplus @1.X$$

be a T_μ -strategy. Hence the sets $\Phi(\mu X.S(X))$, $\tilde{\Phi}(\mu X.S(X))$, $\Phi_\mu(\mu X.S(X))$ and $\tilde{\Phi}_\mu(\mu X.S(X))$ are easily computed as follows:

$$\begin{aligned}
\Phi(\mu X.S(X)) &= \{\mu X.S(X)\} \cup \Phi(S(X)) \\
&= \{\mu X.S(X)\} \cup \{S(X)\} \cup \{(u; @\varepsilon.\tau), (@\varepsilon.\tau), @1.X, X\} \\
&= \{\mu X.S(X), S(X), (u; @\varepsilon.\tau), (@\varepsilon.\tau), @1.X, X\},
\end{aligned}$$

and

$$\begin{aligned}
\tilde{\Phi}(\mu X.S(X)) &= \{\mu X.S(X)\} \cup \tilde{\Phi}(S(X)) \cup \Phi(S(\mu X.S(X))) \\
&= \{\mu X.S(X)\} \cup \Phi(S(X)) \cup \Phi(S(\mu X.S(X))) && \text{(Since } S(X) \text{ is fixed-point free)} \\
&= \{\mu X.S(X)\} \cup \Phi(S(X)) \cup \{S(\mu X.S(X))\} \cup \Phi((u; @ \varepsilon. \tau) \oplus @1. \mu X.S(X)) \\
&&& \text{(Definition of } S(\mu X.S(X))) \\
&= \{\mu X.S(X)\} \cup \Phi(S(X)) \cup \{S(\mu X.S(X))\} \cup \Phi(u; @ \varepsilon. \tau) \cup \Phi(@1. \mu X.S(X)) \\
&= \{\mu X.S(X)\} \cup \Phi(S(X)) \cup \{S(\mu X.S(X))\} \cup \Phi(u; @ \varepsilon. \tau) \cup \{@1. \mu X.S(X)\} \cup \Phi(\mu X.S(X)) \\
&= \{\mu X.S(X)\} \cup \{S(\mu X.S(X))\} \cup \{@1. \mu X.S(X)\} \cup \Phi(\mu X.S(X)) \\
&&& \text{(Since } \Phi(S(X)) \text{ and } \Phi(u; @ \varepsilon. \tau) \text{ are a subset of } \Phi(\mu X.S(X)) \\
&= \{\mu X.S(X)\} \cup \{S(\mu X.S(X))\} \cup \{@1. \mu X.S(X)\} \cup \{S(X), (u; @ \varepsilon. \tau), (@ \varepsilon. \tau), @1.X, X\} \\
&&& \text{(The expression of } \Phi((\mu X.S(X)) \text{ was computed above)} \\
&= \{\mu X.S(X), S(\mu X.S(X)), @1. \mu X.S(X), S(X), (u; @ \varepsilon. \tau), (@ \varepsilon. \tau), @1.X, X\}, \text{ and} \\
\Phi_{\mu}(\mu X.S(X)) &= \{\mu X.S(X)\}, \text{ and} \\
\tilde{\Phi}_{\mu}(\mu X.S(X)) &= \{\mu X.S(X)\}.
\end{aligned}$$

In the Example 24 above we have that $\Phi_{\mu}(\mu X.S(X)) = \tilde{\Phi}_{\mu}(\mu X.S(X))$, but this is not true in general as shown in the following remark.

Remark 25. The inclusion $\Phi_{\mu}(R) \subseteq \tilde{\Phi}_{\mu}(R)$ is strict in general, that is, there is a T_{μ} -strategy R such that $\Phi_{\mu}(R) \subsetneq \tilde{\Phi}_{\mu}(R)$. This is achieved by taking a T_{μ} -strategy R of the form:

$$R = \mu X. \mu Y. S(X, Y),$$

and noticing that the T_{μ} -strategy $\mu Y. S(R, Y)$ is neither in $\Phi_{\mu}(R)$ nor in $\Phi(R)$, but in $\tilde{\Phi}_{\mu}(R)$ and in $\tilde{\Phi}(R)$.

The unification of two T_{μ} -strategies will be given by means of a reduction system that requires storing a piece of information, called *memory*, related to the input T_{μ} -strategies. Roughly speaking, a memory is a set of triples where the first and the second element of each triple is a fixed-point sub- T_{μ} -strategy or an augmented T_{μ} -strategy, and the third element is a fixed-point variable. The idea behind the memory is that the unification of a fixed-point T_{μ} -strategy $\mu X.S(X)$ with a T_{μ} -strategy R amounts to the unification of $S(\mu X.S(X))$ with R , or more precisely, the unification of $\mu X.S(X)$ with R produces a T_{μ} -strategy $\mu Z.T(Z)$, where Z is a fresh-fixed point variable and $T(Z)$ is the unification of $S(\mu X.S(X))$ with R . To ensure that this process terminates we need to store the triple $(\mu X.S(X), R, Z)$ in the memory so that Z is produced whenever $\mu X.S(X)$ is unified again with R .

The formal definition of the memory follows.

Definition 26 (Memory). Given an enumerable set \mathcal{Z} of fixed-point variables, as well as two T_{μ} -strategies S and R , we define the set of all *memories* related to S and R with respect to \mathcal{Z} , denoted by $\mathfrak{M}_{\mathcal{Z}}(S, R)$ or simply by $\mathfrak{M}(S, R)$, as the following set of sets of triples:

$$\mathfrak{M}(S, R) = \wp\left(\left(\tilde{\Phi}_{\mu}(S) \times (\tilde{\Phi}(R) \setminus \mathcal{Z}) \times \mathcal{Z}\right) \cup \left((\tilde{\Phi}(S) \setminus \mathcal{Z}) \times \tilde{\Phi}_{\mu}(R) \times \mathcal{Z}\right)\right).$$

More generally, the set of all memories, denoted by \mathfrak{M} , is defined by

$$\mathfrak{M} = \bigcup_{S, R \in \mathcal{C}} \mathfrak{M}(S, R).$$

An element in $\mathfrak{M}(S, R)$ or in \mathfrak{M} is called a memory.

An example of a memory related to two T_{μ} -strategies follows.

Example 27 (Memory). For given patterns $u, u' \in \mathcal{T}$ and contexts τ, τ' , let

$$S(X) = (u; @ \varepsilon. \tau) \oplus @1.X \quad \text{and} \quad S'(X') = (u'; @ \varepsilon. \tau') \oplus @1.X'$$

be T_{μ} -strategies. From Example 24 above we have that

$$\begin{aligned}
\tilde{\Phi}(\mu X.S(X)) &= \{\mu X.S(X), S(\mu X.S(X)), @1. \mu X.S(X), S(X), (u; @ \varepsilon. \tau), (@ \varepsilon. \tau), @1.X, X\}, \text{ and} \\
\tilde{\Phi}(\mu X'.S'(X')) &= \{\mu X'.S'(X'), S(\mu X'.S'(X')), @1. \mu X'.S'(X'), S(X'), (u'; @ \varepsilon. \tau'), (@ \varepsilon. \tau'), @1.X', X'\}.
\end{aligned}$$

Given $\mathcal{Z} = \{Z_1, Z_2, \dots, Z_6\}$, we give an example of a memory \mathcal{M} related to $\mu X.S(X)$ and $\mu X'.S'(X')$ and \mathcal{Z} , i.e. $\mathcal{M} \in \mathfrak{M}_{\mathcal{Z}}(\mu X.S(X), \mu X'.S'(X'))$.

$$\mathcal{M} = \left\{ (\mu X.S(X), S'(X'), Z_1), \quad (S(X), \mu X'.S'(X'), Z_2), \right. \\ \left. (\mu X.S(X), @_{\varepsilon}.\tau', Z_3), \quad (@_{\varepsilon}.\tau, \mu X'.S'(X'), Z_4), \right. \\ \left. (\mu X.S(X), @1.X', Z_5), \quad (@1.X, \mu X'.S'(X'), Z_6) \right\}.$$

From now on we let \mathcal{Z} to be an enumerable set of fixed-point variables. Since the unification reduction system will handle two T_{μ} -strategies together with a memory, this new object is called a *Pre- T_{μ} -strategy* and defined next.

Definition 28 (*Pre- T_{μ} -strategies*). The class of *pre- T_{μ} -strategies* is defined by the following grammar:

$$P ::= S \mid \langle S, S', \mathcal{M} \rangle \mid u; P \mid P \oplus P \mid \mu X.P \mid @i.P \wedge @i'.P \mid \text{Most}(P) \mid \text{If } S \text{ Then } P$$

where S, S' are T_{μ} -strategies in \mathcal{C} , \mathcal{M} is a memory in \mathfrak{M} , X is a fixed-point variable in \mathcal{Z} , u is a term in \mathcal{T} and i, i' are unitary positions in \mathbb{N}_{ε} . The set of pre- T_{μ} -strategies will be denoted by \mathcal{P} .

Like in the modal μ -calculus, it is easier and convenient to work with T_{μ} -strategies that make progress when applied to a term. Making progress is guaranteed by a syntactic requirement, called *monotonicity*, that imposes that in each fixed-point sub- T_{μ} -strategy $\mu X.S(X)$ there is at least a position jump or a *Most* from the root of $S(X)$ to X .

Definition 29 (*Monotonicity of T_{μ} -strategies*). A T_{μ} -strategy T is *monotonic* if for any $\mu X.S(X) \in \Phi_{\mu}(T)$, there exist T_{μ} -strategies $S'(X)$ and $S''(X)$ each of which is a sub- T_{μ} -strategy of $S(X)$ such that $S'(X)$ is either of the form $@i.S''(X)$ where $i \in \mathbb{N}_{\varepsilon} \setminus \{\varepsilon\}$, or of the form *Most*($S''(X)$).

For instance, the T_{μ} -strategy $\mu X.((u; @_{\varepsilon}.\tau) \oplus @1.X)$ (resp. $\mu X.((u; @_{\varepsilon}.\tau) \oplus \text{Most}(X))$) is monotonic since there the jump “@1” (resp. “Most”) between μX and X . While $\mu X.((u; @_{\varepsilon}.\tau) \oplus X)$ is not monotonic.

We generalize next the condition of well-foundedness from position-based T_{μ} -strategies to T_{μ} -strategies.

Definition 30 (*Well-founded T_{μ} -strategies*). A T_{μ} -strategy S is *well-founded* iff every position-based T_{μ} -strategy that is a sub- T_{μ} -strategy of S is well-founded in the sense of Definition 4.

5.3. The procedure of unification of T_{μ} -strategies

From now on we shall abuse of language and refer to the extension of the unification operation from position-based T_{μ} -strategies to T_{μ} -strategies, as simply the unification of T_{μ} -strategies. Before giving the procedure of unification of T_{μ} -strategies, we need the following assumptions on the structure of T_{μ} -strategies.

Assumptions 31. Throughout this paper, each T_{μ} -strategy is well-founded, monotonic, closed, and in which each fixed-point variable appears once, and each of their sub- T_{μ} -strategies which is of the form $@i.S'$ or $\bigwedge_i @i.S_i$, is preceded by a pattern-matching, i.e. $u; @i.S'$ and $u; \bigwedge_i @i.S_i$.

These assumptions do not exclude interesting cases, since either they exclude cases which do not make sense (e.g. a T_{μ} -strategy with free fixed-point variables, or not well-founded), or they make the T_{μ} -strategies easier to handle in the proofs without missing interesting cases, for instance, imposing that each fixed-point variable appears once is not a restriction since each T_{μ} -strategy can be turned into a T_{μ} -strategy with such a property by applying the following simplification operations which preserve the semantic equivalence (i.e. a T_{μ} -strategy is semantically equivalent to its simplification).

Simplifications 32. The simplification operations of T_{μ} -strategies consist of:

- (i) renaming identical bound variables, for instance $\mu X.S(X) \oplus \mu X.R(X)$ can be turned into $\mu X.S(X) \oplus \mu Y.R(Y)$, this is known in the literature as the α -conversion, and
- (ii) renaming identical occurrences of variables if they are bound to the same fixed-point operator, for instance if $S(X, X)$ is a T_{μ} -strategy in which X appears twice, then we can turn $\mu X.S(X, X)$ into the equivalent T_{μ} -strategy $\mu X.\mu Y.S(X, Y)$, and
- (iii) removing useless μ contractors, i.e. turning $\mu X.S$ into S when X does not appear in S .

We define next the procedure of unification of T_{μ} -strategies by means of a reduction system that operates on pre- T_{μ} -strategies, in which the pattern u related to the position i in T_{μ} -strategy S will be denoted by $\text{Patt}(S, i)$, or simply by $\text{Patt}(i)$ when S is known.

Definition 33. We define the reduction system \mathcal{U} operating on pre- T_μ -strategies and consisting of the following reduction rules with a decreasing order of priority.

1. (a) $\langle f, S, \mathcal{M} \rangle \rightarrow f$.
(b) $\langle S, f, \mathcal{M} \rangle \rightarrow f$.
2. $\langle @\varepsilon.\tau, @\varepsilon.\tau', \mathcal{M} \rangle \rightarrow @\varepsilon.(\tau \cdot \tau')$.
3. (a) $\langle u; S, S', \mathcal{M} \rangle \rightarrow u; \langle S, S', \mathcal{M} \rangle$.
(b) $\langle S', (u; S), \mathcal{M} \rangle \rightarrow u; \langle S', S, \mathcal{M} \rangle$.
4. (a) $\langle @i.S, @i.S', \mathcal{M} \rangle \rightarrow @i. \langle S, S', \mathcal{M} \rangle$.
(b) If $S = \bigwedge_{i \in I} @i.S_i \wedge @\varepsilon.\tau$ and $S' = \bigwedge_{j \in J} @j.S'_j \wedge @\varepsilon.\tau'$ then

$$\langle S, S', \mathcal{M} \rangle \rightarrow \text{If } S \& S' \text{ Then } \bigwedge_{i \in I \cap J} @i. (\langle S_i, S'_i, \mathcal{M} \rangle \oplus S_i \oplus S'_i) \wedge R \wedge R' \wedge @\varepsilon.(\tau \cdot \tau'),$$

where

$$R = \bigwedge_{i \in I \setminus J} @i.S_i \quad \text{and} \quad R' = \bigwedge_{j \in J \setminus I} @j.S'_j.$$

5. (a) $\langle (S_1 \oplus S_2), S, \mathcal{M} \rangle \rightarrow \langle S_1, S, \mathcal{M} \rangle \oplus \langle S_2, S, \mathcal{M} \rangle$.
(b) $\langle S, (S_1 \oplus S_2), \mathcal{M} \rangle \rightarrow \langle S, S_1, \mathcal{M} \rangle \oplus \langle S, S_2, \mathcal{M} \rangle$.
6. (a) $\langle (\text{If } S_1 \text{ Then } S_2), S, \mathcal{M} \rangle \rightarrow \text{If } S_1 \text{ Then } \langle S_2, S, \mathcal{M} \rangle$.
(b) $\langle S, (\text{If } S_1 \text{ Then } S_2), \mathcal{M} \rangle \rightarrow \text{If } S_1 \text{ Then } \langle S, S_2, \mathcal{M} \rangle$.
7. (a) $\langle \text{Most}(S), \text{Most}(S'), \mathcal{M} \rangle \rightarrow \text{If}(\text{Most}(S) \& \text{Most}(S')) \text{Then Most}(\langle S, S', \mathcal{M} \rangle \oplus S \oplus S')$.
(b) $\langle \text{Most}(S), \bigwedge_{i \in I} @i.S_i, \mathcal{M} \rangle \rightarrow \langle \bigwedge_{i \in [1, ar(u)]} @i.S, \bigwedge_{i \in I} @i.S_i, \mathcal{M} \rangle$ where $u = \text{Patt}(i)$
(c) $\langle \bigwedge_{i \in I} @i.S_i, \text{Most}(S), \mathcal{M} \rangle \rightarrow \langle \bigwedge_{i \in I} @i.S_i, \bigwedge_{i \in [1, ar(u)]} @i.S, \mathcal{M} \rangle$ where $u = \text{Patt}(i)$
8. (a)

$$\underbrace{\langle \mu X. S(X), S', \mathcal{M} \rangle}_{\xi} \rightarrow \begin{cases} \mu Z. \langle S(\xi), S', \mathcal{M}' \rangle, & \text{if } (\xi, S', \cdot) \notin \mathcal{M}, \\ & \text{where } \begin{cases} Z = \text{fresh}(\xi, S'), \\ \mathcal{M}' = \mathcal{M} \cup \{(\xi, S', Z)\}. \end{cases} \\ Z & \text{if } (\xi, S', Z) \in \mathcal{M}. \end{cases}$$

(b)

$$\langle S', \underbrace{\mu X. S(X)}_{\xi}, \mathcal{M} \rangle \rightarrow \begin{cases} \mu Z. \langle S', S(\xi), \mathcal{M}' \rangle, & \text{if } (S', \xi, \cdot) \notin \mathcal{M}, \\ & \text{where } \begin{cases} Z = \text{fresh}(S', \xi), \\ \mathcal{M}' = \mathcal{M} \cup \{(S', \xi, Z)\}. \end{cases} \\ Z & \text{if } (S', \xi, Z) \in \mathcal{M}. \end{cases}$$

Explanation of the rules Notice that, by construction, for any tuple $\langle S, S', \mathcal{M} \rangle$ produced by the unification reduction system \mathcal{U} , the memory \mathcal{M} is redundancy free, that is, if (S_1, R_1, Z_1) and (S_1, R_1, Z_2) are in \mathcal{M} , then $Z_1 = Z_2$. We comment on the key points in Definition 33.

Pattern matching: If we omit the memory \mathcal{M} in the rule 3a for sake of simplicity, then the unification of $u; S$ with S' is naturally $u; S''$, where S'' is the unification of S with S' , since we want that the pattern u proceeds the merging of S and S' .

Most: For the unification of two Most s (i.e. rule 7a), we first recall the semantics of this constructor. When a T_μ -strategy $\text{Most}(S)$ is applied to term t , the T_μ -strategy S is applied to each of its children. In particular, $\text{Most}(S)$ fails on t if and only if S fails on each of t 's children. Otherwise, when $\text{Most}(S)$ succeeds on t , then S behaves as the identity on the children of t on which it fails, see Definition 18. While unifying two T_μ -strategies $\text{Most}(S)$ and $\text{Most}(S')$ we need to distinguish two cases. (i) If one of these T_μ -strategies fails, then the result should fail. This is achieved by the condition $\text{If}(\text{Most}(S) \& \text{Most}(S'))$ in the resulting T_μ -strategy. (ii) If both of them do not fail when applied to a term t then we need to consider whether each of them fails or not on each child of t . In order to explain the $\text{Most}(\langle S, S', \mathcal{M} \rangle \oplus S \oplus S')$ part in the resulting unified T_μ -strategy, let t_i be a child of t , and consider the four cases:

- (ii.1) if both of S and S' succeeds on t_i , then we need to consider their unification. This explains the $\langle S, S', \mathcal{M} \rangle$ part.
- (ii.2) If both of them fails on t_i , then their unification should fail on t_i as well. But this holds since $\langle S, S', \mathcal{M} \rangle \oplus S \oplus S'$ fails as well.
- (ii.3) If S succeeds on t_i while S' fails on it, then the resulting unified T_μ -strategy should apply S to t_i . But this is achieved by $\langle S, S', \mathcal{M} \rangle \oplus S \oplus S'$ which is equal to S since $\langle S, S', \mathcal{M} \rangle$ fails on t_i .
- (ii.4) If S fails on t_i while S' succeeds on it, then this case is symmetric to the previous one.

The unification of $\text{Most}(S)$ with a conjunction of position jumps $\bigwedge_{i \in I} @i.S_i$ requires that we encode $\text{Most}(S)$ into a conjunction of position jumps as well.

Fixed-points: The idea behind the unification of $\mu X.S(X)$ with R (i.e. rule 8a) is to unfold $\mu X.S(X)$ to $S(\mu X.S(X))$ and then to unify $S(\mu X.S(X))$ with R . Indeed this process is terminating thanks to the use of memory since we memorized that we passed through the unification of $\mu X.S(X)$ with R and we generated a fresh fixed-point variable Z , this is done by adding the tuple $(\mu X.S(X), R, Z)$ to the memory. Thanks to the memory, the next time we face the unification of $\mu X.S(X)$ with R , we shall produce Z .

We shall show in Subsection 10.2 that the unification system \mathcal{U} is terminating and confluent. This allows us to define the unification operation in terms of the normal form with respect to \mathcal{U} . The normal form of $\langle S, S', \emptyset \rangle$ will be denoted by $\mathcal{NF}\langle S, S', \emptyset \rangle$. The definition of the unification and combination of T_μ -strategies follow. We emphasize that throughout this paper, as far as we are dealing with the unification and combination, we assume that the two sets of the fixed-point variables of the two input T_μ -strategies are disjoint.

Definition 34 (Unification of T_μ -strategies). The unification of T_μ -strategies is the binary operation $\wedge : \mathcal{C} \times \mathcal{C} \longrightarrow \mathcal{C}$, defined for any S and S' in \mathcal{C} by

$$S \wedge S' \stackrel{\text{def}}{=} \mathcal{NF}\langle S, S', \emptyset \rangle.$$

Notice that the unification of two T_μ -strategies yields a T_μ -strategy that captures the effect of both insofar as they are compatible, where the compatibility of two T_μ -strategies depends on each input term and is related to their successful application. That is, if S and S' can be applied successfully to a term t , then the application of their unification $S \wedge S'$ on t succeeds as well and reproduces the effect that S and S' being applied simultaneously. However, the incompatible effects are covered by the combination in the sense that if $S \wedge S'$ fails on a term t , then S or S' fails, and the combination returns the non-failing one, if any. This justifies the following definition of the combination.

Definition 35 (Combination of T_μ -strategies). The combination of T_μ -strategies is the binary operation $\gamma : \mathcal{C} \times \mathcal{C} \longrightarrow \mathcal{C}$, defined for any S and S' in \mathcal{C} by

$$S \gamma S' \stackrel{\text{def}}{=} (S \wedge S') \oplus S \oplus S'.$$

Example 36 (Unification of T_μ -strategies). We give an example of the unification of two fixed-point T_μ -strategies. For given patterns $u, u' \in \mathcal{T}$ and contexts τ, τ' , let

$$\begin{aligned} S(X) &= (u; @\varepsilon.\tau) \oplus @1.X & \text{and} & & S'(X') &= (u'; @\varepsilon.\tau') \oplus @1.X' \\ \xi &= \mu X.S(X) & \text{and} & & \xi' &= \mu X'.S'(X') \end{aligned}$$

be T_μ -strategies. We compute the unification $\mu X.S(X) \wedge \mu X'.S'(X')$ which is the normal form of the tuple $\langle \mu X.S(X), \mu X'.S'(X'), \emptyset \rangle$ by applying the reduction rules of \mathcal{U} given in Definition 33. Let

$$\begin{aligned} (*) &= \langle \mu X.S(X), \mu X'.S'(X'), \emptyset \rangle \\ &\rightarrow \mu Z.\langle S(\xi), \xi', \{(\xi, \xi', Z)\} \rangle && \text{(Rule 8a)} \\ &\rightarrow \mu Z.\mu Z'.\langle S(\xi), S'(\xi'), \underbrace{\{(\xi, \xi', Z), (S(\xi), \xi', Z')\}}_{\mathcal{M}} \rangle && \text{(Rule 8b)} \\ &= \mu Z.\mu Z'.\langle (u; @\varepsilon.\tau) \oplus @1.\xi, S'(\xi'), \mathcal{M} \rangle && \text{(Def. of } S(X)) \\ &\rightarrow \mu Z.\mu Z'.\left(\underbrace{\langle u; @\varepsilon.\tau, S'(\xi'), \mathcal{M} \rangle}_{(I)} \oplus \underbrace{\langle @1.\xi, S'(\xi'), \mathcal{M} \rangle}_{(II)} \right). && \text{(Rule 5a)} \\ (I) &\rightarrow u; \langle @\varepsilon.\tau, S'(\xi'), \mathcal{M} \rangle && \text{(Rule 3a)} \\ &= u; \langle @\varepsilon.\tau, (u'; @\varepsilon.\tau') \oplus @1.\xi', \mathcal{M} \rangle && \text{(Def. of } S'(X')) \end{aligned}$$

$$\rightarrow u; (\langle @ \varepsilon. \tau, u'; @ \varepsilon. \tau', \mathcal{M} \rangle \oplus \langle @ \varepsilon. \tau, @ 1. \xi', \mathcal{M} \rangle) \quad (\text{Rule 5b})$$

$$\rightarrow u; ((u'; \langle @ \varepsilon. \tau, @ \varepsilon. \tau', \mathcal{M} \rangle) \oplus \langle @ \varepsilon. \tau, @ 1. \xi', \mathcal{M} \rangle) \quad (\text{Rule 3b})$$

$$\rightarrow u; ((u'; @ \varepsilon. (\tau \cdot \tau')) \oplus \langle @ \varepsilon. \tau, @ 1. \xi', \mathcal{M} \rangle) \quad (\text{Rule 2})$$

$$\rightarrow u; ((u'; @ \varepsilon. (\tau \cdot \tau')) \oplus (\text{If } @ 1. \xi' \text{ Then } @ 1. \xi' \wedge @ \varepsilon. \tau)). \quad (\text{Rule 4b})$$

$$(II) = \langle @ 1. \xi, (u'; @ \varepsilon. \tau') \oplus @ 1. \xi', \mathcal{M} \rangle \quad (\text{Def. of } S'(X'))$$

$$\rightarrow \langle @ 1. \xi, u'; @ \varepsilon. \tau', \mathcal{M} \rangle \oplus \langle @ 1. \xi, @ 1. \xi', \mathcal{M} \rangle \quad (\text{Rule 5b})$$

$$\rightarrow (u'; \langle @ 1. \xi, @ \varepsilon. \tau', \mathcal{M} \rangle) \oplus \langle @ 1. \xi, @ 1. \xi', \mathcal{M} \rangle \quad (\text{Rule 3b})$$

$$\rightarrow (u'; (\text{If } @ 1. \xi \text{ Then } @ 1. \xi \wedge @ \varepsilon. \tau')) \oplus \langle @ 1. \xi, @ 1. \xi', \mathcal{M} \rangle \quad (\text{Rule 4b})$$

$$= (u'; \text{If } @ 1. \xi \text{ Then } @ 1. \xi \wedge @ \varepsilon. \tau') \oplus @ 1. \langle \xi, \xi', \mathcal{M} \rangle \quad (\text{Rule 4a})$$

$$= (u'; \text{If } @ 1. \xi \text{ Then } @ 1. \xi \wedge @ \varepsilon. \tau') \oplus @ 1. Z. \quad (\text{Rule 8a since } (\xi, \xi', Z) \in \mathcal{M})$$

Summing up, the unification $(**)$ of $\mu X.S(X)$ and $\mu X'.S'(X')$ is:

$$\begin{aligned} (**) &= \mu X.S(X) \wedge \mu X'.S'(X') \\ &= \mu Z. \mu Z'. \left(u; ((u'; @ \varepsilon. (\tau \cdot \tau')) \oplus (\text{If } @ 1. \xi' \text{ Then } @ 1. \xi' \wedge @ \varepsilon. \tau)) \right. \\ &\quad \left. \oplus (u'; \text{If } @ 1. \xi \text{ Then } @ 1. \xi \wedge @ \varepsilon. \tau') \right. \\ &\quad \left. \oplus @ 1. Z \right). \end{aligned}$$

Notice that the fixed-point variable Z' does not appear in the resulting T_μ -strategy and therefore “ $\mu Z'$ ” can be removed. The application of the resulting T_μ -strategy $(**)$ to a term t features four cases.

- i.) Either both u and u' match with t , and in this case the context $\tau' \cdot \tau$ is inserted at the root of t .
- ii.) Or only u matches with t , and in this case τ is inserted at the position 1 of t provided the T_μ -strategy $\mu X'.S'(X')$ is applied successfully at the position 1 of t .
- iii.) Or only u' matches with t , and in this case τ' is inserted at the position 1 of t provided the T_μ -strategy $\mu X.S(X)$ is applied successfully at the position 1 of t .
- iv.) Or both $\mu X.S(X)$ and $\mu X'.S'(X')$ are applied at the position 1 of t .

The unification of two T_μ -strategies in which each fixed-point variable appears once may yield a T_μ -strategy in which a variable appears many times or does not appear at all, e.g. the Z' in the Example 36. An attention will be paid to this issue since this assumption on the occurrences of fixed-point variables is not preserved by unification. However, other assumptions listed in Assumptions 31 are preserved. Namely, it is easy to show that the unification of two well-founded T_μ -strategies is a well-founded one. And we shall show later that the unification of two monotonic T_μ -strategies is a monotonic one as well.

6. Statement of the results

In this section we state the main results of this paper, that is, the correctness of the procedure of unification and combination stated in Subsection 6.1, and the algebraic properties of the unification and combination of T_μ -strategies stated in Subsection 6.2. The proofs of these results can be found in Section 13.

6.1. Correctness of the unification and combination procedures

Theorem 37 (Correctness of the unification). *The unification of T_μ -strategies is correct. That is, for every term $t \in \mathcal{T}$ and for every T_μ -strategies S and R in \mathcal{C} , we have that*

$$\Psi_t(S \wedge R) = \Psi_t(S) \wedge \Psi_t(R).$$

Theorem 38 (Correctness of the combination). *The combination of T_μ -strategies is correct. That is, for every term $t \in \mathcal{T}$ and for every T_μ -strategies S and R in \mathcal{C} , we have that*

$$\Psi_t(S \vee R) = \Psi_t(S) \vee \Psi_t(R).$$

6.2. Algebraic properties of the unification and combination

The existence of the neutral elements and the associativity property of the unification and combination are obvious for the sub-class of position-based \mathbb{T}_μ -strategies but they are far from being so for the larger class of \mathbb{T}_μ -strategies, and it is crucial and useful to have them. Namely, a user of \mathbb{T}_μ -strategies needs know the algebraic properties of the structure he handles. For instance, he needs combine many \mathbb{T}_μ -strategies, and thus needs to know if this combination is associative and/or commutative. Besides, the properties of the neutral and absorbing elements allow one to simplify \mathbb{T}_μ -strategies.

We notice that the neutral elements and the associativity property of the unification and combination must be understood at the semantic level and not at the syntactic level since there are \mathbb{T}_μ -strategies which are syntactically different but semantically equivalent. For instance, the \mathbb{T}_μ -strategies $@_\varepsilon.\square$ and $(x; @_\varepsilon.\square)$ and $(x; @_\varepsilon.\square) \oplus (y; @_\varepsilon.\square)$, where x, y are variables, are all equivalent. More generally, the algebraic properties of the unification and combination will be formulated in terms of equivalence classes of \mathbb{T}_μ -strategies (with respect to the semantic equivalence relation) rather than syntactic \mathbb{T}_μ -strategies.

Technically speaking, since the semantic equivalence “ \equiv ” (Definition 21) is an equivalence relation, we shall use the standard notation $[S]$ for the equivalence class of the \mathbb{T}_μ -strategy S , i.e. $[S] = \{S' \in \mathcal{C} \mid S' \equiv S\}$, and the notation \mathcal{C}/\equiv for the quotient set of \mathcal{C} by “ \equiv ”, i.e. $\mathcal{C}/\equiv = \{[S] \mid S \in \mathcal{C}\}$. Moreover, the unification and combination of the equivalence classes of \mathbb{T}_μ -strategies in \mathcal{C}/\equiv can be defined in a natural way as:

$$[S_1] \wedge [S_2] := [S_1 \wedge S_2] \quad [S_1] \vee [S_2] := [S_1 \vee S_2].$$

We notice that these two operations are well defined since they are a congruence by Theorems 41 and 42. The algebraic properties of the unification of \mathbb{T}_μ -strategies follow. In fact, the unification of \mathbb{T}_μ -strategies inherits the properties of associativity, (non-)commutativity and idempotence from the position-based \mathbb{T}_μ -strategies and the merging of contexts.

Theorem 39. *The quotient set \mathcal{C}/\equiv of \mathbb{T}_μ -strategies together with the unification operation enjoy the following properties.*

1. The neutral element of the unification upon \mathcal{C}/\equiv is $[@_\varepsilon.\square]$.
2. The absorbing element of the unification is $\{f\}$.
3. The unification of \mathbb{T}_μ -strategies is associative, i.e. $([S_1] \wedge [S_2]) \wedge [S_3] = [S_1] \wedge ([S_2] \wedge [S_3])$, for any $S_1, S_2, S_3 \in \mathcal{C}$.
4. The unification of \mathbb{T}_μ -strategies is (non-)commutative if and only if the operation of merging of contexts “ \cdot ” is (non-) commutative.
5. The unification of \mathbb{T}_μ -strategies is idempotent if and only if the operation of merging of contexts is idempotent, that is, $[S] \wedge [S] = [S]$ for any $S \in \mathcal{C}$ iff $\tau \cdot \tau = \tau$ for any context τ in $\mathcal{T}_\mathcal{C}$.

The algebraic properties of the combination of \mathbb{T}_μ -strategies follow. In fact, the combination of \mathbb{T}_μ -strategies inherits the properties of associativity, (non-)commutativity and idempotence from the position-based \mathbb{T}_μ -strategies and the merging of contexts.

Theorem 40. *The quotient set \mathcal{C}/\equiv of \mathbb{T}_μ -strategies together with the combination operation enjoy the following properties.*

1. The neutral element of the combination upon \mathcal{C}/\equiv is $\{f\}$.
2. The combination of \mathbb{T}_μ -strategies is associative, i.e. $([S_1] \vee [S_2]) \vee [S_3] = [S_1] \vee ([S_2] \vee [S_3])$, for any $S_1, S_2, S_3 \in \mathcal{C}$.
3. The combination of \mathbb{T}_μ -strategies is (non-)commutative if and only if the operation of merging of contexts “ \cdot ” is (non-) commutative.
4. The combination of \mathbb{T}_μ -strategies is idempotent if and only if the operation of merging of contexts is idempotent.

Since the mapping $\Psi : \mathcal{T} \longrightarrow \mathcal{C} \longrightarrow \mathcal{E}$ preserves the semantic equivalence in the sense of Eq. (1), then Ψ induces a mapping $\dot{\Psi} : \mathcal{T} \longrightarrow \mathcal{C}/\equiv \longrightarrow \mathcal{E}$ in a natural way by $\dot{\Psi}_t([S]) := \Psi_t(S)$, for any term t in \mathcal{T} and \mathbb{T}_μ -strategy S in \mathcal{C} . It turned out that, for any term t , the mapping $\dot{\Psi}_t : \mathcal{C}/\equiv \longrightarrow \mathcal{E}$ is a morphism from the structure $(\mathcal{C}/\equiv, \wedge, \vee, [@_\varepsilon.\square], \{f\})$ to $(\mathcal{E}, \wedge, \vee, @_\varepsilon.\square, f)$ since for any \mathbb{T}_μ -strategies S_1 and S_2 in \mathcal{C} , on the one hand,

$$\dot{\Psi}_t([@_\varepsilon.\square]) = @_\varepsilon.\square \quad \text{and} \quad \dot{\Psi}_t(\{f\}) = f,$$

and on the other hand, it follows from Theorems 37 and 38 that

$$\dot{\Psi}_t([S_1] \wedge [S_2]) = \dot{\Psi}_t([S_1]) \wedge \dot{\Psi}_t([S_2]) \quad \text{and} \quad \dot{\Psi}_t([S_1] \vee [S_2]) = \dot{\Psi}_t([S_1]) \vee \dot{\Psi}_t([S_2]).$$

The congruence and non-degeneracy of the unification and combination are stated in the two following theorems, respectively.

Theorem 41 (Congruence and non-degeneracy of the unification). *The following holds.*

1. The unification of \mathbb{T}_μ -strategies is a congruence, that is, for any \mathbb{T}_μ -strategies S_1, S_2, S in \mathcal{C} , we have that:

$$\text{If } S_1 \equiv S_2 \quad \text{then} \quad S_1 \wedge S \equiv S_2 \wedge S \quad \text{and} \quad S \wedge S_1 \equiv S \wedge S_2.$$

2. The unification is non-degenerate, that is, for any T_μ -strategies $[S]$ and $[S']$ in $C \equiv$, we have that

$$[S] \wedge [S'] = [f] \quad \text{iff} \quad [S] = [f] \text{ or } [S'] = [f].$$

Theorem 42 (Congruence and non-degeneracy of the combination). *The following hold.*

1. The combination of T_μ -strategies is a congruence, that is, for any T_μ -strategies S_1, S_2, S in C , we have that:

$$\text{If } S_1 \equiv S_2 \quad \text{then} \quad S_1 \vee S \equiv S_2 \vee S \text{ and } S \vee S_1 \equiv S \vee S_2.$$

2. The combination is non-degenerate, that is, for any T_μ -strategies $[S]$ and $[S']$ in $C \equiv$, we have that

$$[S] \vee [S'] = [f] \quad \text{iff} \quad [S] = [f] \text{ and } [S'] = [f].$$

7. Outline of the proof of the main result

The most lengthy and difficult result to prove is Theorem 37 on the correctness of the unification of T_μ -strategies. The remaining theorems are more or less a consequence of this theorem. In this section we give a relatively detailed outline of the proof of Theorem 37 without the technical machinery which will be developed in the next sections. We shall proceed in four steps:

Step 1. We first show that the unification of T_μ -strategies is correct in the particular setting, where the T_μ -strategies are *fixed-point free*. More precisely, we shall show that the mapping Ψ permutes with the unification (in the sense of Theorem 37) within this particular setting. The proof is relatively easy and will be exposed in Section 9.

Step 2. Then we reduce the general setting to the fixed-point free setting by replacing the fixed-point operators by iterations whose number depends on the input term, Sections 10, 11 and 12. That is, we replace in the input T_μ -strategies each fixed-point T_μ -strategy $\mu X.S(X)$ with the unfolding $S(S(\dots(S(f)))) := \mu^n X.S(X)$ whose length is an arbitrary fixed integer n . Clearly, the unfolding of a T_μ -strategy is a fixed-point free one. The key idea is to show that the unification of two T_μ -strategies is n -equivalent to the unification of their unfoldings. To accomplish this, we compare the structure of the resulting two T_μ -strategies and show that they have a similar structure (Lemma 87). We illustrate this idea of similarity of structures in a particular case through a simple example, then we discuss the more general case. For the simple example, let $M(Y), S(X)$ and R be three fixed-point free T_μ -strategies where R does not contain neither a left choice \oplus nor an **If-Then**. Consider, on the one hand, the unification of $M(\mu X.S(X))$ with R , and on the other hand, the unification of the unfolding of $M(\mu X.S(X))$ with the unfolding of R . Notice that the unfolding of R is equal to R since R is fixed-point free. The structure of the T_μ -strategy $M(\mu X.S(X)) \wedge R$ is depicted on the left of Fig. 2, while that of the T_μ -strategy $M(\mu^n X.S(X)) \wedge R$ is on the right. That is, the unification $M(\mu X.S(X)) \wedge R$ yields a T_μ -strategy of the form $T_0(\mu Z_1.T_1(\dots))$, whereas the unification $M(\mu^n X.S(X)) \wedge R$ yields a (fixed-point) free T_μ -strategy of the form $T_0(T_1(\dots))$.

The general case in which we unify S and R where both of them contain many fixed-point operators can be obtained by generalizing the simple example. The general structure of the T_μ -strategy $S \wedge R$ is depicted on the left of Fig. 3, while that of the T_μ -strategy that results from the unification of an unfolding of S with an unfolding of R is on the right. The general structure of the T_μ -strategy on the left is of the form $T_0(\mu Z_1.T_1(\mu Z_2.T_2(\dots \mu Z_m.T_m(Z_m))))$, while that on the right, is $T_0(T_1(\dots T_m))$. Besides, each T_μ -strategy T_i^j on the left is either a fixed-point variable or a fixed-point T_μ -strategy that results from the unification of two T_μ -strategies where one of them is a fixed-point. Assume that T_i^j is the normal form of $\langle \xi_i^j, R_i^j, \cdot \rangle$, where ξ_i^j is a fixed-point T_μ -strategy that is a sub- T_μ -strategy of S , while R_i^j is a sub- T_μ -strategy of R . The main point is that each T_i^j is the result of the unification of an unfolding of ξ_i^j with an unfolding of R_i^j . Furthermore, the more we go deeper into the right tree, i.e. j increases, the more the size of iterations in the unfoldings decreases. The formalization of the notion of similarity between the unification of two T_μ -strategies and that of their unfoldings will be done in Subsection 11.3. Proving the existence of such similarity between the unification and the unification of unfoldings, as well as developing the properties of this similarity, namely the decrease of the size of iterations in the unfoldings, will be done in Section 11.4.

Step 3. The third step of the proof consists of proving that the unification of two T_μ -strategies is equivalent to that of their unfoldings by using the notion of similarity discussed before. More precisely, we shall show that, for any $n \geq 1$, the unification of two T_μ -strategies is n -equivalent to the \mathbf{s} -unfolding of them, where \mathbf{s} -unfolding amounts to replace each fixed-point operator with an iteration of size n . This will be proved in Section 12, Proposition 105. We outline next the general idea of this proof in a simple setting in which the unification $S \wedge R$ yields a T_μ -strategy $\mu Z_1.T_1(Z_1)$. Thanks to the notion of similarity, we know that the unification of S with the \mathbf{r} -unfolding of R is of the form $T_1(T_1^1)$, where T_1^1 is the result of the unification of an \mathbf{s}_1 -unfolding of S with a \mathbf{s}_2 -unfolding of R , where the \mathbf{s}_1 -unfolding (resp. \mathbf{s}_2 -unfolding) replaces each fixed-point operator in S

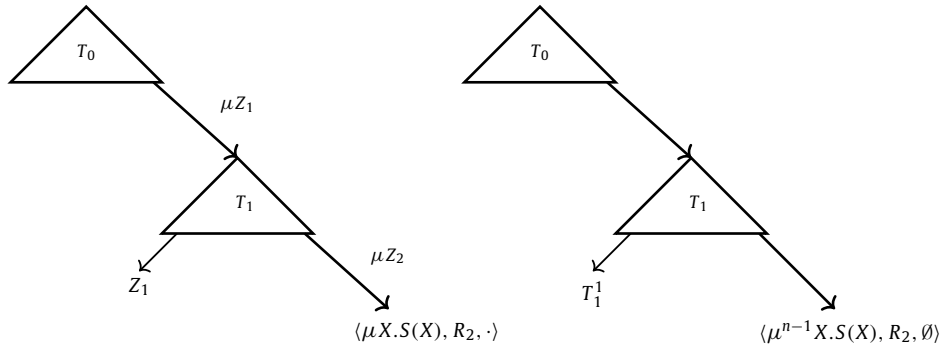


Fig. 2. The structure of the T_μ -strategy $M(\mu X.S(X)) \wedge R$ (left) and that of $M(\mu^n X.S(X)) \wedge R$ (right), where $M(Y)$, $S(X)$ and R are fixed-point free, and $n \geq 1$.

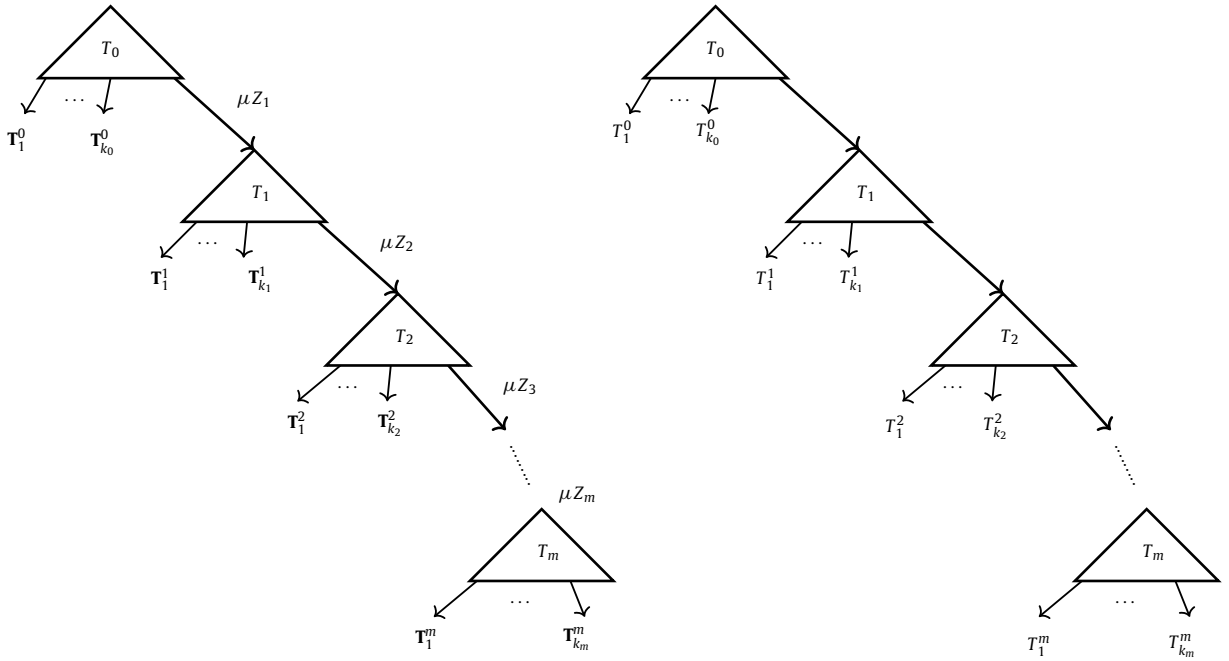


Fig. 3. The general structure of a T_μ -strategy $S \wedge R$ (left) and that of the T_μ -strategy that results from the unification of a full unfolding of S with a full unfolding of R (right), where each T_μ -strategy T_j^i is either a fixed-point T_μ -strategy, or a fixed-point variable. Each T_j^i is a unification of two unfoldings of the same T_μ -strategies involved in T_j^i . Inductively, the structure of each T_j^i is again similar to the one of T_j^i .

(resp. in R) with certain number of iterations that can be computed. To show that $\mu Z_1.T_1(Z_1)$ is n -equivalent to $T_1(T_1^1)$ it suffices to show that $T_1(T_1^1)$ is a fixed-point of $T_1(Z_1)$, i.e. that $T_1(T_1^1)$ is n -equivalent to $T_1(T_1(T_1^1))$. To achieve this it is enough to show that T_1^1 is n' -equivalent to $T_1(T_1^1)$ provided that there is at least $n - n'$ jumps between the root of $T_1(Z_1)$ and Z_1 , where n' is a constant that depends on s_1 and s_2 . This raises two technical problems. (i) Since $T_1(T_1^1)$ is the unification of the s -unfolding of S with the s -unfolding of R , and since T_1^1 is the unification of the s_1 -unfolding of S with the s_2 -unfolding of R , how to relate in general the unification of two unfoldings with the unification of two other unfoldings of the same T_μ -strategies? We shall address this problem in Section 11.1 and show that the two resulting T_μ -strategies are equivalent up to a constant that depends on the four unfoldings. And (ii) how to compute a lower bound on the number of such jumps? This question will be addressed in Subsections 12.1 and 12.2. These results will be summed up in Subsection 12.3 to show the main result of this third step (i.e. Proposition 105).

Step 4. Since an unfolding of a T_μ -strategy is a fixed-point free one, we shall rely on Proposition 105 together with the correctness of the unification and combination for the fixed-point free setting outlined in Step 1, to prove the correctness of the unification and combination in the general setting. The proof turns to be relatively straightforward and will be exposed in Subsection 13.1.

8. From T_μ -strategies to position-based T_μ -strategies: the definition of the mapping Ψ

In this section we define the mapping Ψ announced in Section 5, then state and prove its properties. Before doing this, we need to define the *tree depth* of a T_μ -strategy that corresponds to the usual notion of depth of such a T_μ -strategy after removing all the back-edges. We warn the reader that we shall use the same notation δ used for the depth of terms introduced in the preliminaries section 2.

Definition 43 (*Tree depth of a T_μ -strategy*). The *tree depth* of a T_μ -strategy is the depth of its underlying tree after we have ignored the fixed-point constructors of this T_μ -strategy. That is, it is the function $\delta : \mathcal{C} \rightarrow \mathbb{N}$ defined inductively as follows:

$$\begin{aligned} \delta(f) &= 0 \\ \delta(X) &= 0 \\ \delta(@\varepsilon.\tau) &= 1 \\ \delta(u; S) &= 1 + \delta(S) \\ \delta(@p.S) &= 1 + \delta(S) \\ \delta(S_1 \oplus S_2) &= 1 + \max\{\delta(S_1), \delta(S_2)\} \\ \delta\left(\bigwedge_{i=1,n} S_i\right) &= 1 + \max\{\delta(S_1), \dots, \delta(S_n)\} \\ \delta(\text{If } S_1 \text{ Then } S) &= 1 + \max\{\delta(S_1), \delta(S)\} \\ \delta(\mu X.S(X)) &= \delta(S(X)). \end{aligned}$$

It is useful to normalize T_μ -strategies which are almost position-based T_μ -strategies, i.e. they involve position jumps and conjunctions, by concatenation of their nested positions and by removing the failures. For instance, turning $@i.@j.S$ into $@ij.S$, and turning $@i.S \wedge @j.f$ into $@i.S$. The definition of the normalization follows.

Definition 44 (*Normalization*). The *normalization* is the function θ that turns any T_μ -strategy built up with just position jumps and conjunctions to a position-based T_μ -strategy as follows for any set of positions J :

$$\begin{aligned} \theta(@i.\tau) &= @i.\tau \\ \theta(@i.@j.S) &= \theta(@ij.S) \\ \theta\left(\bigwedge_{j \in J} @j.S_j\right) &= \theta\left(\bigwedge_{j \in J \setminus \{i\}} @j.S_j\right) \text{ if } S_i = f \\ \theta\left(\bigwedge_{j \in J} @j.S_j\right) &= \bigwedge_{j \in J} \theta(@j.S_j) \\ \theta\left(@i.\left(\bigwedge_{j \in J} @j.S_j\right)\right) &= \bigwedge_{j \in J} \theta(@ij.S_j). \end{aligned}$$

Example 45 (*Normalization*). Let τ , τ' and τ'' be contexts in \mathcal{T}_\square . Let S be the following T_μ -strategy:

$$S = @1.(@2.\tau \wedge @3.(@4.\tau' \wedge @5.\tau'')).$$

Then its normalization yields:

$$\theta(S) = @12.\tau \wedge @134.\tau' \wedge @135.\tau''.$$

Guided by the semantics of T_μ -strategies, we next define the mapping Ψ .

Definition 46 (*The mapping Ψ*). We define the mapping

$$\Psi : \mathcal{T} \rightarrow \mathcal{C} \rightarrow \mathcal{E}$$

that associates to any term t in \mathcal{T} and any closed T_μ -strategy S in \mathcal{C} a position-based T_μ -strategy $\Psi_t(S)$ in \mathcal{E} by

1. $\Psi_t(f) = f$.

2. $\Psi_t(@\varepsilon.\tau) = @\varepsilon.\tau$.
3. $\Psi_t(S \oplus S') = \begin{cases} \Psi_t(S) & \text{if } \Psi_t(S) \neq \mathbf{f}, \\ \Psi_t(S') & \text{otherwise.} \end{cases}$
4. $\Psi_t(\mu X.S(X)) = \Psi_t(\mu^{\delta(t)} X.S(X))$.
5. $\Psi_t(u; S) = \begin{cases} \Psi_t(S) & \text{if } u \ll t, \\ \mathbf{f} & \text{otherwise.} \end{cases}$
6. $\Psi_t(\text{If } S' \text{ Then } S) = \begin{cases} \Psi_t(S) & \text{if } \Psi_t(S') \neq \mathbf{f}, \\ \mathbf{f} & \text{otherwise.} \end{cases}$
7. $\Psi_t(\bigwedge_{i=1,n} @p_i.S_i) = \theta(\bigwedge_{i=1,n} @p_i.\Psi_{t|p_i}(S_i))$.
8. $\Psi_t(\text{MOS}t(S)) = \Psi_t(\bigwedge_{i=1,ar(t)} @i.S)$.

Example 47. If we consider the two \mathbb{T}_μ -strategies $S(X)$ and $R(Y)$ defined in Example 19 by

$$S(X) = (b; @\varepsilon.\tau) \oplus @1.X,$$

$$R(Y) = \mu Y.(g(b, b', x); (@1.\tau \wedge @2.\tau' \wedge @3.Y)),$$

together with the two terms $t = f(f(b))$ and $t' = g(b, b', g(b, b', b))$, then

$$\Psi_t(\mu X.S(X)) = @11.\tau,$$

$$\Psi_{t'}(\mu Y.R(Y)) = @1.\tau \wedge @2.\tau' \wedge @31.\tau \wedge @32.\tau'.$$

Lemma 48. The mapping Ψ preserves the semantic equivalence in the sense that, for any term t in \mathcal{T} and any \mathbb{T}_μ -strategy S in \mathcal{C} , we have that

$$\llbracket \Psi_t(S) \rrbracket(t) = \llbracket S \rrbracket(t).$$

The proof of this Lemma does not provide any difficulties since the definition of Ψ is close to the definition of the semantics of \mathbb{T}_μ -strategies. The previous Lemma can be restated in terms of explicit properties as follows.

Lemma 49. The mapping Ψ satisfies the following properties for any terms t, u , and for any closed \mathbb{T}_μ -strategies $S, S', R, R', E',$ where E' is built using only jumps and failures, and for any position-based \mathbb{T}_μ -strategy E :

1. (a) $\Psi_t(E) = E$.
(b) $\Psi_t(\Psi_t(S)) = \Psi_t(S)$.
2. $\Psi_t(u; S) = \Psi_t(u; \Psi_t(S))$.
3. $\Psi_t(S \oplus S') = \Psi_t(\Psi_t(S) \oplus \Psi_t(S'))$.
4. (a) $\Psi_t(\text{If } S' \text{ Then } S) = \Psi_t(\text{If } \Psi_t(S') \text{ Then } S)$.
(b) $\Psi_t(\text{If } S' \text{ Then } S) = \Psi_t(\text{If } S' \text{ Then } \Psi_t(S))$.
(c) $\Psi_t(\text{If } S' \text{ Then } S) = \Psi_t(\text{If } R' \text{ Then } S)$ if $\Psi_t(S') = \Psi_t(R')$.
(d) $\Psi_t(\text{If } E' \text{ Then } S) = \Psi_t(\text{If } \theta(E') \text{ Then } \Psi_t(S))$.
5. (a) $\Psi_t(S \wedge R) = \Psi_t(S \wedge R')$ if $\Psi_t(R) = \Psi_t(R')$, whenever S, R, R' are a conjunction of jumps.
(b) $\Psi_t(S \wedge R) = \Psi_t(S)$ if $\Psi_t(R) = \mathbf{f}$, whenever S, R are a conjunction of jumps.

It turns out that the mapping Ψ (Definition 46) preserves the semantics of \mathbb{T}_μ -strategies in the following sense.

Lemma 50. The mapping Ψ enjoys the following properties.

- i.) For any position-based \mathbb{T}_μ -strategies E, E' in \mathcal{E} , we have that $E = E'$ iff $\Psi_t(E) = \Psi_t(E')$ for any term t .
- ii.) For any \mathbb{T}_μ -strategies S, S' in \mathcal{C} , we have that $S \equiv S'$ iff $\Psi_t(S) = \Psi_t(S')$ for any term t .
- iii.) For any \mathbb{T}_μ -strategies S, S' in \mathcal{C} , we have that $S \equiv_n S'$ iff $\Psi_t(S) = \Psi_t(S')$ for any term t of depth $\delta(t) = n$.

Proof. We only prove Item ii.), the other items follow immediately from the definition of Ψ . On the one hand, from the definition of \equiv we have that

$$S \equiv S' \quad \text{iff} \quad \llbracket S \rrbracket(t) = \llbracket S' \rrbracket(t), \quad \forall t \in \mathcal{T}.$$

However, it follows from Lemma 48 that

$$\llbracket S \rrbracket(t) = \llbracket \Psi_t(S) \rrbracket(t) \quad \text{and} \quad \llbracket S' \rrbracket(t) = \llbracket \Psi_t(S') \rrbracket(t).$$

Therefore,

$$\llbracket \Psi_t(S) \rrbracket(t) = \llbracket \Psi_t(S') \rrbracket(t), \quad \forall t \in \mathcal{T}.$$

Since, both $\Psi_t(S)$ and $\Psi_t(S')$ are position-based \mathcal{T}_μ -strategies, it follows from Item i.) of this Lemma that $\Psi_t(S) = \Psi_t(S')$. \square

We show in the following lemma that the mapping Ψ can be pushed over the \mathcal{T}_μ -strategy constructors.

Lemma 51. *The mapping Ψ satisfies the following properties for any closed \mathcal{T}_μ -strategies S, S' and any position-based \mathcal{T}_μ -strategy E and any terms t, u :*

1. (a) $\Psi_t(u; (\Psi_t(S) \wedge E)) = \Psi_t(u; S) \wedge E$.
 (b) $\Psi_t(u; (E \wedge \Psi_t(S))) = \Psi_t(E \wedge \Psi_t(u; S))$.
2. (a) $\Psi_t((\Psi_t(S) \oplus \Psi_t(S')) \wedge E) = \Psi_t(S \oplus S') \wedge E$.
 (b) $E \wedge \Psi_t(\Psi_t(S) \oplus \Psi_t(S')) = E \wedge \Psi_t(S \oplus S')$.
3. (a) $\Psi_t(\text{If } S' \text{ Then } (\Psi_t(S) \wedge E)) = \Psi_t(\text{If } S' \text{ Then } \Psi_t(S)) \wedge E$.
 (b) $\Psi_t(\text{If } S' \text{ Then } (E \wedge \Psi_t(S))) = E \wedge \Psi_t(\text{If } S' \text{ Then } \Psi_t(S))$.

Proof. We only prove the cases 1a and 2a and 3a since the proof of the cases 1b and 2b and 3b is similar.

1. (a) We distinguish two cases depending on whether u matches with t or not. If u matches with t then the left-hand side of the equation is

$$\begin{aligned} \Psi_t(u; (\Psi_t(S) \wedge E)) &= \Psi_t(\Psi_t(S) \wedge E) && (\text{Def. 46 of } \Psi) \\ &= \Psi_t(S) \wedge E, && (\text{since } \Psi_t(S) \wedge E \text{ is a position-based } \mathcal{T}_\mu\text{-strategy, Item 1a of Lemma 49}) \end{aligned}$$

and the right-hand side of the equation is $\Psi_t(u; S) \wedge E = \Psi_t(S) \wedge E$ by the Definition of Ψ , which is equal to the left-hand side. If u does not match with t then, the left-hand side of the equation is \mathbf{f} by the definition of Ψ ; and the right-hand side is $\Psi_t(u; S) \wedge E = \mathbf{f} \wedge E = \mathbf{f}$.

2. (a) We distinguish two cases depending on whether $\Psi_t(S) = \mathbf{f}$ or not. If $\Psi_t(S) = \mathbf{f}$ then the left-hand side of the equation is

$$\begin{aligned} \Psi_t((\Psi_t(S) \oplus \Psi_t(S')) \wedge E) &= \Psi_t((\mathbf{f} \oplus \Psi_t(S')) \wedge E) \\ &= \Psi_t(\Psi_t(S') \wedge E) \\ &= \Psi_t(S') \wedge E, && (\text{since } \Psi_t(S') \wedge E \text{ is position-based, Item 1a of Lemma 49}) \end{aligned}$$

and the right-hand side of the equation is $\Psi_t(S \oplus S') \wedge E = \Psi_t(S') \wedge E$ by the definition of Ψ , which is equal to the left-hand side. If $\Psi_t(S) \neq \mathbf{f}$, then left-hand side of the equation is $\Psi_t((\Psi_t(S) \oplus \Psi_t(S')) \wedge E) = \Psi_t(\Psi_t(S) \wedge E)$ by the definition of Ψ on the left-choice, which is equal to $\Psi_t(S) \wedge E$, since $\Psi_t(S) \wedge E$ is position-based. For the right-hand side, we have $\Psi_t(S \oplus S') = \Psi_t(S)$ by the definition of Ψ , thus we get the desired result.

3. We distinguish two cases depending on whether $\Psi_t(S') = \mathbf{f}$ or not. If $\Psi_t(S') = \mathbf{f}$ then the left-hand side of the equation is $\Psi_t(\text{If } S' \text{ Then } (\Psi_t(S) \wedge E)) = \mathbf{f}$ by the definition of Ψ , and the right-hand side is $\Psi_t(\text{If } S' \text{ Then } \Psi_t(S)) \wedge E = \mathbf{f} \wedge E = \mathbf{f}$. If $\Psi_t(S') \neq \mathbf{f}$ then left-hand side of the equation is $\Psi_t(\text{If } S' \text{ Then } (\Psi_t(S) \wedge E)) = \Psi_t(\Psi_t(S) \wedge E)$ which is equal to $\Psi_t(S) \wedge E$ since $\Psi_t(S) \wedge E$ is a position-based \mathcal{T}_μ -strategy, by the Item 1a of Lemma 49. And the right-hand side is $\Psi_t(\text{If } S' \text{ Then } \Psi_t(S)) \wedge E = \Psi_t(\Psi_t(S)) \wedge E$ which is equal to $\Psi_t(S) \wedge E$ by the same item. \square

9. Proof of the correctness of the unification of \mathcal{T}_μ -strategies: the fixed-point free setting

In this section we prove the correctness of the unification procedure in the case where the two input \mathcal{T}_μ -strategies are fixed-point free (Proposition 55). This is an important step since we shall reduce in the next three sections 10, 11, 12 the general setting into the fixed-point free one.

We notice that, in the fixed-point free setting, the memory involved in the unification system \mathcal{U} remains empty and does not play any role since the only rules that modify the contexts are the fixed-point ones. Obviously, such rules are not applied since the input \mathcal{T}_μ -strategies are fixed-point free. Besides, in this setting, the proof of the termination and the confluence of \mathcal{U} is trivial. Indeed, \mathcal{U} terminates since each rule transforms a left-hand side \mathcal{T}_μ -strategy into its immediate sub- \mathcal{T}_μ -strategies.

We need a simple set theoretic fact.

Fact 52. Let I', J', J'' be sets. Then, $(I' \cap J'') \cup (I' \setminus (J' \cup J'')) = I' \setminus J'$.

Since the definition of the mapping Ψ involves the normalization of positions (function θ in Item 7 of Definition 46), we need to show that this normalization does not disturb the unification in the following sense.

Lemma 53. Let $S = \bigwedge_{i \in I'} @i.S_i$ and $R = \bigwedge_{j \in J'} @j.R_j$ be two \mathbb{T}_μ -strategies where each S_i and R_i is either the failure \mathfrak{f} or the insertion $@\varepsilon.\tau_i$, for a context τ_i in \mathcal{T}_\square . Then,

$$\Psi_t(S \wedge R) = \Psi_t(\theta(S) \wedge \theta(R)). \quad (2)$$

Proof. Assume that

$$S = \bigwedge_{i \in I'} @i.S_i \wedge \bigwedge_{i \in I''} @i.\mathfrak{f} \quad \text{and} \quad R = \bigwedge_{j \in J'} @j.R_j \wedge \bigwedge_{j \in J''} @j.\mathfrak{f},$$

where $S_i \in \mathcal{T}_\square$ for any $i \in I'$, and $R_j \in \mathcal{T}_\square$ for any $j \in J'$, and $I' \cap I'' = \emptyset$ and $J' \cap J'' = \emptyset$. Therefore,

$$\theta(S) = \bigwedge_{i \in I'} @i.S_i \quad \text{and} \quad \theta(R) = \bigwedge_{j \in J'} @j.R_j.$$

Consider the \mathbb{T}_μ -strategy $\tilde{\Lambda}$:

$$\tilde{\Lambda} = \bigwedge_{i \in I' \cap J'} @i.(S_i \wedge R_i \oplus S_i \oplus R_i) \wedge \bigwedge_{i \in I' \setminus J'} @i.S_i \wedge \bigwedge_{i \in J' \setminus I'} @i.R_i.$$

By computing the \mathbb{T}_μ -strategies $\theta(S) \wedge \theta(R)$ and $S \wedge R$ involved in the right-hand side and the left-hand side of Eq. (2) respectively, we get:

$$\begin{aligned} \Psi_t(\theta(S) \wedge \theta(R)) &= \Psi_t(\mathbf{If} \theta(S) \& \theta(R) \mathbf{Then} \tilde{\Lambda}) && \text{(Item 4b of Def. 33 of } \wedge \text{)} \\ &= \Psi_t(\mathbf{If} S \& R \mathbf{Then} \tilde{\Lambda}) && \text{(Item 4d of Lemma 49)} \\ &= \Psi_t(\mathbf{If} S \& R \mathbf{Then} \Psi_t(\tilde{\Lambda})), && \text{(Item 4b of Lemma 49)} \\ &\text{and} \\ \Psi_t(S \wedge R) &= \Psi_t(\mathbf{If} S \& R \mathbf{Then} \Lambda) && \text{(Item 4b of Def. 33 of } \wedge \text{)} \\ &= \Psi_t(\mathbf{If} S \& R \mathbf{Then} \Psi_t(\Lambda)), && \text{(Item 4b of Lemma 49)} \end{aligned}$$

where Λ is the \mathbb{T}_μ -strategy

$$\begin{aligned} \Lambda &= \bigwedge_{i \in I' \cap J'} @i.(S_i \wedge R_i \oplus S_i \oplus R_i) \wedge \bigwedge_{i \in I' \cap J''} @i.(S_i \wedge \mathfrak{f} \oplus S_i \oplus \mathfrak{f}) \wedge \bigwedge_{i \in I'' \cap J'} @i.(\mathfrak{f} \wedge R_i \oplus \mathfrak{f} \oplus R_i) \wedge \\ &\quad \bigwedge_{i \in I'' \cap J''} @i.\mathfrak{f} \wedge \bigwedge_{i \in I' \setminus (J' \cup J'')} @i.S_i \wedge \bigwedge_{i \in I'' \setminus (J' \cup J'')} @i.\mathfrak{f} \wedge \bigwedge_{i \in J' \setminus (I' \cup I'')} @i.R_i \wedge \bigwedge_{i \in J'' \setminus (I' \cup I'')} @i.\mathfrak{f}. \end{aligned} \quad \text{(Item 4b Def. 33 of } \wedge \text{)}$$

Hence to prove Eq. (2) we need to show that $\Psi_t(\tilde{\Lambda}) = \Psi_t(\Lambda)$. It follows that $\Psi_t(\Lambda)$ can be written as

$$\begin{aligned} \Psi_t(\Lambda) &= \Psi_t \left(\bigwedge_{i \in I' \cap J'} @i.(S_i \wedge R_i \oplus S_i \oplus R_i) \wedge \bigwedge_{i \in I' \cap J''} @i.S_i \wedge \bigwedge_{i \in I'' \cap J'} @i.R_i \wedge \bigwedge_{i \in I'' \cap J''} @i.\mathfrak{f} \wedge \right. \\ &\quad \left. \bigwedge_{i \in I' \setminus (J' \cup J'')} @i.S_i \wedge \bigwedge_{i \in I'' \setminus (J' \cup J'')} @i.\mathfrak{f} \wedge \bigwedge_{i \in J' \setminus (I' \cup I'')} @i.R_i \wedge \bigwedge_{i \in J'' \setminus (I' \cup I'')} @i.\mathfrak{f} \right) \\ &\quad \text{(since } \Psi_t(S_i \wedge \mathfrak{f} \oplus S_i \oplus \mathfrak{f}) = \Psi_t(S_i) \text{ and } \Psi_t(\mathfrak{f} \wedge R_i \oplus \mathfrak{f} \oplus R_i) = \Psi_t(R_i), \text{ by Item 5a of Lemma 49)} \\ &= \Psi_t \left(\bigwedge_{i \in I' \cap J'} @i.(S_i \wedge R_i \oplus S_i \oplus R_i) \wedge \bigwedge_{i \in I' \cap J''} @i.S_i \wedge \bigwedge_{i \in I' \setminus (J' \cup J'')} @i.S_i \wedge \bigwedge_{i \in J' \setminus (I' \cup I'')} @i.R_i \wedge \bigwedge_{i \in I'' \cap J'} @i.R_i \right) \\ &\quad \text{(since } \Psi_t(@i.\mathfrak{f}) = \mathfrak{f}, \text{ by Item 5b of Lemma 49)} \\ &= \Psi_t \left(\bigwedge_{i \in I' \cap J'} @i.(S_i \wedge R_i \oplus S_i \oplus R_i) \wedge \bigwedge_{i \in I' \setminus J'} @i.S_i \wedge \bigwedge_{i \in J' \setminus I'} @i.R_i \right) \\ &\quad \text{(since } (I' \cap J'') \cup (I' \setminus (J' \cup J'')) = I' \setminus J' \text{ and } (J' \cap I'') \cup (J' \setminus (I' \cup I'')) = J' \setminus I', \text{ by Fact 52)} \\ &= \Psi_t(\tilde{\Lambda}). \quad \square && \text{(Def. of } \tilde{\Lambda} \text{)} \end{aligned}$$

Notation 54. Throughout this paper the set of fixed-point free T_μ -strategies will be denoted by C_0 .

Now we are ready to show the main result of this section, that is, that the unification of fixed-point free T_μ -strategies is correct.

Proposition 55. For every term $t \in \mathcal{T}$ and for every fixed-point free T_μ -strategies S and R in C_0 , we have that

$$\Psi_t(S \wedge R) = \Psi_t(S) \wedge \Psi_t(R). \quad (3)$$

Or, equivalently, the following diagram commutes.

$$\begin{array}{ccc} C_0 \times C_0 & \xrightarrow{\wedge} & C_0 \\ \Psi_t \times \Psi_t \downarrow & & \downarrow \Psi_t \\ \mathcal{E} \times \mathcal{E} & \xrightarrow{\wedge} & \mathcal{E} \end{array}$$

Proof. The proof is by structural induction on S and R , which amounts to consider $\delta(S)$ the depth of S , and $\delta(R)$ the depth of R .

Base case. If $(\delta(S), \delta(R)) = (0, 0)$ then $S = f$ or $S = @e.\tau$, and $R = f$ or $R = @e.\tau'$. In this case the proof is trivial since $\Psi_t(S) = S$ and $\Psi_t(R) = R$.

Induction step. We assume that the claim holds for some S' and R' and we shall show it for any S and R such that either i.) S' is an immediate sub- T_μ -strategy of S and $R' = R$, or ii.) R' is an immediate sub- T_μ -strategy of R and $S' = S$, or iii.) S' is an immediate sub- T_μ -strategy of S , and R' is an immediate sub- T_μ -strategy of R .

1. If $S = u$; S' and R is arbitrary then

$$\begin{aligned} \Psi_t(S \wedge R) &= \Psi_t((u; S') \wedge R) \\ &= \Psi_t(u; (S' \wedge R)) && \text{(Item 3a of Def. 33 of } \wedge) \\ &= \Psi_t(u; \Psi_t(S' \wedge R)) && \text{(Item 2 of Lemma 49)} \\ &= \Psi_t(u; (\Psi_t(S') \wedge \Psi_t(R))) \\ &\quad \text{(Ind. hypothesis since } S' \text{ is an immediate sub } T_\mu\text{-strategy of } S, \text{ and } R = R') \\ &= \Psi_t(u; S') \wedge \Psi_t(R) && \text{(Item 1a of Lemma 51)} \\ &= \Psi_t(S) \wedge \Psi_t(R). && \text{(Def. of } S) \end{aligned}$$

2. If $S = S' \oplus S''$ and R is arbitrary then

$$\begin{aligned} \Psi_t(S \wedge R) &= \Psi_t((S' \oplus S'') \wedge R) \\ &= \Psi_t((S' \wedge R) \oplus (S'' \wedge R)) && \text{(Item 5a of Def. 33 of } \wedge) \\ &= \Psi_t(\Psi_t(S' \wedge R) \oplus \Psi_t(S'' \wedge R)) && \text{(Item 3 of Lemma 49)} \\ &= \Psi_t((\Psi_t(S') \wedge \Psi_t(R)) \oplus (\Psi_t(S'') \wedge \Psi_t(R))) && \text{(Ind. hypothesis)} \\ &= \Psi_t((\Psi_t(S') \oplus \Psi_t(S'')) \wedge \Psi_t(R)) && \text{(Def. of } \wedge) \\ &= \Psi_t(S' \oplus S'') \wedge \Psi_t(R) && \text{(Item 2a of Lemma 51)} \\ &= \Psi_t(S) \wedge \Psi_t(R). && \text{(Def. of } S) \end{aligned}$$

3. If $S = \text{If } S' \text{ Then } S''$ and R is arbitrary then

$$\begin{aligned} \Psi_t(S \wedge R) &= \Psi_t((\text{If } S' \text{ Then } S'') \wedge R) \\ &= \Psi_t(\text{If } S' \text{ Then } (S'' \wedge R)) && \text{(Item 6a Def. 33 of } \wedge) \\ &= \Psi_t(\text{If } S' \text{ Then } \Psi_t(S'' \wedge R)) && \text{(Item 4b of Lemma 49)} \\ &= \Psi_t(\text{If } S' \text{ Then } (\Psi_t(S'') \wedge \Psi_t(R))) && \text{(Ind. hypothesis)} \\ &= \Psi_t(\text{If } S' \text{ Then } \Psi_t(S'')) \wedge \Psi_t(R) && \text{(Item 3a of Lemma 51)} \\ &= \Psi_t(\text{If } S' \text{ Then } S'') \wedge \Psi_t(R) && \text{(Item 4b of Lemma 49)} \\ &= \Psi_t(S) \wedge \Psi_t(R). && \text{(Def. of } S) \end{aligned}$$

4. If $S = \bigwedge_{i \in I} @i.S_i$ and $R = \bigwedge_{j \in J} @j.R_j$ then let

$$\begin{aligned} M_1 &= \bigwedge_{i \in I \setminus J} @i.S_i & \text{and} & & M_2 &= \bigwedge_{j \in J \setminus I} @j.R_j, \\ M_1^* &= \bigwedge_{i \in I \setminus J} @i.\Psi_{t|_i}(S_i) & \text{and} & & M_2^* &= \bigwedge_{j \in J \setminus I} @j.\Psi_{t|_j}(R_j). \end{aligned}$$

The left-hand side of Eq. (3) can be written as

$$\begin{aligned} \text{LH.3} &= \Psi_t(S \wedge R) \\ &= \Psi_t(\text{If } S \&R \text{ Then } \bigwedge_{i \in I \cap J} @i.(S_i \wedge R_i \oplus S_i \oplus R_i) \wedge M_1 \wedge M_2) && \text{(Item 4b of Def. 33 of } \wedge) \\ &= \Psi_t(\text{If } S \&R \text{ Then } \Psi_t(\bigwedge_{i \in I \cap J} @i.(S_i \wedge R_i \oplus S_i \oplus R_i) \wedge M_1 \wedge M_2)) && \text{(Item 4b of Lemma 49)} \\ &= \Psi_t(\text{If } S \&R \text{ Then } \theta(\bigwedge_{i \in I \cap J} @i.\Psi_{t|_i}(S_i \wedge R_i \oplus S_i \oplus R_i) \wedge M_1^* \wedge M_2^*)) && \text{(Item 7 of Def. 46 of } \Psi_t(\wedge(\cdot))) \\ &= \Psi_t(\text{If } S \&R \text{ Then } \bigwedge_{i \in I \cap J} @i.\Psi_{t|_i}(S_i \wedge R_i \oplus S_i \oplus R_i) \wedge M_1^* \wedge M_2^*) && \text{(Item 4d of Lemma 49)} \\ &= \Psi_t(\text{If } S \&R \text{ Then } \bigwedge_{i \in I \cap J} @i.(\Psi_{t|_i}(S_i) \wedge \Psi_{t|_i}(R_i) \oplus \Psi_{t|_i}(S_i) \oplus \Psi_{t|_i}(R_i)) \wedge M_1^* \wedge M_2^*) && \text{(Ind. hyp.)} \\ &= \Psi_t(\bigwedge_{i \in I} @i.(\Psi_{t|_i}(S_i)) \wedge \bigwedge_{j \in J} @j.(\Psi_{t|_j}(R_j))) && \text{(Item 4b of Def. 33 of } \wedge) \\ &= \Psi_t(\theta(\bigwedge_{i \in I} @i.(\Psi_{t|_i}(S_i)) \wedge \theta(\bigwedge_{j \in J} @j.(\Psi_{t|_j}(R_j)))) && \text{(Lemma 53)} \\ &= \Psi_t(\Psi_t(\bigwedge_{i \in I} @i.S_i) \wedge \Psi_t(\bigwedge_{j \in J} @j.R_j)) && \text{(Item 7 of Def. 46 of } \Psi_t(\wedge \cdot)) \\ &= \Psi_t(\bigwedge_{i \in I} @i.S_i) \wedge \Psi_t(\bigwedge_{j \in J} @j.R_j) && \text{(Lemma 49)} \\ &= \Psi_t(S) \wedge \Psi_t(R). && \text{(Def. of } S \text{ and } R) \end{aligned}$$

5. If $S = \text{Most}(S')$ and $R = \text{Most}(R')$ then assume that t is neither a constant nor a rewriting variable, i.e. $\delta(t) \geq 2$, the case when $\delta(t) = 1$ being trivial since both sides of the equation are equal to f . In this case we rewrite $\text{Most}(\cdot)$ as $\bigwedge_i(\cdot)$ and we apply Item 4 of this proof. Let

$$S^* = \bigwedge_{i=1, ar(t)} @i.S' \quad \text{and} \quad R^* = \bigwedge_{i=1, ar(t)} @i.R',$$

and notice that $\Psi_t(S^*) = \Psi_t(S)$ and $\Psi_t(R^*) = \Psi_t(R)$. Hence

$$\begin{aligned} \Psi_t(S \wedge R) &= \Psi_t(\text{Most}(S') \wedge \text{Most}(R')) \\ &= \Psi_t(\text{If } (S \&R) \text{ Then } (\text{Most}((S' \wedge R') \oplus S' \oplus R'))) && \text{(Def. 33 of } \wedge) \\ &= \Psi_t(\text{If } (S \&R) \text{ Then } \Psi_t(\text{Most}((S' \wedge R') \oplus S' \oplus R'))) && \text{(Item 4b of Lemma 49)} \\ &= \Psi_t(\text{If } (S^* \&R^*) \text{ Then } \Psi_t(\text{Most}((S' \wedge R') \oplus S' \oplus R'))) && \text{(Item 4c of Lemma 49)} \\ &= \Psi_t(\text{If } (S^* \&R^*) \text{ Then } \Psi_t(\bigwedge_{i=1, ar(t)} @i.((S' \wedge R') \oplus S' \oplus R'))) && \text{(Item 8 of Def. 46 of } \Psi_t(\text{Most}(\cdot))) \\ &= \Psi_t(\text{If } (S^* \&R^*) \text{ Then } \bigwedge_{i=1, ar(t)} @i.((S' \wedge R') \oplus S' \oplus R'))) && \text{(Item 4d of Lemma 49)} \end{aligned}$$

$$\begin{aligned}
&= \Psi_t \left(\bigwedge_{i=1, ar(t)} @i.S' \wedge \bigwedge_{i=1, ar(t)} @i.R' \right) && \text{(Item 4b of Def. 33 of } \wedge \text{ in which } I = J = \{1, \dots, ar(t)\}) \\
&= \Psi_t \left(\bigwedge_{i=1, ar(t)} @i.S' \right) \wedge \Psi_t \left(\bigwedge_{i=1, ar(t)} @i.R' \right) && \text{(Item 4 of this proof)} \\
&= \Psi_t(\text{Most}(S')) \wedge \Psi_t(\text{Most}(R')) && \text{(Item 8 of Def. 46 of } \Psi_t(\text{Most}(\cdot)) \text{)} \\
&= \Psi_t(S) \wedge \Psi_t(R). \quad \square && \text{(Def. of } S \text{ and } R \text{)}
\end{aligned}$$

10. Properties of the unification reduction system and of T_μ -strategies

This section, together with the next two sections 11 and 12, is devoted to developing the ingredients required in the proof of the main result of this paper regarding the correctness of the unification of T_μ -strategies in the general setting, in which the T_μ -strategies contain fixed-point operators. In this section we introduce definitions and show preliminary results which will be used in the next two sections. In Subsection 10.1 we define some measures on the structure of T_μ -strategies, namely the number of nested fixed-point operators of a T_μ -strategy and its size. In Subsection 10.2 we show the termination and the confluence of the unification reduction system. In Subsection 10.3 we introduce the operation of unfolding which turns all fixed-point operators of a T_μ -strategy into iterations of arbitrary fixed size. In Subsection 10.4 we show some useful properties related to T_μ -strategies, namely the semantic equivalence of two T_μ -strategies when applied to terms of a certain depth, as well as a condition under which a T_μ -strategy is equivalent to a fixed-point one. In Subsection 10.5 we show a key Lemma, called *composition lemma*, that expresses the unification of two T_μ -strategies in terms of their sub- T_μ -strategies.

10.1. Measures of T_μ -strategies: the star height and the depth of T_μ -strategies

Taking into account that the structure of a T_μ -strategy is no longer a tree but a tree with back-edges that may contain cycles, we slightly modify the standard measure of the depth of trees in order to capture both the number of nested loops, caused by the nested application of the fixed-point constructor μ , and the distance from the root of the tree to the leaves. Many proofs will be done by induction on this measure.

We adapt the definition of the star height [27,28] that measures the depth of Kleen operator \star in regular languages to T_μ -strategies in order to capture the number of the nested fixed-point constructor.

Definition 56 (*Star height of a T_μ -strategy*). The *star height* of a T_μ -strategy is the function $\mathbf{h} : \mathcal{C} \rightarrow \mathbb{N}$ defined inductively as follows:

$$\mathbf{h}(S) = \begin{cases} 0 & \text{if } S \text{ is fixed-point free} \\ \max\{\mathbf{h}(S'(X_1, \dots, X_n)), \mathbf{h}(R_1), \dots, \mathbf{h}(R_n)\} & \text{if } S = S'(R_1, \dots, R_n), n \geq 1 \\ 1 + \mathbf{h}(S') & \text{if } S = \mu X.S'. \end{cases}$$

Example 57 (*Star height*). If $S(X)$ and $R(Y)$ are fixed-point free T_μ -strategies with distinct free fixed-point variables, then

$$\mathbf{h}(S(X)) = \mathbf{h}(R(Y)) = 0.$$

We compute the star height of the T_μ -strategies $\mu X.S(X) \oplus \mu Y.R(Y)$ and $\mu X.\mu Y.(S(X) \oplus R(Y))$ and $\mu X.(S(X) \oplus \mu Y.R(Y))$. Since the two fixed-point operators in $\mu X.S(X) \oplus \mu Y.R(Y)$ are not nested, we have that:

$$\begin{aligned}
\mathbf{h}(\mu X.S(X) \oplus \mu Y.R(Y)) &= \max\{\mathbf{h}(\mu X.S(X)), \mathbf{h}(\mu Y.R(Y))\} \\
&= \max\{1 + \mathbf{h}(S(X)), 1 + \mathbf{h}(R(Y))\} \\
&= 1.
\end{aligned}$$

However, since the two fixed-point operators in $\mu X.\mu Y.(S(X) \oplus R(Y))$ are nested, we have that:

$$\begin{aligned}
\mathbf{h}(\mu X.\mu Y.(S(X) \oplus R(Y))) &= 1 + \mathbf{h}(\mu Y.(S(X) \oplus R(Y))) \\
&= 1 + 1 + \mathbf{h}(S(X) \oplus R(Y)) \\
&= 2.
\end{aligned}$$

And similarly, the two fixed-point operators in $\mu X.(S(X) \oplus \mu Y.R(Y))$ are nested, thus we get:

$$\mathbf{h}(\mu X.(S(X) \oplus \mu Y.R(Y))) = 2.$$

We combine the star height and the tree depth, defined in Definition 43, to obtain the desired measure that takes into account both the number of the nested fixed-point constructors and the size of a T_μ -strategy.

Definition 58 (Depth of a T_μ -strategy). The *depth* of a T_μ -strategy S is the function $\Delta : \mathcal{C} \longrightarrow \mathbb{N} \times \mathbb{N}$ defined by

$$\Delta(S) = (\mathbf{h}(S), \delta(S)).$$

Notice that if a T_μ -strategy S is fixed-point free, i.e. it does not contain the fixed-point constructor μ , then its depth $\Delta(S) = (0, n)$, for some $n \in \mathbb{N}$.

The following fact shows that the depth of a fixed-point T_μ -strategy is strictly greater than the depth of its unfolding.

Fact 59. Let $\mu X.S(X)$ be a T_μ -strategy where X is free in $S(X)$. Then for any integer $n \geq 0$ we have

$$\Delta(\mu^n X.S(X)) < \Delta(\mu X.S(X)).$$

Proof. The case when $n = 0$ is trivial since $\Delta(\mu^0 X.S(X)) = \Delta(f) = (0, 0)$. We show next that $\mathbf{h}(\mu X.S(X)) = 1 + \mathbf{h}(\mu^n X.S(X))$ for any $n \geq 1$. It follows from the definition of the star height that $\mathbf{h}(\mu^n X.S(X)) = \mathbf{h}(S(S(\dots(S(f)))))) = \max\{\mathbf{h}(S(X)), \mathbf{h}(S(f))\} = \mathbf{h}(S(f)) = \mathbf{h}(S(X))$. On the other hand, by the definition of the star height $\mathbf{h}(\mu X.S(X)) = 1 + \mathbf{h}(S(X))$. And it follows from the lexicographic order that $\Delta(\mu^n X.S(X)) < \Delta(\mu X.S(X))$. \square

We next define the number of jumps (i.e. T_μ -strategies which are position jumps of the form $@i.S$ or $\text{Most } s$) that lie between the root of a T_μ -strategy to a free fixed-point variable. The idea is that by meeting jumps, the T_μ -strategy makes progress. In particular, if at least one jump lies between any fixed-point constructor μX and the occurrence of X in a T_μ -strategy S , then S is monotonic. Besides, we can compare the semantics of two T_μ -strategies $M(S)$ and $M(R)$ thanks to number of jumps between the root of $M(X)$ and X .

Definition 60. Let $S(X)$ be a T_μ -strategy where the fixed-point variable X is free and appears once. The *number of jumps* between the root of $S(X)$ and X , denoted by $\Pi_X(S(X))$, is inductively defined as follows:

$$\begin{aligned} \Pi_X(X) &= 0 \\ \Pi_X(u; S'(X)) &= \Pi_X(S'(X)) \\ \Pi_X(S_1(X) \oplus S_2) &= \Pi_X(S_1(X)) \\ \Pi_X(S_1 \oplus S_2(X)) &= \Pi_X(S_2(X)) \\ \Pi_X(\text{If } S'' \text{ Then } S'(X)) &= \Pi_X(S'(X)) \\ \Pi_X(\text{If } S''(X) \text{ Then } S') &= \Pi_X(S''(X)) \\ \Pi_X(\mu Y.S'(X, Y)) &= \Pi_X(S'(X, Y)) \\ \Pi_X((\bigwedge_{i=1,m} @i.S_i) \wedge @j.S'(X)) &= 1 + \Pi_X(S'(X)) \\ \Pi_X(\text{Most}(S'(X))) &= 1 + \Pi_X(S'(X)). \end{aligned}$$

Example 61. Let u, u' be patterns in \mathcal{T} , and let S' be a fixed-point free T_μ -strategy. Let $S(X)$ be the following T_μ -strategy:

$$S(X) = u; @1.(\text{Most}(u'; @2.X) \oplus S').$$

There are three jumps between the root of $S(X)$ and X , which are $@1.(.)$ and $\text{Most}(.)$ and $@2.(.)$. That is,

$$\begin{aligned} \Pi_X(S(X)) &= \Pi_X(u; @1.(\text{Most}(u'; @2.X) \oplus S')) \\ &= \Pi_X(@1.(\text{Most}(u'; @2.X) \oplus S')) \\ &= 1 + \Pi_X(\text{Most}(u'; @2.X) \oplus S') \\ &= 1 + \Pi_X(\text{Most}(u'; @2.X)) \\ &= 2 + \Pi_X(u'; @2.X) \\ &= 2 + \Pi_X(@2.X) \\ &= 3 + \Pi_X(X) \\ &= 3. \end{aligned}$$

Notice that if S is monotonic, then for every sub- T_μ -strategy $\mu X.S'(X)$ of S , we have that $\Pi_X(S'(X)) \geq 1$.

10.2. Termination and confluence of the unification reduction system

To show the termination of the reduction system \mathcal{U} we need to define a measure on the tuples that strictly decreases with each derivation rule. Notice that all the reduction rules strictly decrease the size of one or both of the left-hand side T_μ -strategies except the fixed-point rules (8a) and (8b) which can replace $\mu X.S(X)$ with $S(\mu X.S(X))$ that is larger than $\mu X.S(X)$. However, these fixed-point rules increase the size of the memory because the right-hand side memory is augmented with $(\mu X.S(X), R, \cdot)$. Since the size of any memory related to two fixed T_μ -strategies is bounded, to ensure the termination of \mathcal{U} , we need to define a measure that couples the difference between such bound and the size of the memory with the size of the T_μ -strategies.

Definition 62. Let S and R be T_μ -strategies, and let \mathcal{M} be a memory in $\mathfrak{M}(S, R)$. We pose

$$\Lambda(S, R, \mathcal{M}) := |\Phi_\mu(S)| \cdot |\Phi(R)| + |\Phi(S)| \cdot |\Phi_\mu(R)| - |\mathcal{M}|$$

and define the measure $(\Lambda(S, R, \mathcal{M}), \Delta(S), \Delta(R))$.

Proposition 63. The unification reduction system \mathcal{U} enjoys the following properties.

1. The reduction system \mathcal{U} is terminating and confluent.
2. The normal form of a pre- T_μ -strategy with respect to \mathcal{U} is a T_μ -strategy in \mathcal{C} (i.e. the normal form does not contain tuples).

Proof. 1. The termination is guaranteed by the fact that each reduction rule strictly decreases the measure $(\Lambda(S, R, \mathcal{M}), \Delta(S), \Delta(R))$ with respect to the lexicographic order. The confluence is guaranteed by the priority order imposed on the reduction rules.
 2. Each rule either advances in the T_μ -strategy of the tuple of the left-hand side part of this rule, or reduces the left-hand side part into a T_μ -strategy. \square

We show next in Lemma 64 a useful property of the unification of monotonic T_μ -strategies: if the same fixed-point T_μ -strategy appears twice in a derivation with respect to the unification reduction system \mathcal{U} , then this derivation produces a jump. Indeed this is a direct consequence of monotonicity.

Lemma 64. Let $\mu X.S(X)$, R and R' be T_μ -strategies. Let $T(Z)$ be a pre- T_μ -strategy. Let $\mathcal{M}, \mathcal{M}' \in \mathfrak{M}$ be memories. If there is a series of derivations of one of the following forms:

$$\begin{aligned} &\langle \mu X.S(X), R, \mathcal{M} \rangle \xrightarrow{*} T(\langle \mu X.S(X), R', \mathcal{M}' \rangle) \\ &\text{or} \\ &\langle R, \mu X.S(X), \mathcal{M} \rangle \xrightarrow{*} T(\langle R', \mu X.S(X), \mathcal{M}' \rangle) \\ &\text{or} \\ &\langle \mu X.S(X), R, \mathcal{M} \rangle \xrightarrow{*} T(\mu X.S(X)) \\ &\text{or} \\ &\langle R, \mu X.S(X), \mathcal{M} \rangle \xrightarrow{*} T(\mu X.S(X)) \end{aligned}$$

in \mathcal{U} , then there is at least one jump between the root of $T(Z)$ and Z . That is,

$$\Pi_Z(T(Z)) \geq 1.$$

Proof. We only consider the first derivation since the other ones can be obtained by the same arguments. Recall that $\mu X.S(X)$ is monotonic by the general Assumption 31, that is, between $\mu X.S(X)$ and X there is a position jump or $\text{Most}(\cdot)$. This implies that, there exist T_μ -strategies \tilde{S} and \tilde{R} , a memory $\tilde{\mathcal{M}}$, a tuple $\tilde{T}(\tilde{Z})$, and a series of derivations

$$\langle \mu X.S(X), R, \mathcal{M} \rangle \xrightarrow{*} \tilde{T}(\langle \tilde{S}, \tilde{R}, \tilde{\mathcal{M}} \rangle) \xrightarrow{*} T(\langle \mu X.S(X), R', \mathcal{M}' \rangle)$$

in \mathcal{U} where \tilde{S} is either of the form $\tilde{S} = \bigwedge_i @i.S'_i$ or $\tilde{S} = \text{Most}(S'')$. This implies that one of the rules (4a), (4b), (7a), (7b), (7c) is applied in the derivation from $\tilde{T}(\langle \tilde{S}, \tilde{R}, \tilde{\mathcal{M}} \rangle)$ to $T(\langle \mu X.S(X), R', \mathcal{M}' \rangle)$. Each of which produces a position jump or $\text{Most}(\cdot)$. \square

An immediate consequence of the previous Lemma 64 is the following Corollary.

Corollary 65. *The unification of two monotonic T_μ -strategies is a monotonic T_μ -strategy.*

10.3. Iteration mapping and (generalized) unfolding of T_μ -strategies

We next generalize the notion of unfolding of T_μ -strategies to allow the replacement of each fixed-point constructor of a T_μ -strategy by an iteration of arbitrary fixed size. The resulting T_μ -strategy is obviously fixed-point free.

Definition 66 (Iteration mapping, unfolding of a T_μ -strategy). Let S be a T_μ -strategy with bound fixed-point variables X_1, \dots, X_r and let $\mathbf{s} : \{X_1, \dots, X_r\} \rightarrow \mathbb{N}$ be a mapping, called hereafter *iteration mapping*. The *unfolding* of S with respect to \mathbf{s} , denoted by $\rho_{\mathbf{s}}(S)$, consists of replacing each fixed-point constructor by a certain number of iterations given by \mathbf{s} . It is inductively defined as follows:

$$\begin{aligned} \rho_{\mathbf{s}}(\mathbf{f}) &= \mathbf{f} \\ \rho_{\mathbf{s}}(X) &= X \\ \rho_{\mathbf{s}}(@\varepsilon.\tau) &= @\varepsilon.\tau \\ \rho_{\mathbf{s}}(u; S) &= u; \rho_{\mathbf{s}}(S) \\ \rho_{\mathbf{s}}(@p.S) &= @p.\rho_{\mathbf{s}}(S) \\ \rho_{\mathbf{s}}(S_1 \oplus S_2) &= \rho_{\mathbf{s}}(S_1) \oplus \rho_{\mathbf{s}}(S_2) \\ \rho_{\mathbf{s}}\left(\bigwedge_{i=1,m} S_i\right) &= \bigwedge_{i=1,m} \rho_{\mathbf{s}}(S_i) \\ \rho_{\mathbf{s}}(\text{If } S_1 \text{ Then } S_2) &= \text{If } \rho_{\mathbf{s}}(S_1) \text{ Then } \rho_{\mathbf{s}}(S_2) \\ \rho_{\mathbf{s}}(\mu X.S(X)) &= \mu^{\mathbf{s}(X)} X.\rho_{\mathbf{s}}(S(X)). \end{aligned}$$

For two iteration mappings \mathbf{s} and \mathbf{s}' defined on the same domain, we shall write $\mathbf{s} \geq \mathbf{s}'$ to mean that $\mathbf{s}(X) \geq \mathbf{s}'(X)$ for any X in the domain. We shall write also $\mathbf{s} > \mathbf{s}'$ to mean that $\mathbf{s} \geq \mathbf{s}'$ and there exists X in the domain such that $\mathbf{s}(X) > \mathbf{s}'(X)$.

Notice that, for a T_μ -strategy S and an iteration mapping \mathbf{s} , if S is fixed-point free then $\rho_{\mathbf{s}}(S) = S$.

Example 67 (Unfolding of a T_μ -strategy). Let $S(X)$ and $R(X)$ be fixed-point free T_μ -strategies. Let

$$T(X) = S(X) \oplus \mu Y.R(Y)$$

be a T_μ -strategy. Consider the iteration mapping \mathbf{s} defined by:

$$\mathbf{s} = \{X \mapsto 2, Y \mapsto 3\}.$$

Then the unfolding of the T_μ -strategy $\mu X.T(X)$ with respect to \mathbf{s} is defined as follows:

$$\begin{aligned} \rho_{\mathbf{s}}(\mu X.T(X)) &= \mu^2 X.\rho_{\mathbf{s}}(T(X)) \\ &= \mu^2 X.\rho_{\mathbf{s}}(S(X) \oplus \mu Y.R(Y)) \\ &= \mu^2 X.(\rho_{\mathbf{s}}(S(X)) \oplus \rho_{\mathbf{s}}(\mu Y.R(Y))) \\ &= \mu^2 X.(S(X) \oplus \rho_{\mathbf{s}}(\mu Y.R(Y))) && \text{(Since } S(X) \text{ is fixed-point free)} \\ &= \mu^2 X.(S(X) \oplus \mu^3 Y.\rho_{\mathbf{s}}(R(Y))) \\ &= \mu^2 X.(S(X) \oplus \mu^3 Y.R(Y)). && \text{(Since } S(X) \text{ is fixed-point free)} \end{aligned}$$

Further computations involve the replacement of each fixed-point operator by an iteration, given in Definition 16, as follows. Let $T'(X)$ be the T_μ -strategy:

$$T'(X) = S(X) \oplus \mu^3 Y.R(Y),$$

hence,

$$\begin{aligned}
\mu^2 X.(S(X) \oplus \mu^3 Y.R(Y)) &= \mu^2 X.T'(X) \\
&= T'(\mu^1 X.T'(X)) \\
&= T'(T'(\mathfrak{f})) && \text{(Def. 16)} \\
&= S(T'(\mathfrak{f})) \oplus \mu^3 Y.R(Y) && \text{(Def. of } T'(X)) \\
&= S(S(\mathfrak{f}) \oplus \mu^3 Y.R(Y)) \oplus \mu^3 Y.R(Y) && \text{(Def. of } T'(X)) \\
&= S(S(\mathfrak{f}) \oplus R(R(R(\mathfrak{f})))) \oplus R(R(R(\mathfrak{f}))).
\end{aligned}$$

10.4. Properties of \mathbb{T}_μ -strategies and their fixed-points

We give fundamental properties of \mathbb{T}_μ -strategies regarding their semantics and fixed-points. Namely the properties related, on the one hand, to the composition of \mathbb{T}_μ -strategies in the sense of a \mathbb{T}_μ -strategy being a sub- \mathbb{T}_μ -strategy of another one (Lemma 68), and on the other hand, a sufficient condition under which a \mathbb{T}_μ -strategy is equivalent to a fixed-point one (i.e. Corollary 70). Finally, we study the equivalence between a \mathbb{T}_μ -strategy and its unfolding (Lemma 71).

Lemma 68. Let $S(X)$, R and R' be \mathbb{T}_μ -strategies where the fixed-point variable X appears once in $S(X)$, and let $n', n'' \geq 1$.

1. If $R \equiv_{n'} R'$ and $n'' = \Pi_X(S(X))$ then $S(R) \equiv_{n'+n''} S(R')$.
2. If $R \equiv_{n'} R'$ and $n'' \leq n'$ then $S(R) \equiv_{n''} S(R')$.
3. For any fixed-point free \mathbb{T}_μ -strategy $\tilde{S}(X^1, \dots, X^k)$, and \mathbb{T}_μ -strategies S_1, \dots, S_k with $k \geq 1$, we have that

$$\tilde{S}(S_1, \dots, S_k) \equiv_{\mathbf{m}} \tilde{S}(\mathfrak{f}, \dots, \mathfrak{f}) \quad \text{where} \quad \mathbf{m} = \min \{ \Pi_{X^i}(\tilde{S}(X^1, \dots, X^k)) \mid S_i \neq \mathfrak{f}, i = 1, \dots, k \}. \quad (4)$$

Proof. The proof of the two first items can be easily done by a straightforward induction on $S(X)$ and does not provide any difficulties. The proof of the third item can be easily done by a straightforward induction on $\tilde{S}(X^1, \dots, X^k)$ since it is a generalization of the first item. \square

Notice that Eq. (4) holds as well if we omit the condition $S_i \neq \mathfrak{f}$, i.e.

$$\tilde{S}(S_1, \dots, S_k) \equiv_{\mathbf{m}} \tilde{S}(\mathfrak{f}, \dots, \mathfrak{f}) \quad \text{where} \quad \mathbf{m} = \min \{ \Pi_{X^i}(\tilde{S}(X^1, \dots, X^k)) \mid i = 1, \dots, k \} \quad (5)$$

because

$$\min \{ \Pi_{X^i}(\tilde{S}(X^1, \dots, X^k)) \mid i = 1, \dots, k \} \leq \min \{ \Pi_{X^i}(\tilde{S}(X^1, \dots, X^k)) \mid S_i \neq \mathfrak{f}, i = 1, \dots, k \}.$$

Indeed, Eq. (4) is more refined than Eq. (5) but we shall sometimes use the latter one.

From Item 2 of Lemma 68 it follows that one has to keep in mind that the notion of n -equivalence between \mathbb{T}_μ -strategies can be equivalently restated as follows: two \mathbb{T}_μ -strategies are n -equivalent if they give the same result when applied to any term t of depth $\delta(t) \leq n$ and not just of depth $\delta(t) = n$ as initially defined in Definition 21.

Corollary 69. Let $T(X)$ and R be \mathbb{T}_μ -strategies. For any term t of depth $\delta(t) = n$ and any positive integer $n' \geq 1$, if we denote by $T^{(n)}(R)$ the n -times iteration \mathbb{T}_μ -strategy $T(T(\dots(R)))$, then we have that

$$\llbracket \mu^{n+n'} X.T(X) \rrbracket(t) = \llbracket \mu^n X.T(X) \rrbracket(t) = \llbracket T^{(n)}(R) \rrbracket(t). \quad (6)$$

The following Corollary is a crucial one. It guarantees that to show that two \mathbb{T}_μ -strategies $\mu X.T(X)$ and R are n -equivalent, it is enough to show that R is a fixed-point of $T(X)$ in the sense that $T(R)$ and R are n -equivalent.

Corollary 70. Let $T(X)$ and R be \mathbb{T}_μ -strategies. For any $n \geq 1$, we have that

$$\text{if} \quad T(R) \equiv_n R \quad \text{then} \quad \mu X.T(X) \equiv_n R.$$

Proof. Let t be a term of depth n . If $\llbracket T(R) \rrbracket(t) = \llbracket R \rrbracket(t)$ then clearly $\llbracket T^{(n)}(R) \rrbracket(t) = \llbracket R \rrbracket(t)$. On the other hand, it follows from the second equality of Eq. (6) of Corollary 69 that $\llbracket \mu^n X.T(X) \rrbracket(t) = \llbracket T^{(n)}(R) \rrbracket(t)$. Hence $\llbracket \mu^n X.T(X) \rrbracket(t) = \llbracket R \rrbracket(t)$. But $\llbracket \mu^{n+n'} X.T(X) \rrbracket(t) = \llbracket \mu X.T(X) \rrbracket(t)$ holds by Definition 18 of the semantics of \mathbb{T}_μ -strategies. \square

We show in the following Lemma 71 that a \mathbb{T}_μ -strategy is \mathbf{m} -equivalent to its unfolding, where \mathbf{m} is the minimal number of iterations in the unfolding. To achieve this, we need a technical property (i.e. Eq. (8)) that will be used later on in other proofs.

Lemma 71. Let S be a \mathbb{T}_μ -strategy with (bound) fixed-point variables X_1, \dots, X_s and let $\mathbf{s} : \{X_1, \dots, X_s\} \rightarrow \mathbb{N}$ be an iteration mapping.

- (i) If S is a fixed-point \mathbb{T}_μ -strategy, say $\mu X.S'(X)$ with $X \in \{X_1, \dots, X_s\}$, then there exists a fixed-point free \mathbb{T}_μ -strategy $\tilde{S}(X^1, \dots, X^m)$ with $m \geq 1$, and \mathbb{T}_μ -strategies $S_1, \dots, S_{m-1}, S_m(X)$ such that for any $n \geq 1$,

$$\mu^n X.S'(X) = \tilde{S}(S_1, \dots, S_{m-1}, S_m(\mu^{n-1} X.S'(X))) \quad (7)$$

$$\rho_{\mathbf{s}}(\mu X.S'(X)) = \tilde{S}(\rho_{\mathbf{s}}(S_1), \dots, \rho_{\mathbf{s}}(S_{m-1}), \rho_{\mathbf{s}'}(S_m(\mu X.S'(X)))) \quad (8)$$

where \mathbf{s}' is the iteration mapping defined on $\{X_1, \dots, X_s\}$ by $\mathbf{s}'(X) = \mathbf{s}(X) - 1$ and $\mathbf{s}'(X') = \mathbf{s}(X')$ for $X' \neq X$.

- (ii) If $\mathbf{m} = \min\{\mathbf{s}(X_1), \dots, \mathbf{s}(X_s)\}$, then $S \equiv_{\mathbf{m}} \rho_{\mathbf{s}}(S)$.

Remark 72. Let S be a \mathbb{T}_μ -strategy with (bound) fixed-point variables X_1, \dots, X_s and let $\mathbf{s}_1, \mathbf{s}_2 : \{X_1, \dots, X_s\} \rightarrow \mathbb{N}$ be iteration mappings where $\mathbf{s}_1 \geq \mathbf{s}_2$. Let $\mathbf{m}_1 = \min\{\mathbf{s}_1(X_i) \mid i = 1, \dots, s\}$, $\mathbf{m}_2 = \min\{\mathbf{s}_2(X_i) \mid i = 1, \dots, s\}$ and $\mathbf{m} = \min(\mathbf{m}_1, \mathbf{m}_2)$. Then it follows from Item (ii) of Lemma 71 that $\rho_{\mathbf{s}_1}(S) \equiv_{\mathbf{m}} \rho_{\mathbf{s}_2}(S)$ since $S \equiv_{\mathbf{m}_1} \rho_{\mathbf{s}_1}(S)$ and $S \equiv_{\mathbf{m}_2} \rho_{\mathbf{s}_2}(S)$. Besides, it follows from the proof of this item that $\rho_{\mathbf{s}_1}(S)$ and $\rho_{\mathbf{s}_2}(S)$ can be written as

$$\rho_{\mathbf{s}_1}(S) = T(T_1, \dots, T_m)$$

$$\rho_{\mathbf{s}_2}(S) = T(\mathfrak{f}, \dots, \mathfrak{f}).$$

10.5. The composition lemma

In the following key Lemma 73 we shall formulate how the unification of two given \mathbb{T}_μ -strategies behaves with respect to their sub- \mathbb{T}_μ -strategies. This Lemma is very useful and will be heavily used throughout this paper, namely when it comes to make a structural induction on the given \mathbb{T}_μ -strategies. More precisely, we shall show, under some assumptions, that the unification of a \mathbb{T}_μ -strategy $S'(\xi_1, \dots, \xi_k)$ with a \mathbb{T}_μ -strategy $R'(\zeta_1, \dots, \zeta_l)$ yields a \mathbb{T}_μ -strategy $T(T_1, \dots, T_m)$ where each T_i is either the unification of some ξ_j with a sub- \mathbb{T}_μ -strategy of $R'(\zeta_1, \dots, \zeta_l)$, or the unification of some sub- \mathbb{T}_μ -strategy of $S'(\xi_1, \dots, \xi_k)$ with a ζ_j .

Lemma 73 (Composition Lemma). Let S and R be \mathbb{T}_μ -strategies. Assume that there are fixed-point free \mathbb{T}_μ -strategies $S'(X_1, \dots, X_k)$ and $R'(Y_1, \dots, Y_l)$, where $k \geq 1$ and $l \geq 1$, and \mathbb{T}_μ -strategies ξ_1, \dots, ξ_k where $\xi_i \in \Phi(S)$, and \mathbb{T}_μ -strategies ζ_1, \dots, ζ_l where $\zeta_i \in \Phi(R)$, such that S and R can be written as:

$$S = S'(\xi_1, \dots, \xi_k) \quad R = R'(\zeta_1, \dots, \zeta_l).$$

Then, there is a fixed-point free \mathbb{T}_μ -strategy $T(Z_1, \dots, Z_m)$ and \mathbb{T}_μ -strategies T_1, \dots, T_m , where $m \geq 1$, such that

$$S \wedge R = T(T_1, \dots, T_m)$$

where for any $i = 1, \dots, m$, there is an alternative between the two following choices.

- (a) There are $j \in \{1, \dots, k\}$, a \mathbb{T}_μ -strategy $R^i(Y^1, \dots, Y^{l'})$ that is a sub- \mathbb{T}_μ -strategy of $R'(Y_1, \dots, Y_l)$ with $l' \leq l$, and a set of \mathbb{T}_μ -strategies $\{\zeta^1, \dots, \zeta^{l'}\} \subseteq \{\zeta_1, \dots, \zeta_l\}$ such that

$$T_i = \xi_j \wedge R^i(\zeta^1, \dots, \zeta^{l'}) \quad \text{or} \quad T_i = \xi_j. \quad (9)$$

- (b) There are $j \in \{1, \dots, l\}$, a \mathbb{T}_μ -strategy $S^i(X^1, \dots, X^{k'})$ that is a sub- \mathbb{T}_μ -strategy of $S'(X_1, \dots, X_k)$ with $k' \leq k$, and a set of \mathbb{T}_μ -strategies $\{\xi^1, \dots, \xi^{k'}\} \subseteq \{\xi_1, \dots, \xi_k\}$ such that

$$T_i = S^i(\xi^1, \dots, \xi^{k'}) \wedge \zeta_j \quad \text{or} \quad T_i = \zeta_j. \quad (10)$$

11. Unification and unfolding

In this section we show two independent results which will be a crucial ingredient for the next section 12 in which the main theorems will be proved. The first result, shown in Subsection 11.1, establishes a semantic equivalence between the unification of unfoldings of two \mathbb{T}_μ -strategies, say $\rho_{\mathbf{s}}(S) \wedge \rho_{\mathbf{r}}(R)$, and the unification of other unfoldings of the same \mathbb{T}_μ -strategies, say $\rho_{\mathbf{s}'}(S) \wedge \rho_{\mathbf{r}'}(R)$. The second result, shown in Subsection 11.4, relates the structure of the unification of two \mathbb{T}_μ -strategies, say $S \wedge R$, with that of their unfoldings, say $\rho_{\mathbf{s}}(S) \wedge \rho_{\mathbf{r}}(R)$, according to a relation of similarity that will be formalized in Subsection 11.3. In Subsection 11.2 we introduce some notions, namely the underlying structure of the set of fixed-point sub- \mathbb{T}_μ -strategies of a given \mathbb{T}_μ -strategy. In Subsection 11.3 we introduce two relations of similarity, a strong and a weak one, between a \mathbb{T}_μ -strategy and a fixed-point free one.

11.1. The equivalence between the unification of several unfoldings of two T_μ -strategies

The purpose of this section is to relate two kinds of fixed-point free T_μ -strategies: the T_μ -strategy that results from the unification of an unfolding of two T_μ -strategies, and the T_μ -strategy that results from the unification of a different unfolding of the same two T_μ -strategies. The purpose is to show that these two resulting T_μ -strategies are equivalent for any term of a certain depth that depends on the unfoldings. Given four iteration mappings $\mathbf{s}, \mathbf{s}', \mathbf{r}, \mathbf{r}'$ where \mathbf{s} and \mathbf{s}' (resp. \mathbf{r} and \mathbf{r}') are defined on the same domain, we shall devise a measure between two the pairs (\mathbf{s}, \mathbf{r}) and $(\mathbf{s}', \mathbf{r}')$, called *codistance* and denoted by $D^*((\mathbf{s}, \mathbf{r}), (\mathbf{s}', \mathbf{r}'))$, and show that the T_μ -strategies $\rho_{\mathbf{s}}(S) \wedge \rho_{\mathbf{r}}(R)$ and $\rho_{\mathbf{s}'}(S) \wedge \rho_{\mathbf{r}'}(R)$ are equivalent for any term of depth at most $D^*((\mathbf{s}, \mathbf{r}), (\mathbf{s}', \mathbf{r}'))$. The definition of this measure will be given in Definition 74. We shall compare in Lemma 76 the fixed-point free T_μ -strategy $\rho_{\mathbf{s}}(S) \wedge \rho_{\mathbf{r}}(R)$ with the (fixed-point free) T_μ -strategy $\rho_{\mathbf{s}'}(S) \wedge \rho_{\mathbf{r}'}(R)$, namely when $\mathbf{s} \geq \mathbf{s}'$ and $\mathbf{r} \geq \mathbf{r}'$, by showing that T_μ -strategy $\rho_{\mathbf{s}}(S) \wedge \rho_{\mathbf{r}}(R)$ and T_μ -strategy $\rho_{\mathbf{s}'}(S) \wedge \rho_{\mathbf{r}'}(R)$ have the same structure except that the former T_μ -strategy is deeper than the latter. The equivalence is the main result of this section and will be proved in Corollary 77.

To illustrate the idea and justify the name of the codistance between two pairs of iteration mappings, we first consider the codistance between two iteration mappings with the same domain. Let \mathbf{s}, \mathbf{s}' and \mathbf{s}'' be iteration mappings and assume

$$\mathbf{s} = \{X_1 \mapsto 100, X_2 \mapsto 100, X_3 \mapsto 5\} \quad (11)$$

$$\mathbf{s}' = \{X_1 \mapsto 100, X_2 \mapsto 60, X_3 \mapsto 5\} \quad (12)$$

$$\mathbf{s}'' = \{X_1 \mapsto 100, X_2 \mapsto 60, X_3 \mapsto 4\}. \quad (13)$$

It is clear that for any T_μ -strategy S with bound variables X_1, X_2, X_3 that the (fixed-point free) T_μ -strategies $\rho_{\mathbf{s}}(S)$ and $\rho_{\mathbf{s}'}(S)$ are equivalent for any t of depth at most 60. This number corresponds to the minimal $\mathbf{s}'(X_i)$ such that $\mathbf{s}'(X_i) \neq \mathbf{s}(X_i)$, for $i = 1, \dots, 3$. For the same reason, $\rho_{\mathbf{s}}(S)$ and $\rho_{\mathbf{s}''}(S)$ are equivalent for any term of depth at most 4. Obviously, $\rho_{\mathbf{s}}(S)$ is equivalent with itself for any term, and this will be taken into account in the definition of codistance 74 by saying that the codistance between an iteration mapping and itself is infinity. Besides, the more two iterations mappings are far from each other, the less is their codistance, which justifies the name of codistance. This idea of codistance between two iteration mappings can be adapted as well to measure the codistance between two pairs of iteration mappings as follows.

Definition 74 (*Codistance between pairs of iteration mappings*). Let $\mathbf{s}, \mathbf{s}' : \{X_1, \dots, X_s\} \rightarrow \mathbb{N}$ and $\mathbf{r}, \mathbf{r}' : \{Y_1, \dots, Y_r\} \rightarrow \mathbb{N}$ be iteration mappings such that $\mathbf{s} \geq \mathbf{s}'$ and $\mathbf{r} \geq \mathbf{r}'$. We define the *codistance* between \mathbf{s} and \mathbf{s}' by:

$$d^*(\mathbf{s}, \mathbf{s}') = \begin{cases} \min\{\mathbf{s}'(X_i) \mid \mathbf{s}'(X_i) \neq \mathbf{s}(X_i) \text{ for } i = 1, \dots, s\} & \text{if } \mathbf{s} > \mathbf{s}' \\ \infty & \text{if } \mathbf{s} = \mathbf{s}'. \end{cases}$$

We define the *codistance* between the pairs (\mathbf{s}, \mathbf{r}) and $(\mathbf{s}', \mathbf{r}')$ by:

$$D^*((\mathbf{s}, \mathbf{r}), (\mathbf{s}', \mathbf{r}')) = \min\{d^*(\mathbf{s}, \mathbf{s}'), d^*(\mathbf{r}, \mathbf{r}')\}.$$

Example 75. We only give an example of the codistance d^* since the computation of D^* is straightforward. If we consider the iteration mappings $\mathbf{s}, \mathbf{s}', \mathbf{s}''$ defined above by Eqs. (11), (12), (13) respectively, then

$$d^*(\mathbf{s}, \mathbf{s}) = d^*(\mathbf{s}', \mathbf{s}') = d^*(\mathbf{s}'', \mathbf{s}'') = \infty,$$

$$d^*(\mathbf{s}, \mathbf{s}') = 60,$$

$$d^*(\mathbf{s}, \mathbf{s}'') = 4.$$

In the following Lemma 76 (which makes use of Lemma 71) and Corollary 77 we use the following definitions: let S and R be T_μ -strategies with bound fixed-point variables X_1, \dots, X_s and Y_1, \dots, Y_r , respectively. Let $\mathbf{s}_1, \mathbf{s}_2 : \{X_1, \dots, X_s\} \rightarrow \mathbb{N}$ and $\mathbf{r}_1, \mathbf{r}_2 : \{Y_1, \dots, Y_r\} \rightarrow \mathbb{N}$ be iteration mappings where $\mathbf{s}_1 \geq \mathbf{s}_2$ and $\mathbf{r}_1 \geq \mathbf{r}_2$.

Lemma 76. *There exist fixed-point free T_μ -strategies $T_1, \dots, T_m, T(Z_1, \dots, Z_m)$, where each Z_i is a free fixed-point variable and $m \geq 1$, such that $\rho_{\mathbf{s}_1}(S) \wedge \rho_{\mathbf{r}_1}(R)$ and $\rho_{\mathbf{s}_2}(S) \wedge \rho_{\mathbf{r}_2}(R)$ can be written as*

$$\rho_{\mathbf{s}_1}(S) \wedge \rho_{\mathbf{r}_1}(R) = T(T_1, \dots, T_m)$$

$$\rho_{\mathbf{s}_2}(S) \wedge \rho_{\mathbf{r}_2}(R) = T(\mathbf{j}, \dots, \mathbf{j}).$$

The following Corollary 77 follows from Lemma 76, it confirms that the definition of codistance between two pairs of iteration mappings is the right one since it provides an upper bound for the depth of terms on which the T_μ -strategies $\rho_{\mathbf{s}}(S) \wedge \rho_{\mathbf{r}}(R)$ and $\rho_{\mathbf{s}'}(S) \wedge \rho_{\mathbf{r}'}(R)$ are equivalent. It is easy to construct examples where this bound is reached.

Corollary 77. *We have that*

$$\rho_{s_1}(S) \wedge \rho_{r_1}(R) \equiv_{D^*((s_1, r_1), (s_2, r_2))} \rho_{s_2}(S) \wedge \rho_{r_2}(R). \quad (14)$$

Proof. It follows from Lemma 76 that there exist fixed-point free T_μ -strategies $T_1, \dots, T_m, T(Z_1, \dots, Z_m)$, where each Z_i is a fixed-point variable and $m \geq 1$, such that $\rho_{s_1}(S) \wedge \rho_{r_1}(R)$ and $\rho_{s_2}(S) \wedge \rho_{r_2}(R)$ can be written as

$$\begin{aligned} \rho_{s_1}(S) \wedge \rho_{r_1}(R) &= T(T_1, \dots, T_m) \\ \rho_{s_2}(S) \wedge \rho_{r_2}(R) &= T(f, \dots, f). \end{aligned}$$

From Item (3) of Lemma 68, it follows that to prove Eq. (14) it suffices to show that

$$\min \{ \Pi_{Z_i}(T(Z_1, \dots, Z_m)) \mid T_i \neq f, i = 1, \dots, m \} \geq D^*((s_1, r_1), (s_2, r_2)). \quad (15)$$

Assume that $D^*((s_1, r_1), (s_2, r_2)) = d^*(s_1, s_2)$ with $s_1 > s_2$. Assume that there exists $v \in \{1, \dots, s\}$ such that $\min\{s_2(X_j) \mid j = 1, \dots, s\} = s_2(X_v)$. Let $\mu_{X_v.S_v}(X_v)$ be the fixed-point T_μ -strategy related to X_v . From the monotonicity property it follows that the shortest path in terms of number of jumps from the root of $T(Z_1, \dots, Z_m)$ to some Z_i , say Z_w with $w \in \{1, \dots, m\}$, $\mu_{X_v.S_v}(X_v)$ unfolded $s_2(X_v)$ times giving arise to at least $s_2(X_v)$ positions. If $s_1(X_v) > s_2(X_v)$ then in this first case we have by the definition of d^* that $d^*(s_1, s_2) = s_2(X_v)$ and we are done. If $s_1(X_v) = s_2(X_v)$ then in this case $T_w = f$ and we pick another $v' \in \{1, \dots, s\} \setminus \{v\}$ such that $\min\{s_2(X_j) \mid j \in \{1, \dots, s\} \setminus \{v\}\} = s_2(X_{v'})$. If such v' does not exist then this means that $T_i = f$ for any $i \in \{1, \dots, m\}$ thus $\rho_{s_1}(S) \wedge \rho_{r_1}(R)$ and $\rho_{s_2}(S) \wedge \rho_{r_2}(R)$ are equivalent in the strong sense. Otherwise, we reiterate the same reasoning of the first case with v' instead of v . \square

11.2. Fixed-point tree and fixed-point sequence

This Subsection is first devoted to the definitions of two notions related to the tree-like structure underlying the set of all fixed-point sub- T_μ -strategies of a given T_μ -strategy, Definition 78. Roughly speaking, if we look at all fixed-point sub- T_μ -strategies of a given T_μ -strategy, they form a tree in the sense that there is an arrow from a fixed-point T_μ -strategy S_1 to a fixed-point T_μ -strategy S_2 if S_2 is a sub- T_μ -strategy of S_1 together with further conditions.

Definition 78 (Fixed-point tree and fixed-point sequence of a T_μ -strategy). Let S be a strategy in which each fixed-point variable appears once.

- i) The *fixed-point tree* of S , denoted by $\mathcal{T}(S)$ or simply \mathcal{T} , is the pair $(\Phi_\mu(S), \sqsupset)$, where \sqsupset is a binary relation over $\Phi_\mu(S)$ defined as follows: $S_1 \sqsupset S_2$ iff S_2 is a sub- T_μ -strategy of S_1 with $S_1 \neq S_2$, and there is no T_μ -strategy S' in $\Phi_\mu(S)$ such that $S' \neq S_1$, $S' \neq S_2$, S_2 is a sub- T_μ -strategy of S' , and S' is a sub- T_μ -strategy of S_1 .
- ii) A sequence S_1, \dots, S_m in the tree $\mathcal{T}(S)$, where $m \geq 1$, is a set of T_μ -strategies where each S_i is in $\Phi_\mu(S)$ such that either $m = 1$ or $m \geq 2$ and in this case $S_i \sqsupset S_{i+1}$, for $i = 1, \dots, m-1$. Such a sequence will be denoted by $S_1 \sqsupset \dots \sqsupset S_m$.
- iii) A sequence $S_1 \sqsupset \dots \sqsupset S_m$ in $\mathcal{T}(S)$ is *left-maximal* (resp. *right-maximal*) if there is no $S' \in \Phi_\mu(S)$ such that $S' \neq S_1$ (resp. $S' \neq S_m$) and $S' \sqsupset S_1$ (resp. $S_m \sqsupset S'$). A sequence is maximal if it is both left-maximal and right-maximal. In such case S_1 is called a root, while S_m is called a leaf.
- iv) A fixed-point tree \mathcal{T} is *connected* if it has just one root.

Notice that if a fixed-point tree is not connected then it is composed of many fixed-point sub-trees each of which is connected.

Example 79. Let $M_1(Y), S_1(X_1), M_2(Z, Z')$ and $S_3(X_3)$ be fixed-point free T_μ -strategies. Consider the T_μ -strategy

$$H = \mu Z. (M_1(\mu X_1.S_1(X_1)) \oplus \mu X_2.M_2(Z, X_2, \mu X_3.S_3(X_3))).$$

The set of fixed-point sub- T_μ -strategies is

$$\Phi_\mu(H) = \{H, \mu X_1.S_1(X_1), \mu X_2.M_2(Z, X_2, \mu X_3.S_3(X_3)), \mu X_3.S_3(X_3)\}$$

and the fixed-point tree $\mathcal{T}(H) = (\Phi_\mu(H), \sqsupset)$ comes with the two maximal sequences

$$\begin{aligned} H \sqsupset \mu X_1.S_1(X_1) \\ H \sqsupset \mu X_2.M_2(Z, X_2, \mu X_3.S_3(X_3)) \sqsupset \mu X_3.S_3(X_3) \end{aligned}$$

Indeed, H is the root of $\mathcal{T}(H)$ while $\mu X_1.S_1(X_1)$ and $\mu X_3.S_3(X_3)$ are leaves. However if we take $H' = \mu X_4.S_4(X_4)$ then the tree $\mathcal{T}(H \oplus H')$ is no longer connected since it has two roots: H and H' .

Table 1
Inference rules for $(\mathcal{C}, \mathcal{C}_0)$ -simulations.

$\frac{S' = R'}{S' \mathfrak{R} R'} \quad S', R' \in \mathcal{C}_0$	$\frac{S_i \mathfrak{R} R_i}{S'(S_1, \dots, S_m) \mathfrak{R} S'(R_1, \dots, R_m)} \quad S'(X_1, \dots, X_m) \in \mathcal{C}_0$
$\frac{}{\mu X.S'(X) \mathfrak{R} \mathfrak{f}}$	$\frac{S(\mu X.S'(X)) \mathfrak{R} R'}{\mu X.S'(X) \mathfrak{R} R'}$

11.3. The relations of $(\mathcal{C}, \mathcal{C}_0)$ -simulation and $(\mathcal{C}, \mathcal{C}_0)$ -quasi-simulation

In Section 7 we informally outlined the proof of the main result of this paper. Namely, we described how to relate the structure of the T_μ -strategy that results from the unification of two T_μ -strategies to the structure of the (fixed-point free) T_μ -strategy that results from the unification of their related unfolding, and we illustrated the idea in Fig. 2 for a simple case, and in Fig. 3 for the general case. Now we formalize this idea that relates a T_μ -strategy in \mathcal{C} to a fixed-point free one in \mathcal{C}_0 in terms of $(\mathcal{C}, \mathcal{C}_0)$ -simulation defined next.

Definition 80 ($(\mathcal{C}, \mathcal{C}_0)$ -simulation). For any T_μ -strategy S in \mathcal{C} and any fixed-point free T_μ -strategy R in \mathcal{C}_0 , a $(\mathcal{C}, \mathcal{C}_0)$ -simulation is a binary relation \mathfrak{R} between the sets of augmented sub- T_μ -strategies of S and of sub- T_μ -strategies of R , i.e.

$$\mathfrak{R} \subseteq \tilde{\Phi}(S) \times \Phi(R),$$

inductively defined from $S \mathfrak{R} R$ that fulfills the inference rules of Table 1.

Notice that if there is a $(\mathcal{C}, \mathcal{C}_0)$ -simulation between two T_μ -strategies, then it is unique, i.e. if $S \mathfrak{R}_1 R$ and $S \mathfrak{R}_2 R$, for two $(\mathcal{C}, \mathcal{C}_0)$ -simulations \mathfrak{R}_1 and \mathfrak{R}_2 , then $\mathfrak{R}_1 = \mathfrak{R}_2$.

Example 81. Let $S(X)$ be a fixed-point free T_μ -strategy. Then, for any $n \geq 0$, there is a $(\mathcal{C}, \mathcal{C}_0)$ -simulation between $\mu X.S(X)$ and $\mu^n X.S(X)$, since $\mu^n X.S(X)$ is nothing but the n -times iteration $S(S(\dots S(f)))$.

The following claims are not hard to prove.

Remark 82. For any T_μ -strategy S with bound fixed-variables X_1, \dots, X_s with $s \geq 0$, any iteration mapping $\mathbf{s} : \{X_1, \dots, X_s\} \rightarrow \mathbb{N}$, and any T_μ -strategy $M(Y)$, the following holds.

1. There is a $(\mathcal{C}, \mathcal{C}_0)$ -simulation between S and $\rho_{\mathbf{s}}(S)$.
2. If there is a $(\mathcal{C}, \mathcal{C}_0)$ -simulation \mathfrak{R} between S and S' , then there is a $(\mathcal{C}, \mathcal{C}_0)$ -simulation \mathfrak{R}' between $M(S)$ and $M(S')$ for any fixed-point free T_μ -strategy $M(Y)$. That is, the following diagram commutes.

$$\begin{array}{ccc} \mathcal{C} & \xrightarrow{M(\cdot)} & \mathcal{C} \\ \mathfrak{R} \downarrow & & \downarrow \mathfrak{R}' \\ \mathcal{C}_0 & \xrightarrow{M(\cdot)} & \mathcal{C}_0 \end{array}$$

3. If there is a $(\mathcal{C}, \mathcal{C}_0)$ -simulation \mathfrak{R} between S and S' and if \tilde{S} results from S by Simplifications (32), denoted hereby \mathcal{O} , that transform a T_μ -strategy into an equivalent T_μ -strategy in which each fixed-point variable occurs once, then there is a $(\mathcal{C}, \mathcal{C}_0)$ -simulation $\tilde{\mathfrak{R}}$ between \tilde{S} and S' as well. That is, the following diagram commutes.

$$\begin{array}{ccc} \mathcal{C} & \xrightarrow{\mathcal{O}} & \mathcal{C} \\ \mathfrak{R} \searrow & & \downarrow \tilde{\mathfrak{R}} \\ & & \mathcal{C}_0 \end{array}$$

We next define a weaker relation of $(\mathcal{C}, \mathcal{C}_0)$ -simulation by relaxing the constraint imposed by the fixed-point rule that unravels $\mu X.S(X)$ into $S(\mu X.S(X))$. The motivation is that in the upcoming proofs, rather than proving the existence of a $(\mathcal{C}, \mathcal{C}_0)$ -simulation, it is much easier and less cumbersome to proceed in two steps by firstly constructing the weaker relation and then strengthening it by deducing its properties.

Table 2
Inference rules for $(\mathcal{C}, \mathcal{C}_0)$ -quasi-simulation.

$\frac{S' = R'}{S' \mathfrak{S} R'} \quad S', R' \in \mathcal{C}_0$			$\frac{S_i \mathfrak{S} R_i}{S'(S_1, \dots, S_m) \mathfrak{S} S'(R_1, \dots, R_m)} \quad S'(X_1, \dots, X_m) \in \mathcal{C}_0$		
$\frac{}{\mu X.S'(X) \mathfrak{S} f}$			$\frac{S'(X) \mathfrak{S} R'}{\mu X.S'(X) \mathfrak{S} R'}$		
			$\frac{}{X \mathfrak{S} R'} \quad X \in \mathcal{Z}$		

Definition 83 ($(\mathcal{C}, \mathcal{C}_0)$ -quasi-simulation). For any T_μ -strategy S in \mathcal{C} and any fixed-point free T_μ -strategy R in \mathcal{C}_0 , a $(\mathcal{C}, \mathcal{C}_0)$ -quasi-simulation is a binary relation \mathfrak{S} between sub- T_μ -strategies of S and of R , i.e.

$$\mathfrak{S} \subseteq \Phi(S) \times \Phi(R),$$

inductively defined from $S \mathfrak{S} R$ that fulfills the inference rules of Table 2 which are the same as the inference rules of Table 1 apart for the fixed-point rule which is replaced by new two rules.

Notice that $(\mathcal{C}, \mathcal{C}_0)$ -quasi-simulation is strictly weaker than the $(\mathcal{C}, \mathcal{C}_0)$ -simulation in the sense that if there is a $(\mathcal{C}, \mathcal{C}_0)$ -simulation between S and R then there is a $(\mathcal{C}, \mathcal{C}_0)$ -quasi-simulation between S and R as well, while the opposite does not hold in general. This is due to the fact that the $(\mathcal{C}, \mathcal{C}_0)$ -simulation imposes that $\mu X.S(X)$ and X must correspond to the “same” T_μ -strategy in R , while the $(\mathcal{C}, \mathcal{C}_0)$ -quasi-simulation does not impose that. For instance, there is a $(\mathcal{C}, \mathcal{C}_0)$ -quasi-simulation between $\mu X.S(X)$ and $S(S')$ whatever maybe S' since $X \mathfrak{S} S'$, while it is not the case that there is in general a $(\mathcal{C}, \mathcal{C}_0)$ -simulation between $\mu X.S(X)$ and $S(S')$ unless further constraints are imposed on S' . Hence Remark 82 holds for $(\mathcal{C}, \mathcal{C}_0)$ -quasi-simulations as well.

A $(\mathcal{C}, \mathcal{C}_0)$ -quasi-simulation \mathfrak{S} between S and R induces two mappings, the first one that maps each fixed-point T_μ -strategy of S to a sub- T_μ -strategy of R , and the second one that maps each bound variable of S to a sub- T_μ -strategy of R as well.

Definition 84. For any $(\mathcal{C}, \mathcal{C}_0)$ -quasi-simulation relation \mathfrak{S} between S and R , with $S \in \mathcal{C}$ and $R \in \mathcal{C}_0$, define the mappings

$$\phi_\mu : \Phi_\mu(S) \cup \text{Bound}(S) \rightarrow \Phi(R) \quad \text{and} \quad \phi_v^\mu : \text{Bound}(S) \rightarrow \Phi(R)$$

as:

- $\phi_\mu(S')$, for any S' , being the unique $R' \in \Phi(R)$ such that $S' \mathfrak{S} R'$, and
- $\phi_v^\mu(X)$, for any X , being $\phi_\mu(\mu X.T(X))$ where $\mu X.T(X)$ is the (unique) fixed-point T_μ -strategy related to X .

Besides, the mapping ϕ_v^μ extends uniquely to an endomorphism $\widehat{\phi}_v^\mu : \mathcal{C} \rightarrow \mathcal{C}$ defined for any T_μ -strategy by:

$$\widehat{\phi}_v^\mu(T(T_1, \dots, T_m)) = T(\widehat{\phi}_v^\mu(T_1), \dots, \widehat{\phi}_v^\mu(T_m)) \quad \text{and} \quad \widehat{\phi}_v^\mu(Z) = \phi_v^\mu(Z).$$

Notice that it follows from Definition 80 that any $(\mathcal{C}, \mathcal{C}_0)$ -simulation from S to R is not defined for the bound fixed-point variables of S since any fixed-point sub- T_μ -strategy $\mu X.S'(X)$ of S is unraveled to $S'(\mu X.S'(X))$ and hence X is never reached.

Example 85 (The mappings ϕ_μ and ϕ_v^μ). Let $S(X)$ and $M(Y)$ be fixed-point free T_μ -strategies. Then there is a $(\mathcal{C}, \mathcal{C}_0)$ -simulation \mathfrak{R} and a $(\mathcal{C}, \mathcal{C}_0)$ -quasi-simulation \mathfrak{S} between $M(\mu X.S(X))$ and $M(\mu^3 X.S(X))$ and we have that:

$$\begin{aligned} \mathfrak{R} &= \{(\mu X.S(X), \mu^3 X.S(X)), (\mu X.S(X), \mu^2 X.S(X)), (\mu X.S(X), \mu^1 X.S(X)), (\mu X.S(X), f)\} \\ \mathfrak{S} &= \{(\mu X.S(X), \mu^3 X.S(X)), (X, \mu^2 X.S(X))\} \end{aligned}$$

And therefore,

$$\begin{aligned} \phi_\mu(\mu X.S(X)) &= \mu^3 X.S(X) = S(S(f)) \\ \phi_\mu(X) &= \mu^2 X.S(X) = S(S(f)) \\ \phi_v^\mu(X) &= \phi_\mu(\mu X.S(X)) = \mu^3 X.S(X) \end{aligned}$$

Remark 86. Notice that if $T(Z_1, \dots, Z_m)$ is a fixed-point free T_μ -strategy in which Z_1, \dots, Z_m are free fixed-point variables, and if $T_1 \dots T_m$ are T_μ -strategies where each of T_i is either fixed-point T_μ -strategy or a fixed-point variable, then it follows from Definition 84 together with Definition 83 of (C, C_0) -quasi-simulations that

$$\phi_\mu(\mu Z.T(T_1, \dots, T_m)) = T(\phi_\mu(T_1), \dots, \phi_\mu(T_m)).$$

11.4. Relating the structure of the unification of two T_μ -strategies with that of their unfolding

The purpose of this section is to relate the structure of the unification of two T_μ -strategies with that of their unfolding as illustrated in Section 7 in Fig. 2 for a simple case, and in Fig. 3 for the general case. More precisely, we show in the following Lemma 87 that the unification commutes with the unfolding in the following sense: there is a (C, C_0) -quasi-simulation between the T_μ -strategy that results from the unification of two T_μ -strategies and the fixed-point free T_μ -strategy that results from the unification of their related unfolding.

We illustrate with a simple unification example how this (C, C_0) -quasi-simulation is constructed, and thus how the two structures in Fig. 2 are obtained. Let $M(Y)$, $S(X)$ and R be fixed-point T_μ -strategies, and consider, on one hand, the unification of $M(\mu X.S(X))$ with R , and on the other hand, the unification of the unfolding of $M(\mu X.S(X))$ with the unfolding of R , which is R , since R is fixed-point free. We explain how these two unifications are related. During the unification process that starts from $\langle M(\mu X.S(X)), R, \emptyset \rangle$ on one side, and from $\langle M(\mu^n X.S(X)), R, \emptyset \rangle$, where $n \geq 1$, on the other, we distinguish many cases.

- (I) As far as we have $\langle M'(\mu^n X.S(X)), R', \emptyset \rangle$ on one side, and $\langle M'(\mu X.S(X)), R', \emptyset \rangle$ on the other, where M' (resp. R') is a sub- T_μ -strategy of M (resp. R), the constructed T_μ -strategy is the same on both sides, it is T_0 in Fig. 2.
- (II) If the derivation reaches a fixed-point T_μ -strategy, that is, it reaches $\langle \mu X.S(X), R'', \emptyset \rangle$ on the left side, and $\langle \mu^n X.S(X), R'', \emptyset \rangle$ on the right one, where R'' is a sub- T_μ -strategy of R , then the left derivation produces $\mu Z_1.\langle S(\mu X.S(X)), R'', \cdot \rangle$ and continues from $\langle S(\mu X.S(X)), R'', \cdot \rangle$, while the right one continues from $\langle S(\mu^{n-1} X.S(X)), R'', \emptyset \rangle$. This goes back to case (I), in which we take $M'(\cdot) = S(\cdot)$, and in which the left derivation will produce $\mu Z_1.T_1(\dots)$, while the right one will produce $T_1(\dots)$. During the generation of $T_1(\dots)$ two cases can happen:
 - (a) If the left derivation reaches $\langle \mu X.S(X), R'', \cdot \rangle$, then the right derivation reaches $\langle \mu^{n-1} X.S(X), R'', \emptyset \rangle$. The left derivation continues and produces the fixed-point Z_1 generated at the end of case (II), while the right derivation produces the T_μ -strategy T_1^1 depicted on the right of Fig. 2.
 - (b) If the left derivation reaches $\langle \mu X.S(X), R_2, \cdot \rangle$ with $R_2 \neq R''$, then the right derivation reaches $\langle \mu^{n-1} X.S(X), R_2, \emptyset \rangle$. Thus the left derivation produces the fixed-point T_μ -strategy $\mu Z_2.\langle S(\mu X.S(X)), R_2, \cdot \rangle$ and continues from $\langle S(\mu X.S(X)), R_2, \cdot \rangle$ (see left of Fig. 2), while the right derivation continues from $\langle \mu^{n-1} X.S(X), R_2, \emptyset \rangle$, see right of Fig. 2. This goes back to case (I).

In the following Lemma 87 we construct a (C, C_0) -quasi-simulation between the unification of any two T_μ -strategies and the unification of their any unfolding.

Lemma 87. Let S and R be T_μ -strategies with bound fixed-point variables $\text{Bound}(S) = \{X_1, \dots, X_s\}$ and $\text{Bound}(R) = \{Y_1, \dots, Y_r\}$. Let $\mathcal{M} \in \mathfrak{M}(S, R)$ be a memory with respect to S and R . Let $\mathbf{s} : \{X_1, \dots, X_s\} \rightarrow \mathbb{N}$ and $\mathbf{r} : \{Y_1, \dots, Y_r\} \rightarrow \mathbb{N}$ be iteration mappings. There is a (C, C_0) -quasi-simulation \mathfrak{S} between $\mathcal{NF}(\langle S, R, \mathcal{M} \rangle)$ and $\mathcal{NF}(\langle \rho_S(S), \rho_R(R), \emptyset \rangle)$. In particular, the following diagram commutes.

$$\begin{array}{ccc} C \times C & \xrightarrow{\lambda} & C \\ \rho_S(\cdot) \times \rho_R(\cdot) \downarrow & & \downarrow \mathfrak{S} \\ C_0 \times C_0 & \xrightarrow{\lambda} & C_0 \end{array}$$

It turned out that the (C, C_0) -quasi-simulation of 87 is actually a (C, C_0) -simulation, but we can not prove it now in this section, because it requires the further developments of the next section 12, and there we shall be ready to prove it in Corollary 98.

Now we can state and prove in Lemma 88 useful properties of the (C, C_0) -quasi-simulation constructed in the proof of the previous Lemma 87. Roughly speaking, we need to distinguish in the resulting T_μ -strategy $S \lambda R$ between two kinds of fixed-point T_μ -strategies:

- (i.) a fixed-point T_μ -strategy $\mu Z.T(Z)$, where Z is fresh, that is generated by the fixed-point rules (8a) and (8b) of the unification reduction system given in Definition 33, and
- (ii.) a fixed-point T_μ -strategy $\mu X'.S'(X')$ that is a sub- T_μ -strategy of S or R .

In the first case, the fixed-point T_μ -strategy $\mu Z.T(Z)$ is related by the (C, C_0) -quasi-simulation to the unification of an iteration (over a fixed-point T_μ -strategy) with a T_μ -strategy, or symmetrically, to the unification of a T_μ -strategy with an

iteration (over a fixed-point T_μ -strategy). However, in the second case, the fixed-point T_μ -strategy $\mu X.S(X)$ is related by the (C, C_0) -quasi-simulation to its unfolding. Formally,

Lemma 88. Let S and R be T_μ -strategies with bound fixed-point variables $\text{Bound}(S) = \{X_1, \dots, X_s\}$ and $\text{Bound}(R) = \{Y_1, \dots, Y_r\}$. Let $\mathbf{s} : \{X_1, \dots, X_s\} \rightarrow \mathbb{N}$ and $\mathbf{r} : \{Y_1, \dots, Y_r\} \rightarrow \mathbb{N}$ be iteration mappings. The (C, C_0) -quasi-simulation \mathfrak{S} between $S \wedge R$ and $\rho_S(S) \wedge \rho_R(R)$ constructed in the proof of Lemma 87 has the following property.

For any sub- T_μ -strategy T in $S \wedge R$ that is either a fixed-point or a bound variable, i.e.

$$T \in \Phi_\mu(S \wedge R) \cup \text{Bound}(S \wedge R),$$

there exist T_μ -strategies $\mu X'.S'(X')$ and R' , iteration mappings $\mathbf{s}' : \{X_1, \dots, X_s\} \rightarrow \mathbb{N}$ and $\mathbf{r}' : \{Y_1, \dots, Y_r\} \rightarrow \mathbb{N}$ and a memory \mathcal{M}' such that one of the four following case holds:

(a)

$$T = \mathcal{NF}(\langle \mu X'.S'(X'), R', \mathcal{M}' \rangle) \quad \text{and} \quad T \mathfrak{S} (\rho_{\mathbf{s}'}(\mu X'.S'(X')) \wedge \rho_{\mathbf{r}'}(R'))$$

and in this case $\mu X'.S'(X') \in \tilde{\Phi}_\mu(S)$ and $R' \in \tilde{\Phi}(R)$.

(b)

$$T = \mathcal{NF}(\langle R', \mu X'.S'(X'), \mathcal{M}' \rangle) \quad \text{and} \quad T \mathfrak{S} (\rho_{\mathbf{r}'}(R') \wedge \rho_{\mathbf{s}'}(\mu X'.S'(X')))$$

and in this case $R' \in \tilde{\Phi}_\mu(S)$ and $\mu X'.S'(X') \in \tilde{\Phi}(R)$.

(c)

$$T = \mu X'.S'(X') \quad \text{and} \quad T \mathfrak{S} \rho_{\mathbf{s}'}(\mu X'.S'(X'))$$

with $\mu X'.S'(X') \in \tilde{\Phi}_\mu(S)$ and $X' \in \{X_1, \dots, X_s\}$.

(d)

$$T = \mu X'.S'(X') \quad \text{and} \quad T \mathfrak{S} \rho_{\mathbf{r}'}(\mu X'.S'(X'))$$

with $\mu X'.S'(X') \in \tilde{\Phi}_\mu(R)$ and $X' \in \{Y_1, \dots, Y_r\}$.

Proof. Item (a) follows immediately from the case (3) of the proof of Lemma 87 since any fixed-point T_μ -strategy $\mu Z.T(Z)$ and any fixed-point variable Z in the resulting T_μ -strategy $S \wedge R$ results from the unification of a fixed-point T_μ -strategy with an arbitrary T_μ -strategy such that $\mu Z.T(Z)$ and Z is related by the (C, C_0) -quasi-simulation \mathfrak{S} to a unification of two T_μ -strategies where the *left* one is an iteration over a fixed-point T_μ -strategy (i.e. $\rho(\mu X'.S'(X), \mathbf{s})$).

Item (b) follows from the symmetric case of case (3) of the proof of Lemma 87 which we omitted and in which any fixed-point T_μ -strategy $\mu Z.T(Z)$ and any fixed-point variable Z in the resulting T_μ -strategy $S \wedge R$ results from the unification of an arbitrary T_μ -strategy with a fixed-point T_μ -strategy such that $\mu Z.T(Z)$ and Z would be related by the (C, C_0) -quasi-simulation \mathfrak{S} to a unification of two T_μ -strategies where the *right* one is an iteration over a fixed-point T_μ -strategy.

Items (c) and (d) follow from the case (3) of the proof of Lemma (87) together with the explicit computations made in the composition Lemma 73, with properties (9) and (10), in which we take one of the ξ_1, \dots, ξ_k or one of the ζ_1, \dots, ζ_l as fixed-point T_μ -strategy, and by taking one of the T_1, \dots, T_m as a fixed-point T_μ -strategy that is either ξ_i or ζ_j , for some $i \in \{1, \dots, k\}$ and some $j \in \{1, \dots, l\}$. \square

In the following example we illustrate the cases (a) and (c) of Lemma 88, we omit the cases (b) and (d) since they are respectively symmetrical to the two former ones.

Example 89. Let $\xi_1, \xi_2, \xi_3, R_1, R_2, R_3$ be T_μ -strategies such that R_1, R_2, R_3 are fixed-point free, and ξ_1, ξ_2, ξ_3 are fixed-point T_μ -strategies of the form

$$\xi_1 = \mu X_1.S_1(X_1), \quad \xi_2 = \mu X_2.S_2(X_2), \quad \xi_3 = \mu X_3.S_3(X_3),$$

where ξ_3 is a sub- T_μ -strategy of ξ_2 which is a sub- T_μ -strategy of ξ_1 . Consider the following iteration mappings in which $n \geq 1$:

$$\mathbf{s}_1 = \{X_1 \mapsto n, X_2 \mapsto n, X_3 \mapsto n\}, \quad \mathbf{s}_2 = \{X_1 \mapsto n-1, X_2 \mapsto n, X_3 \mapsto n\}, \quad \mathbf{s}_3 = \{X_1 \mapsto n-1, X_2 \mapsto n-1, X_3 \mapsto n\}.$$

Since R_1, R_2, R_3 are fixed-point free, then they are equal to their unfoldings. We next consider the two unifications $\xi_1 \wedge R_1$ and $\rho_{\mathbf{s}_1}(\xi_1) \wedge R_1$ that result respectively from the following two derivations, in which we omit the explicit expression of the T_μ -strategies T_1 and of T_2 , where \mathcal{M}_2 and \mathcal{M}_3 are memories:

$$\langle \xi_1, R_1, \emptyset \rangle \xrightarrow{*} \mu Z_1.T_1(\xi_1, \langle \xi_2, R_2, \mathcal{M}_2 \rangle) \xrightarrow{*} \mu Z_1.T_1(\xi_1, \mu Z_2.T_2(\langle \xi_3, R_3, \mathcal{M}_3 \rangle)), \quad (16)$$

$$\langle \rho_{s_1}(\xi_1), R_1, \emptyset \rangle \xrightarrow{*} T_1(\rho_{s_2}(\xi_1), \langle \rho_{s_2}(\xi_2), R_2, \emptyset \rangle) \xrightarrow{*} T_1(\rho_{s_2}(\xi_1), T_2(\langle \rho_{s_3}(\xi_3), R_3, \emptyset \rangle)). \quad (17)$$

If we assume, for the sake of simplicity, that the normal form of $\langle \xi_3, R_3, \mathcal{M}_3 \rangle$ in the derivation (16) produces just one fixed-point T_μ -strategy, then the set of fixed-point sub- T_μ -strategies of $\xi_1 \wedge R_1$ is:

$$\Phi_\mu(\xi_1 \wedge R_1) = \{\xi_1, \underbrace{\mathcal{NF}(\langle \xi_1, R_1, \emptyset \rangle)}_{T_1}, \underbrace{\mathcal{NF}(\langle \xi_2, R_2, \mathcal{M}_2 \rangle)}_{T_2}, \underbrace{\mathcal{NF}(\langle \xi_3, R_3, \mathcal{M}_3 \rangle)}_{T_3}\}.$$

Recall that, from Definition 34 of unification, we have

$$\mathcal{NF}(\langle \rho_{s_2}(\xi_2), R_2, \emptyset \rangle) = \rho_{s_2}(\xi_2) \wedge R_2 \quad \text{and} \quad \mathcal{NF}(\langle \rho_{s_3}(\xi_3), R_3, \emptyset \rangle) = \rho_{s_3}(\xi_3) \wedge R_3.$$

Therefore, the cases (a) and (c) of Lemma 88 are as follows:

$$T_1 \mathfrak{S} (\rho_{s_1}(\xi_1) \wedge R_1) \quad \text{and} \quad T_2 \mathfrak{S} (\rho_{s_2}(\xi_2) \wedge R_2) \quad \text{and} \quad T_3 \mathfrak{S} (\rho_{s_3}(\xi_3) \wedge R_3) \quad (\text{Case (a) of Lemma 88})$$

$$\xi_1 \mathfrak{S} \rho_{s_2}(\xi_1). \quad (\text{Case (c) of Lemma 88})$$

We recall that a T_μ -strategy that results from a unification $S \wedge R$ may contain useless fixed-point constructor of the form $\mu Z.T$ where Z does not appear in T , or it may contain a fixed-point variable that appears many times. We noticed in Item 3 of Remark 82 that Simplifications (32) preserve the relation of $(\mathcal{C}, \mathcal{C}_0)$ -simulation and therefore the $(\mathcal{C}, \mathcal{C}_0)$ -quasi-simulation. Hence we can assume from now on that the T_μ -strategies that result from the unification follow Assumptions 31. It is simpler for later development, to lift the properties of the relation $(\mathcal{C}, \mathcal{C}_0)$ -quasi-simulation of Lemma 88 to its induced mapping ϕ_μ . This will be done in Lemma 90 together with a simple and useful property on the image by ϕ_μ of fixed-points T_μ -strategies in $S \wedge R$. Roughly speaking, this property states that if \mathbf{T} and \mathbf{T}' are fixed-point T_μ -strategies in $S \wedge R$ where \mathbf{T}' is an immediate sub- T_μ -strategy of \mathbf{T} , then the number of iterations over a certain fixed-point T_μ -strategy decreases by one from $\phi_\mu(\mathbf{T})$ to $\phi_\mu(\mathbf{T}')$.

Lemma 90. Let S and R be T_μ -strategies with bound fixed-point variables $\text{Bound}(S) = \{X_1, \dots, X_s\}$ and $\text{Bound}(R) = \{Y_1, \dots, Y_r\}$. Let $\mathbf{s} : \{X_1, \dots, X_s\} \rightarrow \mathbb{N}$ and $\mathbf{r} : \{Y_1, \dots, Y_r\} \rightarrow \mathbb{N}$ be iteration mappings. Let ϕ_μ be the mapping induced by the $(\mathcal{C}, \mathcal{C}_0)$ -quasi-simulation \mathfrak{S} between $S \wedge R$ and $\rho_{\mathbf{s}}(S) \wedge \rho_{\mathbf{r}}(R)$ constructed in the proof of Lemma 87. The mapping ϕ_μ enjoys the following properties.

- For any fixed-point T_μ -strategy \mathbf{T} in $S \wedge R$, there exist T_μ -strategies $\mu X'.S'(X')$ and R' , mappings $\mathbf{s}' : \{X_1, \dots, X_s\} \rightarrow \mathbb{N}$ and $\mathbf{r}' : \{Y_1, \dots, Y_r\} \rightarrow \mathbb{N}$, and a memory \mathcal{M}' such that one of the four following cases holds.
 - $\mathbf{T} = \mathcal{NF}(\langle \mu X'.S'(X'), R', \mathcal{M}' \rangle)$ and $\phi_\mu(\mathbf{T}) = (\rho_{\mathbf{s}'}(\mu X'.S'(X')) \wedge \rho_{\mathbf{r}'}(R'))$.
 - $\mathbf{T} = \mathcal{NF}(\langle R', \mu X'.S'(X'), \mathcal{M}' \rangle)$ and $\phi_\mu(\mathbf{T}) = (\rho_{\mathbf{r}'}(R') \wedge \rho_{\mathbf{s}'}(\mu X'.S'(X')))$.
 - $\mathbf{T} = \mu X'.S'(X')$, with $X' \in \{X_1, \dots, X_s\}$ and $\mu X'.S'(X') \in \Phi_\mu(S)$, and $\phi_\mu(\mathbf{T}) = \rho_{\mathbf{s}'}(\mu X'.S'(X'))$.
 - $\mathbf{T} = \mu X'.S'(X')$, with $X' \in \{Y_1, \dots, Y_r\}$ and $\mu X'.S'(X') \in \Phi_\mu(R)$, and $\phi_\mu(\mathbf{T}) = \rho_{\mathbf{r}'}(\mu X'.S'(X'))$.
- For any fixed-point sequence

$$T_1 \sqsupset \dots \sqsupset T_m$$

in $\mathcal{T}(S \wedge R)$ with $m \geq 1$ and for any $i = 1, \dots, m$, there are iteration mappings $\mathbf{s}_i : \{X_1, \dots, X_s\} \rightarrow \mathbb{N}$ and $\mathbf{r}_i : \{Y_1, \dots, Y_r\} \rightarrow \mathbb{N}$, such that one of the following two cases holds:

- There is a T_μ -strategy $S_i(X^i) \in \Phi(S)$ with $X^i \in \{X_1, \dots, X_s\}$, and a T_μ -strategy $R_i \in \Phi(R)$ such that

$$\phi_\mu(\mathbf{T}_i) = \rho_{\mathbf{s}_i}(\mu X^i.S_i(X^i)) \wedge \rho_{\mathbf{r}_i}(R_i),$$

and for $i = 1, \dots, m-1$ and for any $X \in \{X_1, \dots, X_s\}$ and any $Y \in \{Y_1, \dots, Y_r\}$, we have that

$$\mathbf{s}_{i+1}(X) = \begin{cases} \mathbf{s}_i(X), & \text{if } X \neq X^i \\ \mathbf{s}_i(X^i) - 1, & \text{if } X = X^i \end{cases} \quad \text{and} \quad \mathbf{r}_{i+1}(Y) = \mathbf{r}_i(Y) \quad (18)$$

- There is a T_μ -strategy $S_i \in \Phi(S)$, and a T_μ -strategy $R_i(Y^i) \in \Phi(R)$ with $Y^i \in \{Y_1, \dots, Y_r\}$, such that

$$\phi_\mu(\mathbf{T}_i) = \rho_{\mathbf{s}_i}(S_i) \wedge \rho_{\mathbf{r}_i}(\mu Y^i.R_i(Y^i)),$$

and for $i = 1, \dots, m-1$ and for any $X \in \{X_1, \dots, X_s\}$ and any $Y \in \{Y_1, \dots, Y_r\}$, we have that

$$\mathbf{s}_{i+1}(X) = \mathbf{s}_i(X) \quad \text{and} \quad \mathbf{r}_{i+1}(Y) = \begin{cases} \mathbf{r}_i(Y), & \text{if } Y \neq Y^i \\ \mathbf{r}_i(Y^i) - 1, & \text{if } Y = Y^i \end{cases} \quad (19)$$

Example 91. We consider the two unifications $\xi_1 \wedge R_1$ and $\rho_{s_1}(\xi_1) \wedge R_1$ of Example 89, as well as their related derivations (16) and (17).

1. The cases (1a) and (1c) of Lemma 90 correspond to the following equalities:

$$\phi_\mu(\mathbf{T}_1) = (\rho_{s_1}(\xi_1) \wedge R_1) \quad \text{and} \quad \phi_\mu(\mathbf{T}_2) = (\rho_{s_2}(\xi_2) \wedge R_2) \quad \text{and} \quad \phi_\mu(\mathbf{T}_3) = (\rho_{s_3}(\xi_3) \wedge R_3) \\ \text{(Case (1a) of Lemma 90)}$$

$$\phi_\mu(\xi_1) = \rho_{s_2}(\xi_1). \quad \text{(Case (1c) of Lemma 90)}$$

2. Notice that from the derivation (16) of Example 89, we have that \mathbf{T}_3 is a (fixed-point) sub- \mathbf{T}_μ -strategy of \mathbf{T}_2 , which is a (fixed-point) sub- \mathbf{T}_μ -strategy of \mathbf{T}_1 . Thus we have the fixed-point sequence

$$\mathbf{T}_1 \supset \mathbf{T}_2 \supset \mathbf{T}_3$$

in $\mathcal{T}(\xi_1 \wedge R_1)$. Recall that the iteration mappings s_1 , s_2 and s_3 were defined in Example 89 as:

$$s_1 = \{X_1 \mapsto n, X_2 \mapsto n, X_3 \mapsto n\}, \quad s_2 = \{X_1 \mapsto n-1, X_2 \mapsto n, X_3 \mapsto n\},$$

$$s_3 = \{X_1 \mapsto n-1, X_2 \mapsto n-1, X_3 \mapsto n\}.$$

Therefore, Eq. (18) of the case (2a) of Lemma 90 expresses s_2 in terms of s_1 , as well as s_3 in terms of s_2 as follows:

$$s_2(X) = \begin{cases} s_1(X), & \text{if } X \neq X_1 \\ s_1(X_1) - 1, & \text{if } X = X_1 \end{cases} \quad \text{and} \quad s_3(X) = \begin{cases} s_2(X), & \text{if } X \neq X_2 \\ s_2(X_2) - 1, & \text{if } X = X_2, \end{cases}$$

where $X \in \{X_1, X_2, X_3\}$.

12. The equivalence between the unification of two \mathbf{T}_μ -strategies and that of their unfoldings

This is the most technical section in which we develop the last ingredient required in the proof of the main result of this paper. The purpose of this section is to show that the unification of two \mathbf{T}_μ -strategies is equivalent to the unification of their unfolding for any term of depth at most a certain bound that depends on the two unfoldings, i.e. Proposition 105. More precisely, we shall prove that for any two iteration mappings s and r with $s(X_i) = r(Y_j) = n$, the \mathbf{T}_μ -strategies $S \wedge R$ and $\rho_s(S) \wedge \rho_r(R)$ are equivalent for any term of depth at most n , where X_i (resp. Y_j) are the bound variables of S (resp. R).

To achieve this we need, on the one hand, the main result of Subsection 11.4 that ensures the existence of a $(\mathcal{C}, \mathcal{C}_0)$ -quasi-simulation between $S \wedge R$ and $\rho_s(S) \wedge \rho_r(R)$ (Lemma 87), together with the properties of this relation (Lemma 90). Indeed such results guarantee that $S \wedge R$ and $\rho_s(S) \wedge \rho_r(R)$ have almost the same structure and should be equivalent. However, on the other hand, the structure of $S \wedge R$ differs from that of $\rho_s(S) \wedge \rho_r(R)$ when it comes to certain sub- \mathbf{T}_μ -strategies. Therefore, to complete the proof we need to show that any such sub- \mathbf{T}_μ -strategy of $S \wedge R$ is equivalent to its related sub- \mathbf{T}_μ -strategy of $\rho_s(S) \wedge \rho_r(R)$ with respect to any term of a certain depth that depends on the position of such distinct sub- \mathbf{T}_μ -strategy in $S \wedge R$, or equivalently in $\rho_s(S) \wedge \rho_r(R)$.

To illustrate the idea, we consider the simplest case where $S \wedge R = \mu Z. T(Z)$ such that $T(Z)$ is fixed-point free. Let $\mathbf{E} = \rho_s(S) \wedge \rho_r(R)$. Therefore, thanks to the $(\mathcal{C}, \mathcal{C}_0)$ -quasi-simulation and its properties, we know that $\mathbf{E} = T(\mathbf{E}')$, where $\mathbf{E}' = \rho_{s'}(S) \wedge \rho_{r'}(R)$, for iteration mappings s' and r' . Hence to show that $\mu Z. T(Z)$ is n -equivalent to \mathbf{E} , it suffices to show that \mathbf{E} is a fixed-point of $T(Z)$, i.e. that $T(\mathbf{E}) \equiv_n \mathbf{E}$. But since $\mathbf{E} = T(\mathbf{E}')$, we need to show that $T(\mathbf{E})$ is n -equivalent to $T(\mathbf{E}')$. To achieve this, it suffices to show that \mathbf{E} is n' -equivalent to \mathbf{E}' for some n' provided that the number of jumps between the root of $T(Z)$ and Z is at least $n - n'$. That is, $\rho_s(S) \wedge \rho_r(R)$ and $\rho_{s'}(S) \wedge \rho_{r'}(R)$ are n' -equivalent where n' depends on the iteration mappings s, r, s' and r' . It turns out that in this simple case, n' is nothing but the codistance $D^*((s, r), (s', r'))$, and $n - D^*((s, r), (s', r'))$ is a lower bound for the number of jumps between the root of $T(Z)$ and Z .

However, for the general case where $S \wedge R$ contains many nested fixed-point \mathbf{T}_μ -strategies, say

$$S \wedge R = \mu Z_1. T_1(\mu Z_2. T_2(\cdots \mu Z_m. T_m(Z_m)))$$

which yields the fixed-point sequence $\mathcal{S} = \mu Z_1. T_1(Z_1) \supset \cdots \supset \mu Z_m. T_m(Z_m)$, many difficulties arise. Namely, the codistance D^* is no longer an exact lower bound to the number of jumps, say between the root of $T_i(Z_i)$ and $\mu Z_j. T_j(Z_j)$, where $1 \leq i < j \leq m$. However the same technique remains: to prove that $T(\mathbf{E}) \equiv_n T(\mathbf{E}')$ it is enough to show that $\mathbf{E} \equiv_{n'} \mathbf{E}'$, for some n' , provided that the number of jumps from the root of $T(\mathbf{E})$ to \mathbf{E} is at least $n - n'$. Besides, the same principle remains: the more we go deeper in the sequence \mathcal{S} , the more the iterations in the related \mathbf{T}_μ -strategies of \mathcal{S} (i.e. that result in $\rho_s(S) \wedge \rho_r(R)$ and have the form $\rho_{s_i}(S_i) \wedge \rho_{r_i}(R_i)$ for $i = 1, \dots, m$) decrease, and the more we get more jumps from the root of $T_1(Z_1)$ to $\mu Z_m. T_m(Z_m)$.

Having said that, we need to supplement the codistance D^* with further measures that will be introduced in Subsection 12.1 together with their properties. In Subsection 12.2 we shall show that these measures provide enough information

to compute an adequate lower bound for the number of jumps. More precisely, these measures will allow us to extract a subsequence from the fixed-point sequence \mathcal{S} , called the *derivative sequence*, with the property that there is at least one jump between any two successive T_μ -strategies in this Subsequence. Summing up these results we shall show in Subsection 12.3 that the unification of two T_μ -strategies, say $S \wedge R$, is n -equivalent to the unification of their unfolding, i.e. say $\rho_s(S) \wedge \rho_r(R)$, where the iteration mappings \mathbf{s} and \mathbf{r} associate to each fixed-point variable the constant n . We shall make use of the main result of Subsection 11.1 that allows to compare the equivalence of the unification of an unfolding of two T_μ -strategies with the unification of another unfolding of the same two T_μ -strategies.

12.1. Measures and codistance on fixed-point tree

We define next the number of occurrences of a T_μ -strategy in a sequence of tuples.

Definition 92. Let S and R be T_μ -strategies. Let \mathcal{S} be a sequence of tuples

$$\mathcal{S} = \langle S_1, R_1, \mathcal{M}_1 \rangle, \dots, \langle S_m, R_m, \mathcal{M}_m \rangle$$

with $m \geq 1$, $S_i \in \Phi(S)$ and $R_i \in \Phi(R)$ for $i = 1, \dots, m$. Let S' be a fixed-point sub- T_μ -strategy of S . We shall denote by $\#_{\mathcal{S}}(S')$ the number of occurrences of S' in the sequence \mathcal{S} , that is

$$\#_{\mathcal{S}}(S') = |\{S_i \mid S_i = S', i = 1, \dots, m\}|. \quad (20)$$

For a T_μ -strategy R' that is a fixed-point sub- T_μ -strategy of R , the definition of $\#_{\mathcal{S}}(R')$ is similar to $\#_{\mathcal{S}}(S')$ by taking R_i instead of S_i in Eq. (20).

We shall use the following notations throughout this Subsection and the next Subsection 12.2 as well. Let S (resp. R) be a T_μ -strategy with fixed-point variables X_1, \dots, X_s (resp. Y_1, \dots, Y_r). Let $n \geq 1$ and let $\mathbf{s} : \{X_1, \dots, X_s\} \rightarrow \mathbb{N}$ and $\mathbf{r} : \{Y_1, \dots, Y_r\} \rightarrow \mathbb{N}$ be iteration mappings with $\mathbf{s}(X_i) = \mathbf{s}(X_j) = n$. Let ϕ_μ be the mapping induced by the $(\mathcal{C}, \mathcal{C}_0)$ -quasi-simulation Θ between $S \wedge R$ and $\rho_s(S) \wedge \rho_r(R)$. Let \mathcal{T} be the fixed-point tree of $S \wedge R$. Recall that \mathcal{T} is not necessarily connected, i.e. it may be composed of many connected sub-trees and thus it may have many roots.

In the following Definition 94 we define three measures, one to count the maximal number of repetitions of T_μ -strategies in a sequence of tuples, a second one that is n minus the previous measure, and the third one that transfers the codistance D^* from $\rho_s(S) \wedge \rho_r(R)$ to the related T_μ -strategies that belong to the fixed-point tree \mathcal{T} .

Notations 93 (For Definition 94). In the following Definition 94 we let \mathcal{S} to be a left-maximal sequence

$$\mathbf{T}_1 \sqsupset \dots \sqsupset \mathbf{T}_m$$

in \mathcal{T} (i.e. \mathbf{T}_1 being a root of \mathcal{T}) with $m \geq 1$. According to Items (1a) and (1b) of Lemma 90, we know that for any $i = 1, \dots, m$, one of the following two cases holds.

- (i) $\mathbf{T}_i \in \tilde{\Phi}(S \wedge R) \setminus (\tilde{\Phi}(S) \cup \tilde{\Phi}(R))$ and hence it can be written as $\mathbf{T}_i = \mathcal{NF}(\langle S_i, R_i, \mathcal{M}_i \rangle)$ and in this case $\mathbf{T}_{i'} \in \tilde{\Phi}(S \wedge R) \setminus (\tilde{\Phi}(S) \cup \tilde{\Phi}(R))$ for $i' < i$.
- (ii) $\mathbf{T}_i \in \tilde{\Phi}(S) \cup \tilde{\Phi}(R)$ and in this case $i = m$ and $\mathbf{T}_m = S_m \in \tilde{\Phi}_\mu(S)$ or $\mathbf{T}_m = R_m \in \tilde{\Phi}_\mu(R)$.

This yields the finite sequence of tuples

$$\tilde{\mathcal{S}} = \langle S_1, R_1, \mathcal{M}_1 \rangle, \dots$$

that either ends with a tuple $\langle S_m, R_m, \mathcal{M}_m \rangle$ or a fixed-point T_μ -strategy $S_m \in \tilde{\Phi}_\mu(S)$ or a fixed-point T_μ -strategy $R_m \in \tilde{\Phi}_\mu(R)$. Besides, the mapping ϕ_μ associates to the sequence $\tilde{\mathcal{S}}$ the sequence

$$\phi_\mu(\mathbf{T}_1), \dots, \phi_\mu(\mathbf{T}_m)$$

in $\rho_s(S) \wedge \rho_r(R)$ which is

$$\rho_{\mathbf{s}_1}(S_1) \wedge \rho_{\mathbf{r}_1}(R_1), \dots$$

that ends with the T_μ -strategy $\rho_{\mathbf{s}_m}(S_m) \wedge \rho_{\mathbf{r}_m}(R_m)$ or $\rho_{\mathbf{s}_m}(S_m)$ or $\rho_{\mathbf{r}_m}(R_m)$, for iteration mappings \mathbf{s}_i and \mathbf{r}_i .

Definition 94 (Measures on T_μ -strategies of fixed-point tree). We define three measures.

1. We define $\Omega_S^\#(\mathbf{T}_i, \mathbf{T}_j)$, for $1 \leq i \leq j$, as the maximal number of occurrences of T_μ -strategies that appear in the series of tuples in \tilde{S} starting from the tuple related to \mathbf{T}_i and ending with the tuple related to \mathbf{T}_j . That is, if $\mathbf{T}_j \in \tilde{\Phi}(S \wedge R) \setminus (\tilde{\Phi}(S) \cup \tilde{\Phi}(R))$, then

$$\Omega_S^\#(\mathbf{T}_i, \mathbf{T}_j) = \max\{\#_S(S_p), \#_S(R_p) \mid S_p \in \tilde{\Phi}_\mu(S), R_p \in \tilde{\Phi}_\mu(R), p = i, \dots, j\}. \quad (21)$$

If $\mathbf{T}_j \in \tilde{\Phi}(S) \cup \tilde{\Phi}(R)$, then

$$\Omega_S^\#(\mathbf{T}_i, \mathbf{T}_j) = \begin{cases} 0 & \text{if } i = j \\ \Omega_S^\#(\mathbf{T}_i, \mathbf{T}_{j-1}) & \text{if } i > j. \end{cases} \quad (22)$$

2. For $i \in \{1, m\}$, define

$$\omega_S(\mathbf{T}_i) = n - \Omega_S^\#(\mathbf{T}_1, \mathbf{T}_i). \quad (23)$$

3. For $i \in \{1, m\}$, we define the *codistance* between \mathbf{T}_1 and \mathbf{T}_i as follows.

If $\mathbf{T}_i \in \tilde{\Phi}(S \wedge R) \setminus (\tilde{\Phi}(S) \cup \tilde{\Phi}(R))$, then

$$\mathbf{D}^*_S(\mathbf{T}_i) = \begin{cases} n & \text{if } i = 1 \\ D^*((s_1, r_1), (s_i, r_i)) & \text{if } i > 1. \end{cases} \quad (24)$$

If $\mathbf{T}_i \in \tilde{\Phi}(S) \cup \tilde{\Phi}(R)$, then

$$\mathbf{D}^*_S(\mathbf{T}_i) = \begin{cases} n & \text{if } i = 1 \\ \min\{\mathbf{D}^*(\mathbf{T}_{i-1}), d^*(s_1, s_i)\} & \text{if } i > 1. \end{cases} \quad (25)$$

When the sequence S is known and if there is no ambiguity we shall simplify the notations by omitting S and simply writing $\Omega^\#(\mathbf{T}_i, \mathbf{T}_j)$, $\omega(\mathbf{T}_i)$ and $\mathbf{D}^*(\mathbf{T}_i)$ instead of $\Omega_S^\#(\mathbf{T}_i, \mathbf{T}_j)$, $\omega_S(\mathbf{T}_i)$ and $\mathbf{D}^*_S(\mathbf{T}_i)$. These three measures are illustrated with the following example.

Example 95. Let ξ_1, ξ_2, ξ_3 be fixed-point T_μ -strategies, where $\xi_i = \mu X_i. S_i(X_i)$ for $i = 1, 2, 3$, such that ξ_3 is a sub- T_μ -strategy of ξ_2 which is a sub- T_μ -strategy of ξ_1 . Let R_1, \dots, R_6 be fixed-point free T_μ -strategies, and let $\mathcal{M}_1, \dots, \mathcal{M}_6$ be memories with $\mathcal{M}_1 = \emptyset$.

Firstly, we consider the unification $\xi_1 \wedge R_1$. We do not make explicit the derivation that starts from $\langle \xi_1, R_1, \mathcal{M}_1 \rangle$ because it has been detailed in the similar and simpler Example 89, see Eq. (16). We assume that the unification $\xi_1 \wedge R_1$ gives rise to the following sequence of tuples, in which ξ_1 occurs 3 times, ξ_2 occurs 2 times and ξ_3 occurs once:

$$\langle \xi_1, R_1, \mathcal{M}_1 \rangle, \langle \xi_2, R_2, \mathcal{M}_2 \rangle, \langle \xi_1, R_3, \mathcal{M}_3 \rangle, \langle \xi_3, R_4, \mathcal{M}_4 \rangle, \langle \xi_2, R_5, \mathcal{M}_5 \rangle, \langle \xi_1, R_6, \mathcal{M}_6 \rangle.$$

This yields the following (fixed-point) left-maximal sequence, denoted by \mathcal{S} :

$$\mathbf{T}_1 \sqsupset \mathbf{T}_2 \sqsupset \dots \sqsupset \mathbf{T}_6 \quad (26)$$

in $\mathcal{T}(\xi_1 \wedge R_1)$, where each \mathbf{T}_i is the normal form of the related triplet (i.e. $\mathbf{T}_i = \mathcal{NF}(\langle \xi_1, R_1, \mathcal{M}_1 \rangle)$, etc).

Secondly, we consider the unification of an unfolding of S_1 with an unfolding of R_1 . Recall that R_1 , as well as the other R_2, \dots, R_6 , are fixed-fixed point free, and therefore they are equal to their unfolding. Hence, we define the following iteration mappings in which $n \geq 1$:

$$\begin{aligned} \mathbf{s}_1 &= \{X_1 \mapsto n, X_2 \mapsto n, X_3 \mapsto n\}, & \mathbf{s}_2 &= \{X_1 \mapsto n-1, X_2 \mapsto n, X_3 \mapsto n\}, \\ \mathbf{s}_3 &= \{X_1 \mapsto n-1, X_2 \mapsto n-1, X_3 \mapsto n\}, & \mathbf{s}_4 &= \{X_1 \mapsto n-2, X_2 \mapsto n-1, X_3 \mapsto n\}, \\ \mathbf{s}_5 &= \{X_1 \mapsto n-2, X_2 \mapsto n-1, X_3 \mapsto n-1\}, & \mathbf{s}_6 &= \{X_1 \mapsto n-2, X_2 \mapsto n-2, X_3 \mapsto n-1\}, \end{aligned}$$

and we consider the unification $\rho_{s_1}(\xi_1) \wedge R_1$, which is related to the unification $\xi_1 \wedge R_1$ via the mapping ϕ_μ as follows:

$$\begin{aligned} \phi_\mu(\mathbf{T}_1) &= \rho_{s_1}(\xi_1) \wedge R_1, & \phi_\mu(\mathbf{T}_2) &= \rho_{s_2}(\xi_2) \wedge R_2, & \phi_\mu(\mathbf{T}_3) &= \rho_{s_3}(\xi_1) \wedge R_3, \\ \phi_\mu(\mathbf{T}_4) &= \rho_{s_4}(\xi_3) \wedge R_4, & \phi_\mu(\mathbf{T}_5) &= \rho_{s_5}(\xi_2) \wedge R_5, & \phi_\mu(\mathbf{T}_6) &= \rho_{s_6}(\xi_1) \wedge R_6. \end{aligned}$$

The measures $\Omega_S^\#$ and ω_S and \mathbf{D}^*_S , related to the (fixed-point) sequence \mathcal{S} , are given in Table 3, in which the second row shows the T_μ -strategy among $\{\xi_1, \xi_2, \xi_3\}$ that appears in \mathbf{T}_i ; and the third row shows the iteration mapping \mathbf{s}_i involved in $\phi_\mu(\mathbf{T}_i)$.

Table 3

An example of the measures $\Omega_S^\#$ and ω_S , and the codistance \mathbf{D}^*_S related to the fixed-point left-maximal sequence $S = \mathbf{T}_1 \sqsupset \dots \sqsupset \mathbf{T}_6$ defined in Eq. (26). The second row shows the T_μ -strategy among $\{\xi_1, \xi_2, \xi_3\}$ that appears in \mathbf{T}_i , for $i = 1, \dots, 6$. The third row shows the iteration mapping \mathbf{s}_i involved in $\phi_\mu(\mathbf{T}_i)$, where the triplet (n_1, n_2, n_3) refers to the iteration mapping $\{X_1 \mapsto n_1, X_2 \mapsto n_2, X_3 \mapsto n_3\}$.

\mathbf{T}_i	\mathbf{T}_1	\mathbf{T}_2	\mathbf{T}_3	\mathbf{T}_4	\mathbf{T}_5	\mathbf{T}_6
ξ_j in \mathbf{T}_i	ξ_1	ξ_2	ξ_1	ξ_3	ξ_2	ξ_1
\mathbf{s}_i	(n, n, n)	$(n-1, n, n)$	$(n-1, n-1, n)$	$(n-2, n-1, n)$	$(n-2, n-1, n-1)$	$(n-2, n-2, n-1)$
$\Omega_S^\#(\mathbf{T}_i, \mathbf{T}_i)$	1	1	2	2	2	3
$\omega_S(\mathbf{T}_i)$	$n-1$	$n-1$	$n-2$	$n-2$	$n-2$	$n-3$
$\mathbf{D}^*_S(\mathbf{T}_i)$	n	$n-1$	$n-1$	$n-2$	$n-2$	$n-2$

In Lemma 96 we shall establish a useful relation between ω and \mathbf{D}^* .

Lemma 96. For any left-maximal sequence

$$\mathbf{T}_1 \sqsupset \dots \sqsupset \mathbf{T}_m$$

in \mathcal{T} with $m \geq 2$, and for any p and q where $1 \leq p < q \leq m$,

1. If for $i = 1, \dots, q$, there are T_μ -strategies $S_i \in \tilde{\Phi}(S)$ and $R_i \in \tilde{\Phi}(R)$, and iteration mappings $\mathbf{s}_i : \{X_1, \dots, X_s\} \rightarrow \mathbb{N}$ and $\mathbf{r}_i : \{Y_1, \dots, Y_s\} \rightarrow \mathbb{N}$ such that

$$\phi_\mu(\mathbf{T}_i) = \rho_{\mathbf{s}_i}(S_i) \wedge \rho_{\mathbf{r}_i}(R_i)$$

then

$$\omega(\mathbf{T}_q) \in \{D^*((\mathbf{s}_1, \mathbf{r}_1), (\mathbf{s}_q, \mathbf{r}_q)), D^*((\mathbf{s}_1, \mathbf{r}_1), (\mathbf{s}_q, \mathbf{r}_q)) - 1\}. \quad (27)$$

2. If there is a T_μ -strategy $\xi_m \in \tilde{\Phi}(S) \cup \tilde{\Phi}(R)$ and an iteration mapping \mathbf{s}_m such that

$$\phi_\mu(\mathbf{T}_m) = \rho_{\mathbf{s}_m}(\xi_m)$$

then

$$\min\{\mathbf{s}_m(X) \mid X \in \text{dom}(\mathbf{s}_m)\} \geq \mathbf{D}^*(\mathbf{T}_m). \quad (28)$$

From Lemma 76 we get the following corollary that establishes, in addition to another property, the semantic equivalence between $\phi_\mu(Z_i)$ and $\phi_\nu^\mu(Z_i)$ for a fixed-point variable Z_i of a T_μ -strategy $\mu Z_i.T_i(Z_i)$ that appears in the fixed-point tree \mathcal{T} . Roughly speaking, this corollary will be useful to prove that $\phi_\mu(\mu Z_i.T_i(Z_i))$ is a fixed-point of $T_i(Z_i)$ as explained at the beginning of Subsection 12.3, and used in the proof of Lemma 103.

Corollary 97. Let S be a sequence

$$\mu Z_1.T_1(Z_1) \sqsupset \dots \sqsupset \mu Z_m.T_m(Z_m) \sqsupset Z_i$$

in \mathcal{T} with $m \geq 1$ and $i \in \{1, \dots, m\}$.

1. If $Z_i \in \text{Bound}(S \wedge R) \setminus (\text{Bound}(S) \cup \text{Bound}(R))$ then

$$\phi_\mu(Z_i) \equiv_{\mathbf{D}^*_S(Z_i)} \phi_\nu^\mu(Z_i). \quad (29)$$

2. If $Z_m \in \text{Bound}(S) \cup \text{Bound}(R)$ (i.e. $\mu Z_m.T_m(Z_m) \in \tilde{\Phi}_\mu(S) \cup \tilde{\Phi}_\mu(R)$) then

$$\phi_\mu(\mu Z_m.T_m(Z_m)) \equiv_{\mathbf{D}^*_S(\mu Z_m.T_m(Z_m))} \mu Z_m.T_m(Z_m). \quad (30)$$

Proof. 1. Since $Z_i \in \text{Bound}(S \wedge R) \setminus (\text{Bound}(S) \cup \text{Bound}(R))$ then it follows from Items (1a) and (1b) of Lemma 90 that there are T_μ -strategies $S_i \in \Phi(S)$ and $R_i \in \Phi(R)$, and iteration mappings $\mathbf{s}_i, \mathbf{s}_j : \{X_1, \dots, X_s\} \rightarrow \mathbb{N}$ and $\mathbf{s}_i, \mathbf{r}_j : \{X_1, \dots, X_r\} \rightarrow \mathbb{N}$ such that

$$\phi_\nu^\mu(Z_i) = \rho_{\mathbf{s}_j}(S_i) \wedge \rho_{\mathbf{r}_j}(R_i)$$

$$\phi_\mu(Z_i) = \rho_{\mathbf{s}_i}(S_i) \wedge \rho_{\mathbf{r}_i}(R_i)$$

where $\mathbf{s}_j \geq \mathbf{s}_i$ and $\mathbf{r}_j \geq \mathbf{r}_i$. Thus, by Eq. (24) of Definition 94 of \mathbf{D}^* , we have $\mathbf{D}_S^*(Z_i) = D^*((\mathbf{s}_j, \mathbf{r}_j), (\mathbf{s}_i, \mathbf{r}_i))$. Hence the claim follows from Corollary 77 that states that

$$\rho_{\mathbf{s}_j}(S_i) \wedge \rho_{\mathbf{r}_j}(R_i) \equiv_{D^*((\mathbf{s}_j, \mathbf{r}_j), (\mathbf{s}_i, \mathbf{r}_i))} \rho_{\mathbf{s}_i}(S_i) \wedge \rho_{\mathbf{r}_i}(R_i).$$

2. Assume that $\mu Z_m.T_m(Z_m)$ is a sub- T_μ -strategy of S , the case when it is a sub- T_μ -strategy of R is similar. From Items (1c) of Lemma 90 it follows that there is an iteration mapping $\mathbf{s}_m : \{X_1, \dots, X_s\} \rightarrow \mathbb{N}$ such that

$$\phi_\mu(\mu Z_m.T_m(Z_m)) = \rho_{\mathbf{s}_m}(\mu Z_m.T_m(Z_m)).$$

Let $\mathbf{m} = \min\{\mathbf{s}_m(X_i) \mid i = 1, \dots, s\}$. We know from Item (ii) Lemma 71 that

$$\mu Z_m.T_m(Z_m) \equiv_{\mathbf{m}} \rho_{\mathbf{s}_m}(\mu Z_m.T_m(Z_m))$$

Hence it follows from Item (2) of Lemma 68 that to show Eq. (30) it suffices to show

$$\mathbf{D}^*(\mu Z_m.T_m(Z_m)) \leq \mathbf{m}$$

But this was proved in Lemma 96, see Eq. (28). \square

Although the following corollary will not be used in any further proofs, it is worth mentioning it.

Corollary 98. *The (C, C_0) -quasi-simulation that results between the unification of two T_μ -strategies, say $S \wedge R$, and that of their unfolding, say $\rho_S(S) \wedge \rho_R(R)$, (i.e. constructed in the proof of Lemma 87) is actually a (C, C_0) -simulation.*

Proof. This follows immediately from Corollary 97. That is, on the one hand for any T_μ -strategy $\mu Z.T(Z)$ in $S \wedge R$ that is not a sub- T_μ -strategy of S nor R , we have that each of $\phi_\mu(\mu Z.T(Z))$ (i.e. $\phi_\mu^\mu(Z)$) and $\phi_\mu(Z)$ corresponds to the unification of two unfoldings of the same two T_μ -strategies. And on the other hand, for any T_μ -strategy $\mu Z.T(Z)$ in $S \wedge R$ that is a sub- T_μ -strategy of S or R , there is a (C, C_0) -simulation between $\mu Z.T(Z)$ and any unfolding of it. \square

12.2. Derived tree and a lower bound for the number of jumps

The Eq. (27) of Lemma 96 allows one to distinguish between elements of \mathcal{T} whose ω and \mathbf{D}^* are equal, and those whose ω and \mathbf{D}^* are different by 1. The latter elements form the *derived tree* of \mathcal{T} . The name “derived” tree is justified by the fact that we want to focus on the elements of \mathcal{T} on which \mathbf{D}^* changes and increases by 1.

Definition 99 (*Derived tree $\partial\mathcal{T}$ of \mathcal{T}*). Recall that $\mathcal{T} = (\Phi_\mu(S \wedge R), \sqsupset)$. We define the *derived tree* of \mathcal{T} , denoted by $\partial\mathcal{T}$, as the pair $\partial\mathcal{T} = (A, \sqsupset)$ where $A \subseteq \Phi_\mu(S \wedge R)$ is defined by

$$A = \{\mathbf{T} \in \Phi_\mu(S \wedge R) \mid \omega_S(\mathbf{T}) = \mathbf{D}_S^*(\mathbf{T}) - 1, \text{ for any maximal sequence } \mathcal{S} \text{ in } \mathcal{T} \text{ containing } \mathbf{T}\}.$$

Example 100 (*Derived tree $\partial\mathcal{T}$*). We consider Example 95, and we assume that the fixed-point tree \mathcal{T} of $\xi_1 \wedge R_1$ contains just the sequence $\mathcal{S} = \mathbf{T}_1 \sqsupset \mathbf{T}_2 \sqsupset \dots \sqsupset \mathbf{T}_6$, defined in Eq. (26). By examining the last two rows of Table 3 that respectively exhibit $\omega_S(\mathbf{T}_i)$ and $\mathbf{D}_S^*(\mathbf{T}_i)$, we notice that the equality $\omega_S(\mathbf{T}) = \mathbf{D}_S^*(\mathbf{T}) - 1$ holds for $\mathbf{T} = \mathbf{T}_1, \mathbf{T}_3, \mathbf{T}_6$. Hence it follows that the derived tree $\partial\mathcal{T}$ is composed of $\mathbf{T}_1, \mathbf{T}_3, \mathbf{T}_6$. Besides, in $\partial\mathcal{T}$, we have $\mathbf{T}_1 \sqsupset \mathbf{T}_3 \sqsupset \mathbf{T}_6$.

The following remark provides useful observations that can be illustrated by the Table 3 of the Example 95.

Remark 101. Notice that, for any maximal sequence \mathcal{S} in \mathcal{T} , the following statements follow from Eq. (27) of Lemma 96 and from Definition 99.

1. Any (fixed-point) T_μ -strategy \mathbf{T} which is in \mathcal{T} but not in $\partial\mathcal{T}$ has the property $\omega_S(\mathbf{T}) = \mathbf{D}_S^*(\mathbf{T})$.
2. Since by Items (1a) and (1b) of Lemma 90 we know that each of \mathbf{D}^* and ω can be incremented by at most 1 from a T_μ -strategy to its immediate sub- T_μ -strategy in \mathcal{T} , then if $\hat{\mathbf{T}}_1$ is in $\partial\mathcal{T}$ and \mathbf{T}_2 is in \mathcal{T} such that $\hat{\mathbf{T}}_1 \sqsupset \mathbf{T}_2$, then $\mathbf{D}_S^*(\hat{\mathbf{T}}_1) = \mathbf{D}_S^*(\mathbf{T}_2) + 1$ and hence $\omega_S(\hat{\mathbf{T}}_1) = \omega_S(\mathbf{T}_2)$.
3. Similarly, if $\mathbf{T}_1, \dots, \mathbf{T}_m$ are in \mathcal{T} , and $\hat{\mathbf{T}}_2$ is in $\partial\mathcal{T}$ such that $\mathbf{T}_1 \sqsupset \dots \sqsupset \mathbf{T}_m \sqsupset \hat{\mathbf{T}}_2$, then $\mathbf{D}_S^*(\mathbf{T}_i) = \mathbf{D}_S^*(\hat{\mathbf{T}}_2)$ and $\omega_S(\mathbf{T}_i) = \omega_S(\hat{\mathbf{T}}_2) + 1$, for any $i \in \{1, \dots, m\}$.
4. In particular, if $\hat{\mathbf{T}}_1$ and $\hat{\mathbf{T}}_2$ are in $\partial\mathcal{T}$ such that $\hat{\mathbf{T}}_1 \sqsupset \hat{\mathbf{T}}_2$, then $\mathbf{D}_S^*(\hat{\mathbf{T}}_1) = \mathbf{D}_S^*(\hat{\mathbf{T}}_2) + 1$ and $\omega_S(\hat{\mathbf{T}}_1) = \omega_S(\hat{\mathbf{T}}_2) + 1$.

Thanks to Lemma 96 and Remark 101, we show in the following Lemma 102 a crucial property of the derived tree $\partial\mathcal{T}$ that was behind its introduction: if two T_μ -strategies $\hat{\mathbf{T}}_1$ and $\hat{\mathbf{T}}_2$ are in $\partial\mathcal{T}$ with $\hat{\mathbf{T}}_1 \sqsupset \hat{\mathbf{T}}_2$, then the number of jumps between the root of $\hat{\mathbf{T}}_1$ and $\hat{\mathbf{T}}_2$ is at least one.

Lemma 102. *Let*

$$\mu \hat{Z}_1. \hat{T}_1(\hat{Z}_1) \sqsupset \hat{T}_2$$

be a sequence in $\partial\mathcal{T}$. Define $\hat{T}_1^(Z)$ to be the (unique) \mathbb{T}_μ -strategy satisfying*

$$\hat{T}_1^*(\hat{T}_2) = \hat{T}_1(\hat{Z}_1).$$

We have that

$$1 \leq \Pi_Z(\hat{T}_1^*(Z)). \quad (31)$$

12.3. The unification of two \mathbb{T}_μ -strategies is equivalent to the unification of their unfolding

We arrive at the key lemma that will allow us to show that unification of two \mathbb{T}_μ -strategies is n -equivalent to the unification of their unfolding. We already explained at the beginning of this Section 12 that, in the particular setting where $S \wedge R$ is composed of just one \mathbb{T}_μ -strategy, say $\mu Z.T(Z)$, the purpose is to show that \mathbf{E} is a fixed-point of $T(Z)$, where \mathbf{E} is the unification of the unfolding of two \mathbb{T}_μ -strategies. That is, we want to show that \mathbf{E} is n -equivalent to $T(\mathbf{E})$.

However, if we consider the general setting in which the fixed-point \mathbb{T}_μ -strategies in $S \wedge R$ can be nested, namely if we have a sequence $\mathcal{S} = \mu Z_1.T_1(Z_1) \sqsupset \dots \sqsupset \mu Z_m.T_m(Z_m)$ in $S \wedge R$, then a fixed-point variable Z_i may appear in any \mathbb{T}_μ -strategy $\mu Z_j.T_j(Z_j)$ for $1 \leq i \leq j \leq m$. Therefore, we need a general and inductive way to formulate and then to show that certain fixed-point free \mathbb{T}_μ -strategies $\mathbf{E}_1, \dots, \mathbf{E}_m$ (which are in the \mathbb{T}_μ -strategy that results from the unification of the unfolding of S with the unfolding of R) are a fixed-point of $T_1(Z_1), \dots, T_m(Z_m)$, respectively, in the sense that \mathbf{E}_i is n_i -equivalent to $T_i(\mathbf{E}_i)$, for $i = 1, \dots, m$, where n_i is an appropriate constant. This general and inductive way of formulating such requirements is achieved thanks to the mappings ϕ_μ and $\hat{\phi}_v^\mu$ by just imposing that $\phi_\mu(\mu Z_i.T_i(Z_i))$ and $\hat{\phi}_v^\mu(T_i(Z_i))$ must be $\mathbf{D}^*_\mathcal{S}(\mu Z_i.T_i(Z_i))$ -equivalent. In particular, $\phi_\mu(\mu Z_i.T_i(Z_i))$ corresponds to \mathbf{E}_i , while $\hat{\phi}_v^\mu(T_i(Z_i))$ corresponds to $T(\mathbf{E}_i)$ since, roughly speaking, $\hat{\phi}_v^\mu(T_i(Z_i))$ corresponds to $T_i(\hat{\phi}_v^\mu(Z_i))$ which is $T_i(\mathbf{E}_i)$.

Lemma 103. *Let S (resp. R) be a \mathbb{T}_μ -strategy with bound fixed-point variables X_1, \dots, X_s (resp. Y_1, \dots, Y_r), and let $n \geq 1$. Let $\mathbf{s} : \{X_1, \dots, X_s\} \rightarrow \mathbb{N}$ and $\mathbf{r} : \{Y_1, \dots, Y_r\} \rightarrow \mathbb{N}$ be iteration mappings with $\mathbf{s}(X_i) = \mathbf{r}(Y_j) = n$, for $i = 1, \dots, s$ and $j = 1, \dots, r$. Let \mathcal{T} be the fixed-point tree of $S \wedge R$ rooted at $\mu Z_1.T_1(Z_1)$. Let \mathcal{T}_i be a right maximal sub-tree of \mathcal{T} rooted at $\mu Z_i.T_i(Z_i)$ yielding the unique sequence \mathcal{S}^i :*

$$\mu Z_1.T_1(Z_1) \sqsupset \dots \sqsupset \mu Z_i.T_i(Z_i)$$

in \mathcal{T} and let

$$\omega(i) = \omega_{\mathcal{S}^i}(\mu Z_i.T_i(Z_i))$$

$$\mathbf{D}^*(i) = \mathbf{D}^*_{\mathcal{S}^i}(\mu Z_i.T_i(Z_i)).$$

Then for any $i = 1, \dots, \delta(\mathcal{T})$, and any maximal sequence

$$\mu Z_i.T_i(Z_i) \sqsupset \dots \sqsupset \mu Z_m.T_m(Z_m)$$

in \mathcal{T}_i where $i \leq m$, either

(i) $Z_i \in \text{Bound}(S \wedge R) \setminus (\text{Bound}(S) \cup \text{Bound}(R))$ and in this case we have that

$$\phi_\mu(\mu Z_i.T_i(Z_i)) \equiv_{\mathbf{D}^*(i)} \hat{\phi}_v^\mu(T_i(Z_i)), \quad (32)$$

(ii) or $i = m$ and $Z_m \in \text{Bound}(S) \cup \text{Bound}(R)$, and in this case we have that

$$\phi_\mu(\mu Z_m.T_m(Z_m)) \equiv_{\mathbf{D}^*(m)} \mu Z_m.T_m(Z_m). \quad (33)$$

Proof. The proof is by a double induction. The outer one is a structural induction on the tree $\partial\mathcal{T}_i$.

Outer base case $\delta(\partial\mathcal{T}_i) = 0$. In this case consider a maximal sequence

$$\mu Z_i.T_i(Z_i) \sqsupset \dots \sqsupset \mu Z_m.T_m(Z_m)$$

in \mathcal{T}_i with $1 \leq i \leq m$. Indeed, since $\delta(\partial\mathcal{T}_i) = 0$ then

$$\mathbf{D}^*(i) = \mathbf{D}^*(i+1) = \dots = \mathbf{D}^*(m). \quad (34)$$

We make an inner structural induction on \mathcal{T}_i .

Inner base case: $\delta(\mathcal{T}_i) = 1$.

Since \mathcal{T}_i is not necessarily connected, it may contain many maximal sequences, but each one of them is composed of just one fixed-point T_μ -strategy. Hence, consider a maximal sequence

$$\mu Z_m.T_m(Z_m)$$

in \mathcal{T}_i . And we need to show that

$$\begin{aligned} \phi_\mu(\mu Z_m.T_m(Z_m)) &\equiv_{\mathbf{D}^*(m)} \widehat{\phi}_v^\mu(T_m(Z_m)) && \text{if } Z_m \in \text{Bound}(S \wedge R) \setminus (\text{Bound}(S) \cup \text{Bound}(R)) && \text{(a)} \\ \phi_\mu(\mu Z_m.T_m(Z_m)) &\equiv_{\mathbf{D}^*(m)} \mu Z_m.T_m(Z_m) && \text{if } Z_m \in \text{Bound}(S) \cup \text{Bound}(R). && \text{(b)} \end{aligned} \quad (35)$$

If $Z_m \in \text{Bound}(S) \cup \text{Bound}(R)$ then Eq. (35)(b) follows from Eq. (30) of Corollary 97.

If $Z_m \in \text{Bound}(S \wedge R) \setminus (\text{Bound}(S) \cup \text{Bound}(R))$ then notice that $T_m(Z_m)$ is fixed point-free but may contain free fixed-point variables besides Z_m . Therefore there exists a fixed point-free T_μ -strategy $T^*(Z^1, \dots, Z^l, Z_m)$ with $l \geq 0$ and $\{Z^1, \dots, Z^l\} \subseteq \{Z_1, \dots, Z_m\} \setminus \{Z_m\}$ such that $T_m(Z_m) = T_m^*(Z^1, \dots, Z^l, Z_m)$. Hence we need to show that

$$\phi_\mu(\mu Z_m.T_m^*(Z^1, \dots, Z^l, Z_m)) \equiv_{\mathbf{D}^*(m)} \widehat{\phi}_v^\mu(T_m^*(Z^1, \dots, Z^l, Z_m)). \quad (36)$$

On the one hand, it follows from Remark 86 that the left-hand side of Eq. (36) can be written as

$$\begin{aligned} \text{LHS.}(36) &= \phi_\mu(\mu Z_m.T_m^*(Z^1, \dots, Z^l, Z_m)) \\ &= T_m^*(\phi_\mu(Z^1), \dots, \phi_\mu(Z^l), \phi_\mu(Z_m)). \end{aligned}$$

On the other hand, by the Definition 84 of $\widehat{\phi}_v^\mu$, the right-hand side of Eq. (36) can be written as

$$\begin{aligned} \text{RHS.}(36) &= \widehat{\phi}_v^\mu(T_m^*(Z^1, \dots, Z^l, Z_m)) \\ &= T_m^*(\widehat{\phi}_v^\mu(Z^1), \dots, \widehat{\phi}_v^\mu(Z^l), \widehat{\phi}_v^\mu(Z_m)) \\ &= T_m^*(\phi_v^\mu(Z^1), \dots, \phi_v^\mu(Z^l), \phi_v^\mu(Z_m)). \end{aligned}$$

Thus we need to show that

$$T_m^*(\phi_\mu(Z^1), \dots, \phi_\mu(Z^l), \phi_\mu(Z_m)) \equiv_{\mathbf{D}^*(m)} T_m^*(\phi_v^\mu(Z^1), \dots, \phi_v^\mu(Z^l), \phi_v^\mu(Z_m)). \quad (37)$$

From Eq. (29) of Corollary 97 we have that

$$\phi_\mu(Z_m) \equiv_{\mathbf{D}^*(Z_m)} \phi_v^\mu(Z_m) \quad \text{and} \quad \phi_\mu(Z^j) \equiv_{\mathbf{D}^*(Z^j)} \phi_v^\mu(Z^j) \text{ for } j = 1, \dots, l.$$

But we know from Eq. (34) above that $\mathbf{D}^*(Z_m) = \mathbf{D}^*(m)$ as well as $\mathbf{D}^*(Z_m) = \mathbf{D}^*(Z^j)$ for $j = 1, \dots, l$. Thus Eq. (37) holds by Item (2) of Lemma 68.

Inner induction step. Assume that Eq. (32) holds for a fixed-point sub-tree \mathcal{T}_i of \mathcal{T} , and we shall prove it for the (unique) fixed-point sub-tree \mathcal{T}_{i-1} (of \mathcal{T}) that contains \mathcal{T}_i such that \mathcal{T}_i is an immediate sub-tree of \mathcal{T}_i . Assume that \mathcal{T}_{i-1} is rooted at $\mu Z_{i-1}.T_{i-1}(Z_{i-1})$.

Consider such tree \mathcal{T}_{i-1} and a maximal sequence

$$\mu Z_{i-1}.T_{i-1}(Z_{i-1}) \sqsupset \mu Z_i.T_i(Z_i) \sqsupset \dots \sqsupset \mu Z_m.T_m(Z_m)$$

in \mathcal{T}_{i-1} . We recall that we have

$$\mathbf{D}^*(i-1) = \dots = \mathbf{D}^*(m). \quad (38)$$

The T_μ -strategy $T_{i-1}(Z_{i-1})$ can be written in terms of its immediate fixed-point sub- T_μ -strategies and fixed-point variables in the sense that there exist $k \geq 1$ and $l \geq 0$ and

- i.) a fixed-point free T_μ -strategy $T_{i-1}^*(X^1, \dots, X^{k+l})$ in which each fixed-point variable X^j is free, and
 - ii.) T_μ -strategies $\mathbf{T}_1, \dots, \mathbf{T}_k$ where each \mathbf{T}_j is either a fixed-point T_μ -strategy in $\Phi_\mu(S \wedge R)$, and
 - iii.) fixed-point variables Z^1, \dots, Z^l where $\{Z^1, \dots, Z^l\} \subseteq \{Z_1, \dots, Z_{i-1}\}$,
- such that $T_{i-1}(Z_{i-1})$ can be written as

$$T_{i-1}(Z_{i-1}) = T_{i-1}^*(\mathbf{T}_1, \dots, \mathbf{T}_k, Z^1, \dots, Z^l).$$

Hence, we need to show that

$$\phi_\mu(\mu Z_{i-1}.T_{i-1}^*(\mathbf{T}_1, \dots, \mathbf{T}_k, Z^1, \dots, Z^l)) \equiv_{\mathbf{D}^*(i-1)} \widehat{\phi}_v^\mu(T_{i-1}^*(\mathbf{T}_1, \dots, \mathbf{T}_k, Z^1, \dots, Z^l)). \quad (39)$$

On the one hand, it follows from Remark 86 that the left-hand side of Eq. (39) can be written as

$$\begin{aligned} \text{LH.}(39) &= \phi_\mu(\mu Z_{i-1}.T_{i-1}^*(\mathbf{T}_1, \dots, \mathbf{T}_k, Z^1, \dots, Z^l)) \\ &= T_{i-1}^*(\phi_\mu(\mathbf{T}_1), \dots, \phi_\mu(\mathbf{T}_k), \phi_\mu(Z^1), \dots, \phi_\mu(Z^l)). \end{aligned}$$

On the one hand, by Definition 84 of $\widehat{\phi}_v^\mu$, the right-hand side of Eq. (39) can be written as

$$\begin{aligned} \text{RH.}(39) &= \widehat{\phi}_v^\mu(T_{i-1}^*(\mathbf{T}_1, \dots, \mathbf{T}_k, Z^1, \dots, Z^l)) \\ &= T_{i-1}^*(\widehat{\phi}_v^\mu(\mathbf{T}_1), \dots, \widehat{\phi}_v^\mu(\mathbf{T}_k), \phi_v^\mu(Z^1), \dots, \phi_v^\mu(Z^l)). \end{aligned}$$

Therefore showing Eq. (39) amounts to show that

$$T_{i-1}^*(\phi_\mu(\mathbf{T}_1), \dots, \phi_\mu(\mathbf{T}_k), \phi_\mu(Z^1), \dots, \phi_\mu(Z^l)) \equiv_{\mathbf{D}^*(i-1)} T_{i-1}^*(\widehat{\phi}_v^\mu(\mathbf{T}_1), \dots, \widehat{\phi}_v^\mu(\mathbf{T}_k), \phi_v^\mu(Z^1), \dots, \phi_v^\mu(Z^l)). \quad (40)$$

We recall that from Eq. (38), we have $\mathbf{D}^*(\mathbf{T}_j) = \mathbf{D}^*(i-1)$ for $j = 1, \dots, k$ as well as $\mathbf{D}^*(Z^j) = \mathbf{D}^*(i-1)$ for $j = 1, \dots, l$. Therefore from Item 2 of Lemma 68 it follows that to show Eq. (40) it is enough to show that for any $j = 1, \dots, k$

$$\phi_\mu(\mathbf{T}_j) \equiv_{\mathbf{D}^*(\mathbf{T}_j)} \widehat{\phi}_v^\mu(\mathbf{T}_j) \quad (41)$$

and that for any $j = 1, \dots, l$,

$$\phi_\mu(Z^j) \equiv_{\mathbf{D}^*(Z^j)} \phi_v^\mu(Z^j) \quad (42)$$

To achieve this, consider the two cases.

- For Eq. (41) assume that \mathbf{T}_j is of the form $\mathbf{T}_j = \mu \mathbf{Z}^j. \mathbf{T}_j^*(\mathbf{Z}^j)$. We distinguish two cases depending on whether $\mathbf{Z}^j \in \text{Bound}(S \wedge R) \setminus (\text{Bound}(S) \cup \text{Bound}(R))$ or $\mathbf{Z}^j \in (\text{Bound}(S) \cup \text{Bound}(R))$. For the first case we have the sequence

$$\mu Z_{i-1}.T_{i-1}(Z_{i-1}) \sqsupset \mathbf{T}_j \sqsupset \mu Z_{i+1}.T_{i+1}(Z_{i+1}) \sqsupset \dots \sqsupset \mu Z_m.T_m(Z_m)$$

in \mathcal{T} . Let \mathcal{T}^j be the maximal sub-tree of \mathcal{T}_{i-1} which is rooted at \mathbf{T}_j . Since \mathcal{T}^j is an immediate sub-tree of \mathcal{T}_{i-1} , then Eq. (41) follows from the inner induction hypothesis. However, for the second case where $\mathbf{Z}^j \in (\text{Bound}(S) \cup \text{Bound}(R))$ we have the sequence

$$\mu Z_{i-1}.T_{i-1}(Z_{i-1}) \sqsupset \mathbf{T}_j$$

in \mathcal{T} . That is, in this case we remind that the fixed-point \mathbf{T}_μ -strategy \mathbf{T}_j is either a sub- \mathbf{T}_μ -strategy of S or of R . Hence, we have $\widehat{\phi}_v^\mu(\mathbf{T}_j) = \mathbf{T}_j$. It follows from the base case, i.e. Eq. (33) that

$$\phi_\mu(\mathbf{T}_j) \equiv_{\mathbf{D}^*(\mathbf{T}_j)} \mathbf{T}_j.$$

- For Eq. (42), it follows from Eq. (29) of Corollary 97.

Outer induction step. Assume that Eq. (32) holds for a fixed-point sub-tree $\partial \mathcal{T}_i$ of \mathcal{T} , we shall prove it for the (unique) fixed-point sub-tree $\partial(\mathcal{T}_{i-1})$ (of \mathcal{T}) that contains $\partial \mathcal{T}_i$ such that $\partial \mathcal{T}_i$ is an immediate sub-tree of $\partial \mathcal{T}_i$. Let $\mu \hat{Z}_{i-1}.\hat{T}_{i-1}(\hat{Z}_{i-1})$ be a root of $\partial(\mathcal{T}_{i-1})$, and let $\mu \hat{Z}_i.\hat{T}_i(\hat{Z}_i)$ be a root of $\partial(\mathcal{T}_i)$. Consider such tree $\partial(\mathcal{T}_{i-1})$ and a maximal sequence

$$\mu \hat{Z}_{i-1}.\hat{T}_{i-1}(\hat{Z}_{i-1}) \sqsupset \mu \hat{Z}_i.\hat{T}_i(\hat{Z}_i) \sqsupset \dots \sqsupset \mu \hat{Z}_m.\hat{T}_m(\hat{Z}_m)$$

in $\partial \mathcal{T}_{i-1}$. Assume that the maximal sequence in \mathcal{T}_{i-1} that lays between the root of $\partial \mathcal{T}_{i-1}$ and the root of $\partial(\mathcal{T}_i)$ is non-empty, the case where it is empty can be handled similarly. Let the following be such a sequence:

$$\mu \hat{Z}_{i-1}.\hat{T}_{i-1}(\hat{Z}_{i-1}) \sqsupset \mu Z_p.T_p(Z_p) \sqsupset \mu Z_{p+1}.T_{p+1}(Z_{p+1}) \sqsupset \dots \sqsupset \mu Z_q.T_q(Z_q) \sqsupset \mu \hat{Z}_i.\hat{T}_i(\hat{Z}_i)$$

where $1 \leq p \leq q$. In this case, by Definition 99 of the derived tree $\partial \mathcal{T}$ we have

$$\mathbf{D}^*(\mu \hat{Z}_{i-1}.\hat{T}_{i-1}(\hat{Z}_{i-1})) = \mathbf{D}^*(\mu Z_p.T_p(Z_p)) + 1 \quad (43)$$

$$\mathbf{D}^*(\mu Z_j.T_j(Z_j)) = \mathbf{D}^*(\mu Z_{j+1}.T_{j+1}(Z_{j+1})) = \mathbf{D}^*(\mu \hat{Z}_i.\hat{T}_i(\hat{Z}_i)) \quad \text{for } j = p, \dots, q-1. \quad (44)$$

On the one hand, from the outer induction hypothesis we have that

$$\phi_\mu(\mu \hat{Z}_i.\hat{T}_i(\hat{Z}_i)) \equiv_{\mathbf{D}^*(\hat{T}_i(\hat{Z}_i))} \widehat{\phi}_v^\mu(\hat{T}_i(\hat{Z}_i)). \quad (45)$$

On the other hand, as far as Eq. (44) holds, using the same kind of induction made in the inner base case, we can easily show that, for $j = 1, \dots, q - 1$, we have

$$\phi_\mu(\mu Z_j.T_j(Z_j)) \equiv_{\mathbf{D}^*(\mu Z_j.T_j(Z_j))} \widehat{\phi}_\mu^\nu(T_j(Z_j)). \quad (46)$$

Since $\mu \hat{Z}_i.\hat{T}_i(\hat{Z}_i)$ is a sub- \mathbb{T}_μ -strategy of $\mu \hat{Z}_{i-1}.\hat{T}_{i-1}(\hat{Z}_{i-1})$ then there is a \mathbb{T}_μ -strategy $\hat{T}_{i-1}^*(Z)$ such that $\hat{T}_{i-1}(\hat{Z}_{i-1})$ can be written as

$$\hat{T}_{i-1}(\hat{Z}_{i-1}) = T_{i-1}^*(\mu \hat{Z}_i.\hat{T}_i(\hat{Z}_i)).$$

Since by Eq. (43) we know that $\mathbf{D}^*(\mu \hat{Z}_{i-1}.\hat{T}_{i-1}(\hat{Z}_{i-1})) = \mathbf{D}^*(\mu Z_p.T_p(Z_p)) + 1$, then it follows from Item 1 of Lemma 68 that to show Eq. (32), it suffices to show that

$$1 \leq \Pi_Z(\hat{T}_{i-1}^*(Z)),$$

but this was proved in Lemma 102, see Eq. (31). \square

In the following Corollary we show that the unification of two \mathbb{T}_μ -strategies is equivalent to that of their unfolding in the particular setting in which one of these two \mathbb{T}_μ -strategies is a fixed-point one.

Corollary 104. *Let S (resp. R) be a \mathbb{T}_μ -strategy with bound fixed-point variables X_1, \dots, X_s (resp. Y_1, \dots, Y_r) and let $n \geq 1$. Let $\mathbf{s} : \{X_1, \dots, X_s\} \rightarrow \mathbb{N}$ and $\mathbf{r} : \{Y_1, \dots, Y_r\} \rightarrow \mathbb{N}$ be iteration mappings with $\mathbf{s}(X_i) = \mathbf{r}(Y_j) = n$ for $i = 1, \dots, s$ and $j = 1, \dots, r$. If either S or R is a fixed-point \mathbb{T}_μ -strategy then*

$$S \wedge R \equiv_n \rho_{\mathbf{s}}(S) \wedge \rho_{\mathbf{r}}(R) \quad (47)$$

Or, the following two diagrams commute where \mathcal{C}_μ stands of the set of fixed-point \mathbb{T}_μ -strategies.

$$\begin{array}{ccc} \mathcal{C}_\mu \times \mathcal{C} & \xrightarrow{\wedge} & \mathcal{C} \\ \rho_{\mathbf{s}}(\cdot) \times \rho_{\mathbf{r}}(\cdot) \downarrow & & \downarrow \equiv_n \\ \mathcal{C}_0 \times \mathcal{C}_0 & \xrightarrow{\wedge} & \mathcal{C}_0 \end{array} \quad \begin{array}{ccc} \mathcal{C} \times \mathcal{C}_\mu & \xrightarrow{\wedge} & \mathcal{C} \\ \rho_{\mathbf{s}}(\cdot) \times \rho_{\mathbf{r}}(\cdot) \downarrow & & \downarrow \equiv_n \\ \mathcal{C}_0 \times \mathcal{C}_0 & \xrightarrow{\wedge} & \mathcal{C}_0 \end{array}$$

Proof. Let

$$\mathbf{E} = \rho_{\mathbf{s}}(S) \wedge \rho_{\mathbf{r}}(R),$$

and assume that $S \wedge R = \mu Z_1.T_1(Z_1)$ for some \mathbb{T}_μ -strategy $T_1(Z_1)$. The key idea of the proof is to show that \mathbf{E} is a fixed-point of $T_1(Z_1)$ in the sense that $T_1(\mathbf{E}) \equiv_n \mathbf{E}$. To achieve this we take $i = 1$ in Eq. (32) of Lemma 103, and we get

$$\phi_\mu(\mu Z_1.T_1(Z_1)) \equiv_{\mathbf{D}^*(\mu Z_1.T_1(Z_1))} \widehat{\phi}_\nu^\mu(T_1(Z_1))$$

But since $\mathbf{D}^*(\mu Z_1.T_1(Z_1)) = n$ by the Eq. (24) of Definition 94 of \mathbf{D}^* , we get

$$\phi_\mu(\mu Z_1.T_1(Z_1)) \equiv_n \widehat{\phi}_\nu^\mu(T_1(Z_1)). \quad (48)$$

On the one hand, by Definition 84 of ϕ_μ together with Lemma 90 on the properties of ϕ_μ , it follows that the left-hand side of Eq. (48) can be written as:

$$\text{LH.}(48) = \phi_\mu(\mu Z_1.T_1(Z_1)) = \mathbf{E}. \quad (49)$$

On the other hand, the right-hand side of Eq. (48) can be written as:

$$\begin{aligned} \text{RH.}(48) &= \widehat{\phi}_\nu^\mu(T_1(Z_1)) \\ &= T_1(\widehat{\phi}_\nu^\mu(Z_1)) && \text{(Since } Z_1 \text{ is the only free fixed-point variable of } T_1(Z_1)) \\ &= T_1(\phi_\nu^\mu(Z_1)) && \text{(Definition 84 of } \widehat{\phi}_\nu^\mu) \\ &= T_1(\phi_\mu(\mu Z_1.T_1(Z_1))) && \text{(Definition 84 of } \phi_\nu^\mu) \\ &= T_1(\mathbf{E}). && \text{(From Eq. (49))} \end{aligned}$$

Summing up, and relying on Eq. (48), we get

$$T_1(\mathbf{E}) \equiv_n \mathbf{E}.$$

It follows from Corollary 70 that

$$\mu Z_1.T_1(Z_1) \equiv_n \mathbf{E}.$$

But since, by definition, we have that $S \wedge R = \mu Z_1.T_1(Z_1)$ and $\rho_s(S) \wedge \rho_r(R) = \mathbf{E}$, then we get the desired result, i.e. Eq. (47). \square

We generalize Corollary 104 by relaxing the assumption on the input T_μ -strategies and letting them to be arbitrary instead of being fixed-point ones. We thus arrive at the main result of this Subsection.

Proposition 105. *Let S (resp. R) be a T_μ -strategy with bound fixed-point variables X_1, \dots, X_s (resp. Y_1, \dots, Y_r) and let $n \geq 1$. Let $\mathbf{s} : \{X_1, \dots, X_s\} \rightarrow \mathbb{N}$ and $\mathbf{r} : \{Y_1, \dots, Y_r\} \rightarrow \mathbb{N}$ be iteration mappings with $\mathbf{s}(X_i) = \mathbf{r}(Y_j) = n$ for $i = 1, \dots, s$ and $j = 1, \dots, r$. Then,*

$$S \wedge R \equiv_n \rho_s(S) \wedge \rho_r(R),$$

which is illustrated by the commutative diagram below.

$$\begin{array}{ccc} \mathcal{C} \times \mathcal{C} & \xrightarrow{\wedge} & \mathcal{C} \\ \rho_s(\cdot) \times \rho_r(\cdot) \downarrow & & \downarrow \equiv_n \\ \mathcal{C}_0 \times \mathcal{C}_0 & \xrightarrow{\wedge} & \mathcal{C}_0 \end{array}$$

Proof. There are fixed-point free T_μ -strategies $S'(X^1, \dots, X^k)$ and $R'(Y^1, \dots, Y^l)$, where $k \geq 1$ and $l \geq 1$, as well as fixed-point T_μ -strategies ξ_1, \dots, ξ_k and ζ_1, \dots, ζ_l such that S and R can be written as:

$$S = S'(\xi_1, \dots, \xi_k) \quad R = R'(\zeta_1, \dots, \zeta_l)$$

On the one hand, it follows from the composition Lemma 73 that there is a fixed-point free T_μ -strategy $T(Z_1, \dots, Z_m)$ and T_μ -strategies T_1, \dots, T_m , where $m \geq 1$, such that $S \wedge R$ can be written as

$$S \wedge R = T(T_1, \dots, T_m),$$

where for any $i = 1, \dots, m$, one of the following cases holds.

1. There is $j \in \{1, \dots, k\}$ and a T_μ -strategy R^i that is a sub- T_μ -strategy of R such that

$$T_i = \xi_j \wedge R^i \quad \text{or} \quad T_i = \xi_j.$$

2. There is $j \in \{1, \dots, l\}$ and a T_μ -strategy S^i that is a sub- T_μ -strategy of S such that

$$T_i = S^i \wedge \zeta_j \quad \text{or} \quad T_i = \zeta_j.$$

We only discuss the first case since the second one is similar. On the other hand, since there is a $(\mathcal{C}, \mathcal{C}_0)$ -quasi-simulation between $S \wedge R$ and $\rho_s(S) \wedge \rho_r(R)$ (i.e. Lemma 87) together with the properties of the induced mapping ϕ_μ (Item (1) of Lemma 90) it follows that $\rho_s(S) \wedge \rho_r(R)$ can be written as

$$\rho_s(S) \wedge \rho_r(R) = T(\tilde{T}_1, \dots, \tilde{T}_m)$$

such that for any $i = 1, \dots, m$, we have

$$\tilde{T}_i = \phi_\mu(T_i) = \rho_s(\xi_j) \wedge \rho_r(R^i) \quad \text{or} \quad \tilde{T}_i = \phi_\mu(T_i) = \rho_s(\xi_j).$$

If $T_i = \xi_j$ then it follows from Item (ii) of Lemma 71 that $\xi_j \equiv_n \rho_s(\xi_j)$ since $\mathbf{s}(X) = n$ for any X in $\{X_1, \dots, X_s\}$. Otherwise, if $T_i = \xi_j \wedge R^i$ then it follows from Corollary 104 that $\xi_j \wedge R^i \equiv_n \rho_s(\xi_j) \wedge \rho_r(R^i)$. Therefore,

$$T_i \equiv_n \tilde{T}_i, \quad \text{for } i = 1, \dots, m.$$

Hence,

$$T(T_1, \dots, T_m) \equiv_n T(\tilde{T}_1, \dots, \tilde{T}_m).$$

Thus the desired result follows. \square

13. Proof of the main results

In this section we prove the main results of this paper stated in Section 6. The correctness of the unification and combination operations for arbitrary T_μ -strategies will be proved in Subsection 13.1. The algebraic properties of the unification and combination follow immediately from the correctness result, and will be proved in Subsection 13.2.

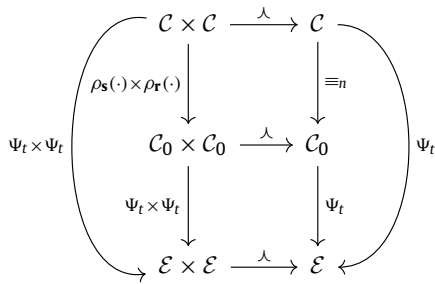
13.1. The correctness of the unification and combination

Now we are ready to prove the first main theorem of this paper regarding the correctness of the unification of T_μ -strategies, Theorem 37. Its proof relies mainly on Proposition 105 and on the correctness of the unification for the fixed-point free fragment of T_μ -strategies stated and proved in Proposition 55.

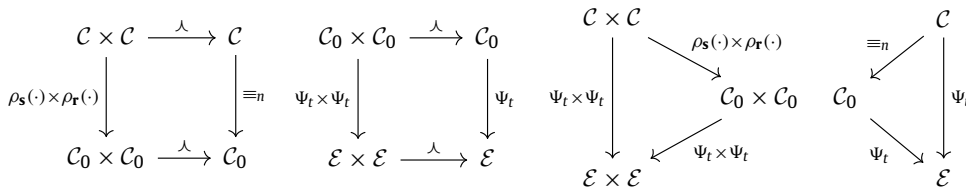
Theorem 37 (Correctness of the unification). *For every term $t \in \mathcal{T}$ and for every T_μ -strategies S and R in \mathcal{C} , we have that*

$$\Psi_t(S \wedge R) = \Psi_t(S) \wedge \Psi_t(R).$$

Proof. Let n be the depth of t . Assume that X_1, \dots, X_s (resp. Y_1, \dots, Y_r) are the (bound) fixed-point variables of S (resp. R) and let \mathbf{s} and \mathbf{r} be iteration mappings with $\mathbf{s}(X_i) = \mathbf{r}(Y_j) = n$, for $i = 1, \dots, s$ and $j = 1, \dots, r$. The proof follows from the commutativity of the following diagram.



Indeed, it follows from Proposition 105, Proposition 55, Item (ii) of Lemma 71 + Item (iii) of Lemma 49, and Item (iii) of Lemma 49, respectively, that the following diagrams commute.



We restate these arguments in the language of equations rather than the language of diagrams. Let

$$\mathbf{S} = \rho_{\mathbf{s}}(S) \quad \text{and} \quad \mathbf{R} = \rho_{\mathbf{r}}(R).$$

We have that

$$S \wedge R \equiv_n \mathbf{S} \wedge \mathbf{R} \quad (\text{Proposition 105})$$

$$\Psi_t(S \wedge R) = \Psi_t(\mathbf{S} \wedge \mathbf{R}). \quad (\text{Item (iii) of Lemma 49})$$

$$\Psi_t(S \wedge R) = \Psi_t(\mathbf{S}) \wedge \Psi_t(\mathbf{R}). \quad (\text{Proposition 55, since } \mathbf{S} \text{ and } \mathbf{R} \text{ are fixed-point free})$$

On the other hand,

$$\mathbf{S} \equiv_n S \quad \text{and} \quad \mathbf{R} \equiv_n R \quad (\text{Item (ii) of Lemma 71})$$

$$\Psi_t(\mathbf{S}) = \Psi_t(S) \quad \text{and} \quad \Psi_t(R) = \Psi_t(\mathbf{R}). \quad (\text{Item (iii) of Lemma 49})$$

Therefore

$$\Psi_t(S \wedge R) = \Psi_t(S) \wedge \Psi_t(R). \quad \square$$

We can now state and prove the second main theorem of this paper on the correctness of the combination of T_μ -strategies. In fact, the correctness of the combination follows from the correctness of the unification that we stated and proved in Theorem 37 above.

Theorem 38 (Correctness of the combination). *For every term $t \in \mathcal{T}$ and for every T_μ -strategies S and R in \mathcal{C} , we have that*

$$\Psi_t(S \curlyvee R) = \Psi_t(S) \curlyvee \Psi_t(R).$$

Proof.

$$\begin{aligned} \Psi_t(S \curlyvee R) &= \Psi_t((S \wedge R) \oplus S \oplus R) && \text{(Def. 35 of } \curlyvee \text{)} \\ &= \Psi_t(\Psi_t(S \wedge R) \oplus \Psi_t(S) \oplus \Psi_t(R)) && \text{(Item (3) of Lemma 49)} \\ &= \Psi_t((\Psi_t(S) \wedge \Psi_t(R)) \oplus \Psi_t(S) \oplus \Psi_t(R)) && \text{(Theorem 37)} \\ &= \Psi(\Psi_t(S) \curlyvee \Psi_t(R)) && \text{(Def. 35 of } \curlyvee \text{)} \\ &= \Psi_t(S) \curlyvee \Psi_t(R). \quad \square && \text{(Item (1a) of Lemma 49 since } \Psi_t(S) \curlyvee \Psi_t(R) \text{ is position-based)} \end{aligned}$$

13.2. The algebraic properties of the unification and combination

Thanks to Theorems 37 and 38, and using mapping Ψ (Definition 46), we can transfer all the algebraic properties of the combination and unification of position-based T_μ -strategies (stated in Propositions 11 and 12) to T_μ -strategies.

Theorem 39. *The quotient set $\mathcal{C} \equiv$ of T_μ -strategies together with the unification operation enjoy the following properties.*

1. The neutral element of the unification upon $\mathcal{C} \equiv$ is $[\text{@}\varepsilon.\square]$.
2. The absorbing element of the unification is $[\text{f}]$.
3. The unification of T_μ -strategies is associative, i.e. $([S_1] \wedge [S_2]) \wedge [S_3] = [S_1] \wedge ([S_2] \wedge [S_3])$, for any $S_1, S_2, S_3 \in \mathcal{C}$.
4. The unification of T_μ -strategies is (non-)commutative if and only if the operation of merging of contexts “ \cdot ” is (non-)commutative.
5. The unification of T_μ -strategies is idempotent if and only if the operation of merging of contexts is idempotent, that is, $[S] \wedge [S] = [S]$ for any $S \in \mathcal{C}$ iff $\tau \cdot \tau = \tau$ for any contexts τ in \mathcal{T}_\square .

Proof. We only prove the associativity property. To prove the associativity of the unification for T_μ -strategies we rely on the associativity of the unification of position-based T_μ -strategies (Proposition 11) together with the property of the function Ψ_t (Theorems 37). Let S_1, S_2 and S_3 be T_μ -strategies in \mathcal{C} . To prove $([S_1] \wedge [S_2]) \wedge [S_3] = [S_1] \wedge ([S_2] \wedge [S_3])$ we shall prove $[(S_1 \wedge S_2) \wedge S_3] = [S_1 \wedge (S_2 \wedge S_3)]$, i.e.

$$S_1 \wedge (S_2 \wedge S_3) \equiv (S_1 \wedge S_2) \wedge S_3.$$

It follows from Item iii.) of Lemma 49 that it suffices to prove that, for any term $t \in \mathcal{T}$, we have that

$$\Psi_t(S_1 \wedge (S_2 \wedge S_3)) = \Psi_t((S_1 \wedge S_2) \wedge S_3).$$

But this follows from an easy computation:

$$\begin{aligned} \Psi_t(S_1 \wedge (S_2 \wedge S_3)) &= \Psi_t(S_1) \wedge \Psi_t(S_2 \wedge S_3) && \text{(Theorem 38)} \\ &= \Psi_t(S_1) \wedge (\Psi_t(S_2) \wedge \Psi_t(S_3)) && \text{(Theorem 38)} \\ &= (\Psi_t(S_1) \wedge \Psi_t(S_2)) \wedge \Psi_t(S_3) && \text{(Proposition 11)} \\ &= \Psi_t(S_1 \wedge S_2) \wedge \Psi_t(S_3) && \text{(Theorem 38)} \\ &= \Psi_t((S_1 \wedge (S_2 \wedge S_3))). \quad \square && \text{(Theorem 38)} \end{aligned}$$

The algebraic properties of the combination of T_μ -strategies follow. They inherit the properties of associativity, (non-)commutativity and idempotence from the position-based T_μ -strategies and the merging of contexts.

Theorem 40. *The quotient set $\mathcal{C} \equiv$ of T_μ -strategies together with the combination operation enjoy the following properties.*

1. The neutral element of the combination upon $\mathcal{C} \equiv$ is $\{\text{f}\}$.
2. The combination of T_μ -strategies is associative, i.e. $([S_1] \curlyvee [S_2]) \curlyvee [S_3] = [S_1] \curlyvee ([S_2] \curlyvee [S_3])$, for any $S_1, S_2, S_3 \in \mathcal{C}$.
3. The combination of T_μ -strategies is (non-)commutative if and only if the operation of merging of contexts “ \cdot ” is (non-)commutative.

4. The combination of \mathbb{T}_μ -strategies is idempotent if and only if the operation of merging of contexts is idempotent, that is, $[S] \vee [S] = [S]$ for any $S \in \mathcal{C}$ iff $\tau \cdot \tau = \tau$ for any contexts τ in \mathcal{T}_\square .

Proof. Very similar to the proof of Theorem 39. \square

The congruence and non-degeneracy of the unification and combination are stated in the two following theorems, respectively.

Theorem 41 (Congruence and non-degeneracy of the unification). *The following holds.*

1. The unification of \mathbb{T}_μ -strategies is a congruence, that is, for any \mathbb{T}_μ -strategies S_1, S_2, S in \mathcal{C} , we have that:

$$\text{If } S_1 \equiv S_2 \quad \text{then} \quad S_1 \wedge S \equiv S_2 \wedge S \text{ and } S \wedge S_1 \equiv S \wedge S_2.$$

2. The unification is non-degenerate, that is, for any \mathbb{T}_μ -strategies $[S]$ and $[S']$ in $\mathcal{C} \equiv$, we have that

$$[S] \wedge [S'] = [\text{f}] \quad \text{iff} \quad [S] = [\text{f}] \text{ or } [S'] = [\text{f}].$$

Proof. We only prove the first Item. On the one hand, it follows from Theorem 38 that

$$\Psi_t(S_1 \wedge S) = \Psi_t(S_1) \wedge \Psi_t(S).$$

On the other hand, since $S_1 \equiv S_2$, it follows from Item iii.) of Lemma 49 that

$$\Psi_t(S_1) = \Psi_t(S_2).$$

Hence we get

$$\begin{aligned} \Psi_t(S_1 \wedge S) &= \Psi_t(S_2) \wedge \Psi_t(S) \\ &= \Psi_t(S_2 \wedge S). \end{aligned} \tag{Theorem 38}$$

Again, from Item iii.) of Lemma 49, we get

$$S_1 \wedge S \equiv S_2 \wedge S.$$

The proof of the remaining claims is similar. \square

Theorem 42 (Congruence and non-degeneracy of the combination). *The following holds.*

1. The combination of \mathbb{T}_μ -strategies is a congruence, that is, for any \mathbb{T}_μ -strategies S_1, S_2, S in \mathcal{C} , we have that:

$$\text{If } S_1 \equiv S_2 \quad \text{then} \quad S_1 \vee S \equiv S_2 \vee S \text{ and } S \vee S_1 \equiv S \vee S_2.$$

2. The combination is non-degenerate, that is, for any \mathbb{T}_μ -strategies $[S]$ and $[S']$ in $\mathcal{C} \equiv$, we have that

$$[S] \vee [S'] = [\text{f}] \quad \text{iff} \quad [S] = [\text{f}] \text{ and } [S'] = [\text{f}].$$

Proof. Similar to the proof of Theorem 41. \square

14. Conclusion and future work

We addressed the problem of extension and combination of proofs encountered in the field of computer aided asymptotic model derivation. We introduced a class of rewriting strategies on which the operations of unification and combination were defined and proved correct. The design of this class is inspired by the μ -calculus formalism [8] together with practical needs emerging from asymptotic model derivation.

The \mathbb{T}_μ -strategies are indeed modular in the sense that they navigate in the tree without modifying it, then they insert contexts. This makes our formalism flexible since it allows one to modify and enrich the navigation part and/or the insertion part without disturbing the set-up. Besides, the ideas and techniques behind the unification and combination of the navigation part, namely the unification of fixed-point \mathbb{T}_μ -strategies or recursion, are generic and could be used in several applications beyond rewriting strategies as far as they incorporate recursion. Although the \mathbb{T}_μ -strategies can be viewed as a finite algebraic representation of infinite trees [29,30], our technique of unification and combination involving μ -terms and their unfolding is new. We envision consequences of these results on the study of the syntactic (or modulo a theory)

unification and the pattern-matching of infinite trees once they are expressed as μ -terms in the same way we expressed the T_μ -strategies. It follows that a rewriting language that transforms algebraic infinite trees and incorporates the least and greatest fixed-point operators could be elaborated.

We implemented the unification procedure within a user specification language of mathematical expressions, proofs and extensions and their combination for asymptotic models. We noticed that the size of the resulting T_μ -strategies is big, and the good news is that they contain many redundant and inaccessible parts in the same way a graph or a transition system contains equivalent sub-parts, and a program contains inaccessible code. This raises the question of the minimization or reduction of T_μ -strategies which remains open. We managed recently to design an algorithm that decides whether two T_μ -strategies are semantically equivalent by looking at their structure. This is known as the word problem in other fields, e.g. in universal algebras [31,32]. Proving the correctness of this algorithm is under way. This semantic equivalence algorithm will probably be useful for the minimization of T_μ -strategies since one can factorize the equivalent sub-parts. This technique is similar to the techniques of reduction of Petri nets and transition systems and event structures by the bisimulation equivalence relation [33–36], and to the reduction of graphs by internal isomorphisms, or automorphism [37,38].

Since the class of T_μ -strategies can be viewed as μ -calculus in the sense that it supplements elementary strategies with the fixed-point operator, one can pose the hierarchy problem for it. The hierarchy problem asks whether, for any $n \geq 1$, there exists a T_μ -strategy with n bound fixed-point variables, such that no T_μ -strategy with less than n bound fixed-point variables is equivalent to it. The hierarchy problem was posed for many μ -calculi [39,40] and it might help in reducing the size of the T_μ -strategies, namely in minimizing the number of bound fixed-point variables.

Declaration of competing interest

This manuscript has not been submitted to, nor is under review at, another journal or other publishing venue.

The authors have no affiliation with any organization with a direct or indirect financial interest in the subject matter discussed in the manuscript

Appendix: proofs of lemmas

A. Proofs for Section 9

Fact 52. Let I', J', J'' be sets. Then, $(I' \cap J'') \cup (I' \setminus (J' \cup J'')) = I' \setminus J'$.

Proof.

$$\begin{aligned}
 (I' \cap J'') \cup (I' \setminus (J' \cup J'')) &= \{x \mid x \in I' \text{ and } x \in J''\} \cup \{x \mid x \in I' \text{ and } x \notin J' \cup J''\} \\
 &= \{x \mid x \in I' \text{ and } x \in J''\} \cup \{x \mid x \in I' \text{ and } x \notin J' \text{ and } x \notin J''\} \\
 &= \{x \mid (x \in I' \text{ and } x \in J'') \text{ or } (x \in I' \text{ and } x \notin J' \text{ and } x \notin J'')\} \\
 &= \{x \mid x \in I' \text{ and } (x \in J'' \text{ or } x \notin J' \text{ or } x \notin J'')\} \\
 &= \{x \mid x \in I' \text{ and } x \notin J'\} \\
 &= I' \setminus J'. \quad \square
 \end{aligned}$$

B. Proofs for Section 10

Lemma 71. Let S be a T_μ -strategy with (bound) fixed-point variables X_1, \dots, X_s and let $\mathbf{s} : \{X_1, \dots, X_s\} \rightarrow \mathbb{N}$ be an iteration mapping.

(i) If S is a fixed-point T_μ -strategy, say $\mu X.S'(X)$ with $X \in \{X_1, \dots, X_s\}$, then there exists a fixed-point free T_μ -strategy $\tilde{S}(X^1, \dots, X^m)$ with $m \geq 1$, and T_μ -strategies $S_1, \dots, S_{m-1}, S_m(X)$ such that for any $n \geq 1$,

$$\mu^n X.S'(X) = \tilde{S}(S_1, \dots, S_{m-1}, S_m(\mu^{n-1} X.S'(X))) \quad (50)$$

$$\rho_{\mathbf{s}}(\mu X.S'(X)) = \tilde{S}(\rho_{\mathbf{s}}(S_1), \dots, \rho_{\mathbf{s}}(S_{m-1}), \rho_{\mathbf{s}'}(S_m(\mu X.S'(X)))) \quad (51)$$

where \mathbf{s}' is the iteration mapping defined on $\{X_1, \dots, X_s\}$ by $\mathbf{s}'(X) = \mathbf{s}(X) - 1$ and $\mathbf{s}'(X') = \mathbf{s}(X')$ for $X' \neq X$.

(ii) If $\mathbf{m} = \min\{\mathbf{s}(X_1), \dots, \mathbf{s}(X_s)\}$, then $S \equiv_{\mathbf{m}} \rho_{\mathbf{s}}(S)$.

Proof. For Item (i), indeed $S'(X)$ can be written in terms of its immediate fixed-point sub- T_μ -strategies where X appears free in one of them since X appears once in $S'(X)$. That is, there exists a fixed-point free T_μ -strategy $\tilde{S}(X^1, \dots, X^m)$ with $m \geq 1$, and (fixed-point) T_μ -strategies $S_1, \dots, S_{m-1}, S_m(X)$ such that $S'(X)$ can be written as $S'(X) =$

$\tilde{S}(S_1, \dots, S_{m-1}, S_m(X))$. To show Eq. (50) we rely on the fact that $\tilde{S}(X^1, \dots, X^m)$ is fixed-point free and on Definition 66 of unfolding together with a simple structural induction on $\tilde{S}(X^1, \dots, X^m)$. The computations are straightforward and we don't make them. To show Eq. (51), let $\tilde{\mathbf{s}}$ be the iteration mapping defined on $\{X_1, \dots, X_s\}$ as the restriction of \mathbf{s} on $\{X_1, \dots, X_s\} \setminus \{X\}$. Since $\tilde{S}(X^1, \dots, X^m)$ is fixed-point free, then by the Definition 66 of unfolding and making use of Eq. (50) we get

$$\begin{aligned}
 \rho_s(\mu X.S'(X)) &= \rho_s(\mu X.\tilde{S}(S_1, \dots, S_{m-1}, S_m(X))) \\
 &= \mu^{\mathbf{s}(X)} X. \rho_s(\tilde{S}(S_1, \dots, S_{m-1}, S_m(X))) \\
 &= \mu^{\mathbf{s}(X)} X. \tilde{S}(\rho_s(S_1), \dots, \rho_s(S_{m-1}), \rho_s(S_m(X))) \\
 &= \mu^{\mathbf{s}(X)} X. \tilde{S}(\rho_s(S_1), \dots, \rho_s(S_{m-1}), \rho_{\tilde{\mathbf{s}}}(S_m(X))) \\
 &= \tilde{S}(\rho_s(S_1), \dots, \rho_s(S_{m-1}), \rho_{\tilde{\mathbf{s}}}(\mu^{\mathbf{s}(X)-1} X.S'(X))) \quad (\text{By Eq. (50)}) \\
 &= \tilde{S}(\rho_s(S_1), \dots, \rho_s(S_{m-1}), \rho_{\mathbf{s}'}(S_m(\mu X.S'(X)))).
 \end{aligned}$$

To show the Item (ii) we next generalize the idea that a T_μ -strategy $\mu^n X.S'(X)$ could be written as $S'(S'(\dots(f)))$ where the number of jumps between its root and f is at least n , as well as the fact that $\mu X.S'(X)$ could be written as $S'(S'(\dots(\mu X.S'(X))))$. Technically, we rely on Eq. (5) and we shall show that there exist T_μ -strategies ξ_1, \dots, ξ_m and a fixed-point free T_μ -strategy $T(X^1, \dots, X^m)$ and an unraveling $\mathcal{U}(\cdot)$ of S , such that $\mathcal{U}(S)$ and $\rho(S)$ can be written as

$$\mathcal{U}(S) = T(\xi_1, \dots, \xi_m) \quad (52)$$

$$\rho_s(S) = T(f, \dots, f) \quad (53)$$

such that

$$\min \{ \Pi_{X^i}(T(X^1, \dots, X^m)) \mid i = 1, \dots, m \} \geq \mathbf{m}. \quad (54)$$

We make a double induction: the outer one being on $\mathfrak{S}(\mathbf{s}) \stackrel{\text{def}}{=} (\mathbf{s}(X_1), \dots, \mathbf{s}(X_s))$ with the lexicographic order, and the inner one being on the number of nested fixed-point sub- T_μ -strategies of S , i.e. on $\mathbf{h}(S)$ the star height of S . The outer base case when $\mathfrak{S}(\mathbf{s}) = (0, \dots, 0)$ holds trivially since in this case the set of terms of depth 0 is empty. For the outer induction step, we assume that the claim holds for \mathbf{s}' and we shall prove it for any \mathbf{s} with $\mathfrak{S}(\mathbf{s}) = \mathfrak{S}(\mathbf{s}') + (b_1, \dots, b_s)$ where there is $i \in \{1, \dots, s\}$ such that $b_i = 1$ and $b_j = 0$ for any $i \neq j$. We make an inner induction on $\mathbf{h}(S)$. The inner base case $\mathbf{h}(S) = 0$ holds trivially since in this case S is fixed-point free because the unfolding of S is S . For the inner induction step we assume that the claim holds for a T_μ -strategy S' and we shall prove it for any S with $\mathbf{h}(S) = \mathbf{h}(S') + 1$. We only discuss the case when S is a fixed-point T_μ -strategy, say $S = \mu X.S'(X)$, since the case when S is of the form $S = \tilde{S}(\xi_1, \dots, \xi_k)$, for a fixed-point free T_μ -strategy $\tilde{S}(X^1, \dots, X^k)$ and a fixed-point T_μ -strategies ξ_1, \dots, ξ_k with $k \geq 1$, does not provide difficulties since it is easily reducible to the case under discussion, because $\rho_s(\tilde{S}(\xi_1, \dots, \xi_k)) = \tilde{S}(\rho_s(\xi_1), \dots, \rho_s(\xi_k))$. We rely on the fact that $S'(X)$ can be written as $S'(X) = \tilde{S}(S_1, \dots, S_{m-1}, S_m(X))$, for fixed-point T_μ -strategies $S_1, \dots, S_{m-1}, S_m(X)$ in $\tilde{\Phi}_\mu(S)$, $\tilde{S}(X^1, \dots, X^m)$ being a fixed-point free T_μ -strategy. From Eq. (50) above we have that $\rho_s(S) = \rho_s(\mu X.S'(X)) = \tilde{S}(\rho_s(S_1), \dots, \rho_s(S_{m-1}), \rho_{\mathbf{s}'}(S_m(\mu X.S'(X))))$, where \mathbf{s}' is the iteration mapping defined on $\{X_1, \dots, X_s\}$ by $\mathbf{s}'(X) = \mathbf{s}(X) - 1$ and $\mathbf{s}'(X') = \mathbf{s}(X')$ for $X' \neq X$.

Therefore, we have that

$$\begin{aligned}
 S &= \mu X.\tilde{S}(S_1, \dots, S_{m-1}, S_m(X)) \\
 \mathcal{U}(S) &\stackrel{\text{def}}{=} \tilde{S}(S_1, \dots, S_{m-1}, S_m(\mu X.S'(X))) \\
 \rho_s(S) &= \tilde{S}(\rho_s(S_1), \dots, \rho_s(S_{m-1}), \rho_{\mathbf{s}'}(S_m(\mu X.S'(X)))).
 \end{aligned}$$

On the one hand, then it follows from inner induction hypothesis that the claims (52), (53) and (54) hold for S_i with respect to $\rho_s(S_i)$ for $i = 1, \dots, m-1$, since $\mathbf{h}(S_i) < \mathbf{h}(S)$. On the other hand, since $\mathbf{s}'(X) = \mathbf{s}(X) - 1$ and $\mathbf{s}'(X') = X'$ for any $X' \neq X$, then it follows from the outer induction hypothesis that there is a fixed-point free T_μ -strategy $\tilde{S}_k(Y^1, \dots, Y^k)$ and T_μ -strategies ζ_1, \dots, ζ_k such that

$$\mathcal{U}(\mu X.S'(X)) = \tilde{S}_m(\zeta_1, \dots, \zeta_k) \quad (55)$$

$$\rho_{\mathbf{s}'}(S_m(\mu X.S'(X))) = \tilde{S}_m(f, \dots, f) \quad (56)$$

such that

$$\min \{ \Pi_{Y^i}(\tilde{S}_m(Y^1, \dots, Y^k)) \mid i = 1, \dots, k \} \geq \mathbf{m}' \quad (57)$$

where $\mathbf{m}' = \min \{ \mathbf{s}'(X_i) \mid i = 1, \dots, s \}$. If $\mathbf{m} > \mathbf{s}(X)$, then we are done since in this case $\mathbf{m}' = \mathbf{m}$. Otherwise, if $\mathbf{m} = \mathbf{s}(X)$ then $\mathbf{m}' = \mathbf{s}(X) - 1$. But since $\mu X.S'(X)$ is monotonic then $\Pi_X(S'(X)) \geq 1$. That is, there is at least one jump between the root of $S'(X)$ and X . This jump is either between the root of $\tilde{S}(S_1, \dots, S_{m-1}, X^m)$ and X^m , i.e. $\Pi_{X^m}(\tilde{S}(S_1, \dots, S_{m-1}, X^m)) \geq 1$ and in this case we are done; or between the root of $S_m(X)$ and X , i.e. $\Pi_X(S_m(X)) \geq 1$ and in this case we can assume without loss of generality that X is an immediate sub- \mathbb{T}_μ -strategy of $S_m(X)$, say $\mu X.S'(X) = \zeta_k$, and thus we get the desired result since $\Pi_{X^m}(T(X^1, \dots, X^m)) \leq 1 + \Pi_{Y^k}(T(X^1, \dots, S_m(Y^k)))$. \square

Lemma 73 (Composition Lemma). *Let S and R be \mathbb{T}_μ -strategies. Assume that there are fixed-point free \mathbb{T}_μ -strategies $S'(X_1, \dots, X_k)$ and $R'(Y_1, \dots, Y_l)$, where $k \geq 1$ and $l \geq 1$, and \mathbb{T}_μ -strategies ξ_1, \dots, ξ_k where $\xi_i \in \Phi(S)$, and \mathbb{T}_μ -strategies ζ_1, \dots, ζ_l where $\zeta_i \in \Phi(R)$, such that S and R can be written as:*

$$S = S'(\xi_1, \dots, \xi_k) \quad R = R'(\zeta_1, \dots, \zeta_l).$$

Then, there is a fixed-point free \mathbb{T}_μ -strategy $T(Z_1, \dots, Z_m)$ and \mathbb{T}_μ -strategies T_1, \dots, T_m , where $m \geq 1$, such that

$$S \wedge R = T(T_1, \dots, T_m)$$

where for any $i = 1, \dots, m$, there is an alternative between the two following choices.

- (a) *There are $j \in \{1, \dots, k\}$, a \mathbb{T}_μ -strategy $R^i(Y^1, \dots, Y^{l'})$ that is a sub- \mathbb{T}_μ -strategy of $R'(Y_1, \dots, Y_l)$ with $l' \leq l$, and a set of \mathbb{T}_μ -strategies $\{\zeta^1, \dots, \zeta^{l'}\} \subseteq \{\zeta_1, \dots, \zeta_l\}$ such that*

$$T_i = \xi_j \wedge R^i(\zeta^1, \dots, \zeta^{l'}) \quad \text{or} \quad T_i = \xi_j. \quad (58)$$

- (b) *There are $j \in \{1, \dots, l\}$, a \mathbb{T}_μ -strategy $S^i(X^1, \dots, X^{k'})$ that is a sub- \mathbb{T}_μ -strategy of $S'(X_1, \dots, X_k)$ with $k' \leq k$, and a set of \mathbb{T}_μ -strategies $\{\xi^1, \dots, \xi^{k'}\} \subseteq \{\xi_1, \dots, \xi_k\}$ such that*

$$T_i = S^i(\xi^1, \dots, \xi^{k'}) \wedge \zeta_j \quad \text{or} \quad T_i = \zeta_j. \quad (59)$$

Proof. The proof is by structural induction on the fixed-point free \mathbb{T}_μ -strategies $S'(X^1, \dots, X^k)$ and $R'(Y^1, \dots, Y^l)$. The base case is when $k = l = 1$ and $S'(X_1) = X_1$ and $R'(Y_1) = Y_1$. In this case we have $S'(\xi_1) = \xi_1$ and $R'(\zeta_1) = \zeta_1$. The result is obvious since $S \wedge R = \xi_1 \wedge \zeta_1$. For the induction step assume that the claim holds for some \mathbb{T}_μ -strategies S'' and R'' , and we shall show it for any S and R such that either (i) S'' is an immediate sub- \mathbb{T}_μ -strategy of S and $R'' = R$, or (ii) $S = S''$ and R'' is an immediate sub- \mathbb{T}_μ -strategy of R , or (iii) S'' (resp. R'') is an immediate sub- \mathbb{T}_μ -strategy of S (resp. R). The proof is not hard and involves straightforward computations. We only elucidate the case when S is a pattern-matching and R is arbitrary, and the case when both S and R are $\text{Most } \mathbb{T}_\mu$ -strategies. The remaining cases fall into one of these two.

- If $S'(X_1, \dots, X_k) = u$; $S''(X^1, \dots, X^k)$ and R is arbitrary, then in this case

$$\begin{aligned} S \wedge R &= S'(\xi_1, \dots, \xi_k) \wedge R'(\zeta_1, \dots, \zeta_l) \\ &= u; (S''(\xi_1, \dots, \xi_k) \wedge R'(\zeta_1, \dots, \zeta_l)). \end{aligned}$$

From the induction hypothesis it follows that there is a fixed-point free \mathbb{T}_μ -strategy $T'(Z_1, \dots, Z_m)$ and \mathbb{T}_μ -strategies T'_1, \dots, T'_m with the right properties (58) and (59) such that $S''(\xi_1, \dots, \xi_k) \wedge R'(\zeta_1, \dots, \zeta_l) = T'(T'_1, \dots, T'_m)$. By letting $T(Z_1, \dots, Z_m) = u; T'(Z_1, \dots, Z_m)$ we get the desired result.

- If $S'(X_1, \dots, X_k) = \text{Most}(S''(X_1, \dots, X_k))$ and $R(X_1, \dots, X_k) = \text{Most}(R''(X_1, \dots, X_k))$, then

$$\begin{aligned} S \wedge R &= S'(\xi_1, \dots, \xi_k) \wedge R'(\zeta_1, \dots, \zeta_l) \\ &= \text{Most}(S''(\xi_1, \dots, \xi_k)) \wedge \text{Most}(R''(\zeta_1, \dots, \zeta_l)) \\ &= \text{If}(\text{Most}(S''(\xi_1, \dots, \xi_k)) \& \text{Most}(R''(\zeta_1, \dots, \zeta_l))) \\ &\quad \text{Then } \text{Most}((S''(\xi_1, \dots, \xi_k) \wedge R''(\zeta_1, \dots, \zeta_l)) \oplus S''(\xi_1, \dots, \xi_k) \oplus R''(\zeta_1, \dots, \zeta_l)). \end{aligned} \quad (\text{Rule 7a})$$

On the one hand, it follows from the induction hypothesis that there is a fixed-point free \mathbb{T}_μ -strategy $T'(Z'_1, \dots, Z'_m)$ and \mathbb{T}_μ -strategies T'_1, \dots, T'_m with the right properties (58) and (59) such that $S''(\xi_1, \dots, \xi_k) \wedge R''(\zeta_1, \dots, \zeta_l) = T'(T'_1, \dots, T'_m)$. On the other hand, let $T(Z_1^1, \dots, Z_k^1, Z_1^2, \dots, Z_l^2, Z_1^3, \dots, Z_m^3, Z_1^4, \dots, Z_l^4)$ the fixed-point free \mathbb{T}_μ -strategy with free variables $Z_1^1, \dots, Z_k^1, Z_1^2, \dots, Z_l^2, Z_1^3, \dots, Z_m^3, Z_1^4, \dots, Z_l^4$ defined as follows:

$$\begin{aligned}
T(Z_1^1, \dots, Z_k^1, Z_1^2, \dots, Z_l^2, Z_1', \dots, Z_m', Z_1^3, \dots, Z_k^3, Z_1^4, \dots, Z_l^4) = \\
\text{If}(\text{Most}(S''(Z_1^1, \dots, Z_k^1)) \& \text{Most}(R''(Z_1^2, \dots, Z_l^2))) \\
\text{Then Most}(T'(Z_1', \dots, Z_m') \oplus S''(Z_1^3, \dots, Z_k^3) \oplus R''(Z_1^4, \dots, Z_l^4))
\end{aligned}$$

Let $T_i^1, T_i^3, T_j^2, T_j^4$ be the T_μ -strategies defined by

$$\begin{aligned}
T_i^1 = T_i^3 = \xi_i, \quad & \text{for } i = 1, \dots, k \\
T_j^2 = T_j^4 = \zeta_j, \quad & \text{for } j = 1, \dots, l
\end{aligned}$$

Therefore, $S \wedge R$ can be written as

$$S \wedge R = T(T_1^1, \dots, T_k^1, T_1^2, \dots, T_l^2, T_1', \dots, T_m', T_1^3, \dots, T_k^3, T_1^4, \dots, T_l^4)$$

which satisfies the properties (58) and (59). \square

C. Proofs for Section 11

Lemma 76. *There exist fixed-point free T_μ -strategies $T_1, \dots, T_m, T(Z_1, \dots, Z_m)$, where each Z_i is a free fixed-point variable and $m \geq 1$, such that $\rho_{s_1}(S) \wedge \rho_{r_1}(R)$ and $\rho_{s_2}(S) \wedge \rho_{r_2}(R)$ can be written as*

$$\begin{aligned}
\rho_{s_1}(S) \wedge \rho_{r_1}(R) &= T(T_1, \dots, T_m) \\
\rho_{s_2}(S) \wedge \rho_{r_2}(R) &= T(f, \dots, f).
\end{aligned}$$

Proof. The proof is by induction on $\Gamma(S, R, \mathbf{s}_1, \mathbf{s}_2, \mathbf{r}_1, \mathbf{r}_2) \stackrel{\text{def}}{=} (\delta(\rho_{s_1}(S)), \delta(\rho_{s_2}(S)), \delta(\rho_{r_1}(R)), \delta(\rho_{r_2}(R)))$. The base case is when $\Gamma(S, R, \mathbf{s}_1, \mathbf{s}_2, \mathbf{r}_1, \mathbf{r}_2) = (0, 0, 0, 0)$, i.e. S and R are either f or $@\varepsilon.\tau$. This case is trivial. For the induction step, assume that the claim holds for T_μ -strategies \tilde{S}, \tilde{R} and iteration mappings $\tilde{\mathbf{s}}_1, \tilde{\mathbf{s}}_2, \tilde{\mathbf{r}}_1, \tilde{\mathbf{r}}_2$, and we shall prove it for any T_μ -strategies S, R and iteration mappings $\mathbf{s}_1, \mathbf{s}_2, \mathbf{r}_1, \mathbf{r}_2$ where $\Gamma(S, R, \mathbf{s}_1, \mathbf{s}_2, \mathbf{r}_1, \mathbf{r}_2) = \Gamma(\tilde{S}, \tilde{R}, \tilde{\mathbf{s}}_1, \tilde{\mathbf{s}}_2, \tilde{\mathbf{r}}_1, \tilde{\mathbf{r}}_2) + (1, 1, 0, 0)$, or $\Gamma(S, R, \mathbf{s}_1, \mathbf{s}_2, \mathbf{r}_1, \mathbf{r}_2) = \Gamma(\tilde{S}, \tilde{R}, \tilde{\mathbf{s}}_1, \tilde{\mathbf{s}}_2, \tilde{\mathbf{r}}_1, \tilde{\mathbf{r}}_2) + (0, 0, 1, 1)$, or $\Gamma(S, R, \mathbf{s}_1, \mathbf{s}_2, \mathbf{r}_1, \mathbf{r}_2) = \Gamma(\tilde{S}, \tilde{R}, \tilde{\mathbf{s}}_1, \tilde{\mathbf{s}}_2, \tilde{\mathbf{r}}_1, \tilde{\mathbf{r}}_2) + (1, 1, 1, 1)$. We only discuss the cases when $\delta(\rho_{s_2}(S)) \geq 1$ (and hence $\delta(\rho_{s_1}(S)) \geq 1$ since $\mathbf{s}_1 \geq \mathbf{s}_2$) and $\delta(\rho_{r_2}(R)) \geq 1$ (and hence $\delta(\rho_{r_1}(R)) \geq 1$ since $\mathbf{r}_1 \geq \mathbf{r}_2$), because the cases when $\delta(\rho_{s_2}(S)) = 0$ or $\delta(\rho_{s_1}(S)) = 0$ (but not both) are just a particular case of the general case that follows, and can be handled similarly using the composition Lemma 73. We distinguish two cases depending on S and R .

First case. If neither S nor R is a fixed-point T_μ -strategy, then there exist fixed-point free T_μ -strategies $S'(X^1, \dots, X^k)$ and $R'(Y^1, \dots, Y^l)$ and T_μ -strategies S_1, \dots, S_k and R_1, \dots, R_l , where each S_i (resp. R_i) is an immediate sub- T_μ -strategy of S (resp. R), i.e. $\delta(S'(X^1, \dots, X^k)) = 1$ (resp. $\delta(R'(Y^1, \dots, Y^l)) = 1$), such that S and R can be written as:

$$\begin{aligned}
S &= S'(S_1, \dots, S_k) \\
R &= R'(R_1, \dots, R_l).
\end{aligned}$$

Hence,

$$\begin{cases} \rho_{s_1}(S) = S'(\rho_{s_1}(S_1), \dots, \rho_{s_1}(S_k)) \\ \rho_{r_1}(R) = R'(\rho_{r_1}(R_1), \dots, \rho_{r_1}(R_l)), \end{cases} \quad \text{and} \quad \begin{cases} \rho_{s_2}(S) = S'(\rho_{s_2}(S_1), \dots, \rho_{s_2}(S_k)) \\ \rho_{r_2}(R) = R'(\rho_{r_2}(R_1), \dots, \rho_{r_2}(R_l)). \end{cases} \quad (60)$$

It follows from the composition Lemma 73 that there exist a fixed-point free T_μ -strategy $T(Z_1, \dots, Z_m)$, and T_μ -strategies T_1^1, \dots, T_m^1 and T_1^2, \dots, T_m^2 such that

$$\begin{aligned}
\rho_{s_1}(S) \wedge \rho_{r_1}(R) &= T(T_1^1, \dots, T_m^1) \\
\rho_{s_2}(S) \wedge \rho_{s_2}(S) &= T(T_1^2, \dots, T_m^2),
\end{aligned}$$

where the item (a) or (b) holds. We only discuss the first possibility (since the second is symmetric) according to which, for any $i = 1, \dots, m$ there is $j \in \{1, \dots, k\}$, and a T_μ -strategy $R^i(Y_1, \dots, Y_{l'})$ that is a sub- T_μ -strategy of $R'(Y_1, \dots, Y_l)$ with $l' \leq l$, and a set of T_μ -strategies $\{R_1^1, \dots, R_{l'}^1\} \subseteq \{R_1, \dots, R_l\}$ such that

$$T_i^1 = \rho_{s_1}(S_j) \wedge R^i(R_1^1, \dots, R_{l'}^1) \quad \text{or} \quad T_i^1 = \rho_{s_1}(S_j) \quad (61)$$

$$T_i^2 = \rho_{s_1}(S_j) \wedge R^i(R_1^2, \dots, R_{l'}^2) \quad \text{or} \quad T_i^2 = \rho_{s_2}(S_j). \quad (62)$$

If $T_i^1 = \rho_{s_1}(S_j)$ and hence $T_i^2 = \rho_{s_2}(S_j)$, then the claim follows from Remark 72. Otherwise, the claim follows from the induction hypothesis.

Second case. If S is a fixed-point T_μ -strategy, say $\mu X.\tilde{S}(X)$, then we distinguish two cases. If $\mathbf{s}_2(X) = 0$ then the claim holds trivially since in this case $\rho_{\mathbf{s}_2}(S) = \mathbf{f}$. If $\mathbf{s}_2(X) > 0$ and therefore $\mathbf{s}_1(X) > 0$ since $\mathbf{s}_1 \geq \mathbf{s}_2$, then it follows from Eq. (51) of Lemma 71, that there exists a fixed-point free T_μ -strategy $S'(X^1, \dots, X^k)$ and T_μ -strategies $S_1, \dots, S_{k-1}, S_k(X)$, where $\delta(S'(X^1, \dots, X^k)) = 0$, such that $\rho_{\mathbf{s}_1}(\mu X.\tilde{S}(X))$ and $\rho_{\mathbf{s}_2}(\mu X.\tilde{S}(X))$ can be written as

$$\begin{aligned}\rho_{\mathbf{s}_1}(\mu X.\tilde{S}(X)) &= S'(\rho_{\mathbf{s}_1}(S_1), \dots, \rho_{\mathbf{s}_1}(S_{k-1}), \rho_{\mathbf{s}'_1}(S_k(\mu X.\tilde{S}(X)))) \\ \rho_{\mathbf{s}_2}(\mu X.\tilde{S}(X)) &= S'(\rho_{\mathbf{s}_2}(S_1), \dots, \rho_{\mathbf{s}_2}(S_{k-1}), \rho_{\mathbf{s}'_2}(S_k(\mu X.\tilde{S}(X))))\end{aligned}$$

where $\mathbf{s}'_v(X) = \mathbf{s}'_v(X) - 1$ and $\mathbf{s}'_v(X') = \mathbf{s}_v(X')$ for $X' \neq X$, for $v = 1, 2$. Thus the reasoning is very similar to the one made in the first case, more precisely it is done by taking Eq. (60) in which we replace $\rho_{\mathbf{s}_v}(S_k)$ by $\rho_{\mathbf{s}'_v}(S_k(\mu X.\tilde{S}(X)))$, for $v = 1, 2$. Thus the induction hypothesis can be applied as well. \square

Lemma 87. Let S and R be T_μ -strategies with bound fixed-point variables $\text{Bound}(S) = \{X_1, \dots, X_s\}$ and $\text{Bound}(R) = \{Y_1, \dots, Y_r\}$. Let $\mathcal{M} \in \mathfrak{M}(S, R)$ be a memory with respect to S and R . Let $\mathbf{s} : \{X_1, \dots, X_s\} \rightarrow \mathbb{N}$ and $\mathbf{r} : \{Y_1, \dots, Y_r\} \rightarrow \mathbb{N}$ be iteration mappings. There is a (C, C_0) -quasi-simulation \mathfrak{S} between $\mathcal{NF}(\langle S, R, \mathcal{M} \rangle)$ and $\mathcal{NF}(\langle \rho_{\mathbf{s}}(S), \rho_{\mathbf{r}}(R), \emptyset \rangle)$. In particular, the following diagram commutes.

$$\begin{array}{ccc} C \times C & \xrightarrow{\lambda} & C \\ \rho_{\mathbf{s}}(\cdot) \times \rho_{\mathbf{r}}(\cdot) \downarrow & & \downarrow \mathfrak{S} \\ C_0 \times C_0 & \xrightarrow{\lambda} & C_0 \end{array}$$

Proof. We make of use of Lemma 73. The proof is by structural induction on $\rho_{\mathbf{s}}(S)$ and $\rho_{\mathbf{r}}(R)$, according to which the (C, C_0) -simulation \mathfrak{S} will be inductively constructed. The base case holds trivially. For the induction step we assume that the claim holds for T_μ -strategies $\rho_{\mathbf{s}''}(S'')$ and $\rho_{\mathbf{r}''}(R'')$ and we shall prove for any T_μ -strategies $\rho_{\mathbf{s}}(S)$ and $\rho_{\mathbf{r}}(R)$ such that either (i) $\rho_{\mathbf{s}''}(S'')$ is an immediate sub- T_μ -strategy of $\rho_{\mathbf{s}}(S)$ and $R'' = R$ and $\mathbf{r}'' = \mathbf{r}$, or (ii) $\rho_{\mathbf{r}''}(R'')$ is an immediate sub- T_μ -strategy of $\rho_{\mathbf{r}}(R)$ and $S'' = S$ and $\mathbf{s}'' = \mathbf{s}$, or (iii) $\rho_{\mathbf{s}''}(S'')$ (resp. $\rho_{\mathbf{r}''}(R'')$) is an immediate sub- T_μ -strategy of $\rho_{\mathbf{s}}(S)$ (resp. $\rho_{\mathbf{r}}(R)$). We distinguish three cases depending on S and R :

1. If S and R are fixed-point free, then this case is trivial since $\rho_{\mathbf{s}}(S) = S$ and $\rho_{\mathbf{r}}(R) = R$.
2. If S and R are of the form $S = S'(S_1, \dots, S_k)$ and $R = R'(R_1, \dots, R_l)$ for fixed-point free T_μ -strategies $S'(X_1, \dots, X_k)$ and $R'(Y_1, \dots, Y_l)$, i.e. $S = u$; S' or $S = S' \oplus S''$ or $S = \text{Most}(S')$ or $S = \text{If } S' \text{ Then } S''$ or $S = \bigwedge_{i=1,k} @p_i.S_i$ and similarly for R , then the result follows immediately from Lemma 73 since in these cases $\rho_{\mathbf{s}}(S'(S_1, \dots, S_k)) = S'(\rho_{\mathbf{s}}(S_1), \dots, \rho_{\mathbf{s}}(S_k))$ and $\rho_{\mathbf{r}}(R'(R_1, \dots, R_l)) = R'(\rho_{\mathbf{r}}(R_1), \dots, \rho_{\mathbf{r}}(R_l))$, since the induction hypothesis can be applied on each $\rho_{\mathbf{r}}(S_i)$ and $\rho_{\mathbf{r}}(R_j)$, for $i \in \{1, \dots, k\}$ and $j \in \{1, \dots, l\}$.
3. If S is fixed-point $S = \mu X.S'(X)$, with $X \in \{X_1, \dots, X_s\}$, then S is replaced by $S'(S)$ in the unification, and thus we reduce this case to the case 2 above as follows:

$$\langle S, R, \mathcal{M} \rangle = \langle \mu X.S'(X), R, \mathcal{M} \rangle \rightarrow \begin{cases} \mu Z.\langle S'(S), R, \mathcal{M}' \rangle & \text{if } (S, R, \cdot) \notin \mathcal{M} \\ Z & \text{if } (S, R, Z) \in \mathcal{M} \end{cases}$$

where $Z = \text{fresh}(S, R)$ and $\mathcal{M}' = \mathcal{M} \cup \{(S, R, Z)\}$, and

$$\begin{aligned}\langle \rho_{\mathbf{s}}(S), \rho_{\mathbf{r}}(R), \emptyset \rangle &= \langle \rho_{\mathbf{s}}(\mu X.S'(X)), \rho_{\mathbf{r}}(R), \emptyset \rangle \\ &= \begin{cases} \langle \mathbf{f}, \rho_{\mathbf{r}}(R), \emptyset \rangle & \text{if } \mathbf{s}(X) = 0 \\ \langle \rho_{\mathbf{s}}(\mu X.S'(X)), \rho_{\mathbf{r}}(R), \emptyset \rangle & \text{if } \mathbf{s}(X) > 0 \end{cases} \\ &= \begin{cases} \mathbf{f} & \text{if } \mathbf{s}(X) = 0 \\ \langle \rho_{\mathbf{s}}(\mu X.S'(X)), \rho_{\mathbf{r}}(R), \emptyset \rangle & \text{if } \mathbf{s}(X) > 0. \end{cases}\end{aligned}$$

If $\mathbf{s}(X) = 0$ then this case is trivial since there is by definition a (C, C_0) -quasi-simulation between any fixed-point T_μ -strategy and \mathbf{f} , as well as between any fixed-point variable Z and \mathbf{f} . If $\mathbf{s}(X) > 0$ and $(S, R, Z) \in \mathcal{M}$ then there is by definition a (C, C_0) -quasi-simulation between Z and $\mathcal{NF}(\langle \rho_{\mathbf{s}}(\mu X.S'(X)), \rho_{\mathbf{r}}(R), \emptyset \rangle)$. If $\mathbf{s}(X) > 0$ and $(S, R, \cdot) \notin \mathcal{M}$ then it follows from Eq. (51) of Lemma 71 that there exist a fixed-point free T_μ -strategy $\tilde{S}(X^1, \dots, X^m)$ and T_μ -strategies $S_1, \dots, S_{m-1}, S_m(X)$, with $m \geq 1$, such that $S'(X)$ can be written as $S'(X) = \tilde{S}(S_1, \dots, S_{m-1}, S_m(X))$. On the one hand, $S'(S) = \tilde{S}(S_1, \dots, S_{m-1}, S_m(S))$. On the other hand,

$$\rho_{\mathbf{s}}(\mu X.S'(X)) = \tilde{S}(\rho_{\mathbf{s}}(S_1), \dots, \rho_{\mathbf{s}}(S_{m-1}), \rho_{\mathbf{s}'}(S_m(\mu X.S'(X))))$$

where $\mathbf{s}'(X) = \mathbf{s}(X) - 1$ and $\mathbf{s}'(X') = \mathbf{s}(X')$ for $X' \neq X$. This brings us back to the case 2 above in which the induction hypothesis can be applied on each $\rho_{\mathbf{s}}(S_i)$, for $i = 1, \dots, m-1$ and for $\rho_{\mathbf{s}'}(S_m(\mu X'.S'(X')))$. \square

Lemma 90. Let S and R be \mathbb{T}_μ -strategies with bound fixed-point variables $\text{Bound}(S) = \{X_1, \dots, X_s\}$ and $\text{Bound}(R) = \{Y_1, \dots, Y_r\}$. Let $\mathbf{s} : \{X_1, \dots, X_s\} \rightarrow \mathbb{N}$ and $\mathbf{r} : \{Y_1, \dots, Y_r\} \rightarrow \mathbb{N}$ be iteration mappings. Let ϕ_μ be the mapping induced by the $(\mathcal{C}, \mathcal{C}_0)$ -quasi-simulation \mathfrak{S} between $S \wedge R$ and $\rho_{\mathbf{s}}(S) \wedge \rho_{\mathbf{r}}(R)$ constructed in the proof of Lemma 87. The mapping ϕ_μ enjoys the following properties.

1. For any fixed-point \mathbb{T}_μ -strategy \mathbf{T} in $S \wedge R$, there exist \mathbb{T}_μ -strategies $\mu X'.S'(X')$ and R' , mappings $\mathbf{s}' : \{X_1, \dots, X_s\} \rightarrow \mathbb{N}$ and $\mathbf{r}' : \{Y_1, \dots, Y_r\} \rightarrow \mathbb{N}$, and a memory \mathcal{M}' such that one of the four following cases holds.
 - (a) $\mathbf{T} = \mathcal{NF}(\mu X'.S'(X'), R', \mathcal{M}')$ and $\phi_\mu(\mathbf{T}) = (\rho_{\mathbf{s}'}(\mu X'.S'(X')) \wedge \rho_{\mathbf{r}'}(R'))$.
 - (b) $\mathbf{T} = \mathcal{NF}(R', \mu X'.S'(X'), \mathcal{M}')$ and $\phi_\mu(\mathbf{T}) = (\rho_{\mathbf{r}'}(R') \wedge \rho_{\mathbf{s}'}(\mu X'.S'(X')))$.
 - (c) $\mathbf{T} = \mu X'.S'(X')$, with $X' \in \{X_1, \dots, X_s\}$ and $\mu X'.S'(X') \in \Phi_\mu(S)$, and $\phi_\mu(\mathbf{T}) = \rho_{\mathbf{s}'}(\mu X'.S'(X'))$.
 - (d) $\mathbf{T} = \mu X'.S'(X')$, with $X' \in \{Y_1, \dots, Y_r\}$ and $\mu X'.S'(X') \in \Phi_\mu(R)$, and $\phi_\mu(\mathbf{T}) = \rho_{\mathbf{r}'}(\mu X'.S'(X'))$.
2. For any fixed-point sequence

$$\mathbf{T}_1 \sqsubset \dots \sqsubset \mathbf{T}_m$$

in $\mathcal{T}(S \wedge R)$ with $m \geq 1$ and for any $i = 1, \dots, m$, there are iteration mappings $\mathbf{s}_i : \{X_1, \dots, X_s\} \rightarrow \mathbb{N}$ and $\mathbf{r}_i : \{Y_1, \dots, Y_r\} \rightarrow \mathbb{N}$, such that one of the following two cases holds:

- (a) There is a \mathbb{T}_μ -strategy $S_i(X^i) \in \Phi(S)$ with $X^i \in \{X_1, \dots, X_s\}$, and a \mathbb{T}_μ -strategy $R_i \in \Phi(R)$ such that

$$\phi_\mu(\mathbf{T}_i) = \rho_{\mathbf{s}_i}(\mu X^i.S_i(X^i)) \wedge \rho_{\mathbf{r}_i}(R_i),$$

and for $i = 1, \dots, m-1$ and for any $X \in \{X_1, \dots, X_s\}$ and any $Y \in \{Y_1, \dots, Y_r\}$, we have that

$$\mathbf{s}_{i+1}(X) = \begin{cases} \mathbf{s}_i(X), & \text{if } X \neq X^i \\ \mathbf{s}_i(X^i) - 1, & \text{if } X = X^i \end{cases} \quad \text{and} \quad \mathbf{r}_{i+1}(Y) = \mathbf{r}_i(Y) \quad (63)$$

- (b) There is a \mathbb{T}_μ -strategy $S_i \in \Phi(S)$, and a \mathbb{T}_μ -strategy $R_i(Y^i) \in \Phi(R)$ with $Y^i \in \{Y_1, \dots, Y_r\}$, such that

$$\phi_\mu(\mathbf{T}_i) = \rho_{\mathbf{s}_i}(S_i) \wedge \rho_{\mathbf{r}_i}(\mu Y^i.R_i(Y^i)),$$

and for $i = 1, \dots, m-1$ and for any $X \in \{X_1, \dots, X_s\}$ and any $Y \in \{Y_1, \dots, Y_r\}$, we have that

$$\mathbf{s}_{i+1}(X) = \mathbf{s}_i(X) \quad \text{and} \quad \mathbf{r}_{i+1}(Y) = \begin{cases} \mathbf{r}_i(Y), & \text{if } Y \neq Y^i \\ \mathbf{r}_i(Y^i) - 1, & \text{if } Y = Y^i \end{cases} \quad (64)$$

Proof. 1. For Item 1, we just replaced the $(\mathcal{C}, \mathcal{C}_0)$ -quasi-simulation relation \mathfrak{S} of Lemma 88 by its induced mapping ϕ_μ .
 2. For Item 2, we consider a fixed-point \mathbb{T}_μ -strategy \mathbf{T}_i in $\mathcal{T}(S \wedge R)$ with $i \in \{1, \dots, m-1\}$, and we shall see that Eq. (63) and Eq. (64) hold for any \mathbb{T}_μ -strategy \mathbf{T} in $\mathcal{T}(S \wedge R)$ such that

$$\mathbf{T}_i \sqsubset \mathbf{T}.$$

For this purpose, assume that

$$\phi_\mu(\mathbf{T}_i) = \rho_{\mathbf{s}_i}(\mu X^i.S_i(X^i)) \wedge \rho_{\mathbf{r}_i}(R_i) \quad (65)$$

since the case when

$$\phi_\mu(\mathbf{T}_i) = \rho_{\mathbf{s}_i}(S_i) \wedge \rho_{\mathbf{r}_i}(\mu Y^i.R_i(Y^i)) \quad (66)$$

can be handled similarly. It follows from Eq. (51) of Lemma 71 that there is a \mathbb{T}_μ -strategy \tilde{S} such that $\rho_{\mathbf{s}_i}(\mu X^i.S_i(X^i))$ can be written as

$$\rho_{\mathbf{s}_i}(\mu X^i.S_i(X^i)) = \rho_{\mathbf{s}'_i}(\tilde{S}) \quad \text{where} \quad \mathbf{s}'_i(X) = \begin{cases} \mathbf{s}_i(X) & \text{if } X \neq X^i \\ \mathbf{s}_i(X) - 1 & \text{if } X = X^i. \end{cases} \quad (67)$$

On the other hand, notice that there is a fixed-point free \mathbb{T}_μ -strategy $\hat{S}^i(X_1, \dots, X_k)$ (resp. $\hat{R}^i(Y_1, \dots, Y_l)$) with $k \geq 1$ (resp. $l \geq 1$), and fixed-point \mathbb{T}_μ -strategies ξ_1, \dots, ξ_k (resp. ζ_1, \dots, ζ_k) each one is in $\Phi_\mu(S)$ (resp. $\Phi_\mu(R)$), such that $\rho_{\mathbf{s}'_i}(\tilde{S})$ (resp. $\rho_{\mathbf{r}_i}(R_{i+1})$) can be written as

$$\begin{aligned} \rho_{\mathbf{s}'_i}(\tilde{S}) &= \hat{S}^i(\rho_{\mathbf{s}'_i}(\xi_1), \dots, \rho_{\mathbf{s}'_i}(\xi_k)) \\ \rho_{\mathbf{r}_i}(R_{i+1}) &= \hat{R}^i(\rho_{\mathbf{r}_i}(\zeta_1), \dots, \rho_{\mathbf{r}_i}(\zeta_l)). \end{aligned}$$

It follows from the composition Lemma 73 that there is a fixed-point free T_μ -strategy $T_i(Z_1, \dots, Z_m)$ such that

$$\begin{aligned}\phi_\mu(\mathbf{T}_i) &= \rho_{\mathbf{s}_i}(\mu X^i . S_i(X^i)) \wedge \rho_{\mathbf{r}_i}(R_i) \\ &= \hat{S}^i(\rho_{\mathbf{s}'_i}(\xi_1), \dots, \rho_{\mathbf{s}'_i}(\xi_k)) \wedge \hat{R}^i(\rho_{\mathbf{r}_i}(\zeta_1), \dots, \rho_{\mathbf{r}_i}(\zeta_l)) \\ &= T(\alpha_1, \dots, \alpha_m)\end{aligned}$$

such that for any $v = 1, \dots, m$, one of the following two cases holds.

- (a) There is $w \in \{1, \dots, k\}$, and a T_μ -strategy $\tilde{R}^v(Y^1, \dots, Y^l)$ that is a sub- T_μ -strategy of $\hat{R}^i(Y_1, \dots, Y_l)$ with $l' \leq l$, and a set $\{\zeta^1, \dots, \zeta^{l'}\} \subseteq \{\zeta_1, \dots, \zeta_l\}$ such that

$$\alpha_v = \rho_{\mathbf{s}'_i}(\xi_w) \wedge \tilde{R}^v(\rho_{\mathbf{r}_i}(\zeta^1), \dots, \rho_{\mathbf{r}_i}(\zeta^{l'})) \quad \text{or} \quad \alpha_v = \rho_{\mathbf{s}'_i}(\xi_w).$$

But since $\tilde{R}^v(\rho_{\mathbf{r}_i}(\zeta^1), \dots, \rho_{\mathbf{r}_i}(\zeta^{l'})) = \rho_{\mathbf{r}_i}(\tilde{R}^v(\zeta^1, \dots, \zeta^{l'}))$, $\mathbf{T}_i \sqsupset \phi_\mu^{-1}(\alpha_v)$, and the iteration mappings s'_i and s_i satisfy Eq. (67), then we get Eq. (63).

- (b) There is $w \in \{1, \dots, k\}$, and a T_μ -strategy $\tilde{S}^v(X^1, \dots, X^{k'})$ that is a sub- T_μ -strategy of $\hat{S}^i(X_1, \dots, X_k)$ with $k' \leq k$, and a set $\{\xi^1, \dots, \xi^{k'}\} \subseteq \{\xi_1, \dots, \xi_k\}$ such that

$$\alpha_v = \tilde{S}^v(\rho_{\mathbf{s}'_i}(\xi^1), \dots, \rho_{\mathbf{s}'_i}(\xi^{k'})) \wedge \rho_{\mathbf{r}_i}(\zeta_w) \quad \text{or} \quad \alpha_v = \rho_{\mathbf{r}_i}(\zeta_w).$$

But since $\tilde{S}^v(\rho_{\mathbf{r}_i}(\xi^1), \dots, \rho_{\mathbf{r}_i}(\xi^{k'})) = \rho_{\mathbf{r}_i}(\tilde{S}^v(\xi^1, \dots, \xi^{k'}))$ and then we have $\mathbf{T}_i \sqsupset \phi_\mu^{-1}(\alpha_v)$, and the iteration mappings s'_i and s_i satisfy Eq. (67), then we get Eq. (63).

In summary, we assumed that $\phi_\mu(\mathbf{T}_i)$ satisfies Eq. (65) and we get Eq. (63). However if we assume that $\phi_\mu(\mathbf{T}_i)$ satisfies Eq. (66) then we get Eq. (64) by similar arguments. \square

D. Proofs for Section 12

Before proving Lemma 96, we want to get a certain fixed-point T_μ -strategy from each \mathbf{T}_i of the sequence \mathcal{S} . More precisely, notice that for any $i \in \{1, \dots, m\}$, one of the following situations holds.

- i.) If $\mathbf{T}_i = \mathcal{NF}(S_i, R_i, \mathcal{M}_i)$, then either S_i is a fixed-point T_μ -strategy regardless of R_i that could be a fixed-point T_μ -strategy as well, or R_i is a fixed-point T_μ -strategy and S_i is not. In the first case we want to get S_i , and in the second we want to get R_i .
- ii.) Otherwise, if \mathbf{T}_i is a fixed-point sub- T_μ -strategy of S or R , then we want to get \mathbf{T}_i .

The formal definition follows.

Definition 91. For any $i \in \{1, \dots, m\}$, we define

$$\Omega_\mu(\mathbf{T}_i) = \begin{cases} S_i & \text{if } \mathbf{T}_i = \mathcal{NF}(S_i, R_i, \mathcal{M}_i) \text{ and } S_i \in \Phi_\mu(S) \\ R_i & \text{if } \mathbf{T}_i = \mathcal{NF}(S_i, R_i, \mathcal{M}_i) \text{ and } R_i \in \Phi_\mu(R) \\ \mathbf{T}_i & \text{if } \mathbf{T}_i \in \tilde{\Phi}_\mu(S) \cup \tilde{\Phi}_\mu(R). \end{cases}$$

We need the following simple Fact.

Fact 92. For any finite sets $A, A', B, B' \subset \mathbb{N}$,

- (i) if $\max(A) \leq \max(A')$ and if $\max(B) \leq \max(B')$ then $\max(A \cup B) \leq \max(A' \cup B')$.
- (ii) Therefore, to show that $\max(A \cup B) \leq \max(A' \cup B')$, it suffices to show that $\max(A) \leq \max(A')$ and $\max(B) \leq \max(B')$.

Lemma 96. For any left-maximal sequence

$$\mathbf{T}_1 \sqsupset \dots \sqsupset \mathbf{T}_m$$

in \mathcal{T} with $m \geq 2$, and for any p and q where $1 \leq p < q \leq m$,

1. If for $i = 1, \dots, q$, there are T_μ -strategies $S_i \in \tilde{\Phi}(S)$ and $R_i \in \tilde{\Phi}(R)$, and iteration mappings $\mathbf{s}_i : \{X_1, \dots, X_s\} \rightarrow \mathbb{N}$ and $\mathbf{r}_i : \{Y_1, \dots, Y_s\} \rightarrow \mathbb{N}$ such that

$$\phi_\mu(\mathbf{T}_i) = \rho_{\mathbf{s}_i}(S_i) \wedge \rho_{\mathbf{r}_i}(R_i)$$

then

$$\omega(\mathbf{T}_q) \in \{D^*((\mathbf{s}_1, \mathbf{r}_1), (\mathbf{s}_q, \mathbf{r}_q)), D^*((\mathbf{s}_1, \mathbf{r}_1), (\mathbf{s}_q, \mathbf{r}_q)) - 1\}. \quad (68)$$

2. If there is a τ_μ -strategy $\xi_m \in \tilde{\Phi}(S) \cup \tilde{\Phi}(R)$ and an iteration mapping \mathbf{s}_m such that

$$\phi_\mu(\mathbf{T}_m) = \rho_{\mathbf{s}_m}(\xi_m)$$

then

$$\min\{\mathbf{s}_m(X) \mid X \in \text{dom}(\mathbf{s}_m)\} \geq \mathbf{D}^*(\mathbf{T}_m). \quad (69)$$

Proof. 1. Since $\omega(\mathbf{T}_q) = n - \Omega^\#(\mathbf{T}_1, \mathbf{T}_q)$, showing Eq. (68) amounts to show

$$n - \Omega^\#(\mathbf{T}_1, \mathbf{T}_q) \in \{D^*((\mathbf{s}_1, \mathbf{r}_1), (\mathbf{s}_q, \mathbf{r}_q)), D^*((\mathbf{s}_1, \mathbf{r}_1), (\mathbf{s}_q, \mathbf{r}_q)) - 1\}. \quad (70)$$

Since $\mathbf{s}_1 \geq \mathbf{s}_q$ and $\mathbf{r}_1 \geq \mathbf{r}_q$, then for $v = 1, \dots, s$ there exist positive numbers α_v^q where $n - \alpha_v^q \geq 0$, and for $w = 1, \dots, r$, there exist positive numbers β_w^q where $n - \beta_w^q \geq 0$, such that the iteration mappings $\mathbf{s}_q, \mathbf{r}_q$ can be written as

$$\begin{cases} \mathbf{s}_q(X_v) &= n - \alpha_v^q \\ \mathbf{r}_q(Y_w) &= n - \beta_w^q. \end{cases}$$

On the one hand, from the Definition 74 of d^* and D^* , we get

$$\begin{aligned} d^*(\mathbf{s}_1, \mathbf{s}_q) &= \begin{cases} \min\{\mathbf{s}_q(X_v) \mid \mathbf{s}_q(X_v) \neq \mathbf{s}_1(X_v) \text{ for } v = 1, \dots, s\} & \text{if } \mathbf{s}_1 > \mathbf{s}_q \\ \infty & \text{if } \mathbf{s}_1 = \mathbf{s}_q \end{cases} \\ &= \begin{cases} \min\{n - \alpha_v^q \mid n - \alpha_v^q \neq n \text{ for } v = 1, \dots, s\} & \text{if } \mathbf{s}_1 > \mathbf{s}_q \\ \infty & \text{if } \mathbf{s}_1 = \mathbf{s}_q \end{cases} \\ &= \begin{cases} n - \max\{\alpha_v^q \mid \text{for } v = 1, \dots, s\} & \text{if } \mathbf{s}_1 > \mathbf{s}_q \\ \infty & \text{if } \mathbf{s}_1 = \mathbf{s}_q. \end{cases} \end{aligned}$$

Similarly

$$d^*(\mathbf{r}_1, \mathbf{r}_q) = \begin{cases} n - \max\{\beta_w^q \mid \text{for } w = 1, \dots, r\} & \text{if } \mathbf{r}_1 > \mathbf{r}_q \\ \infty & \text{if } \mathbf{r}_1 = \mathbf{r}_q. \end{cases}$$

Let

$$\mathbf{m}_S = \max\{\alpha_v^q \mid \text{for } v = 1, \dots, s\}$$

$$\mathbf{m}_R = \max\{\beta_w^q \mid \text{for } w = 1, \dots, r\}.$$

Hence

$$\begin{aligned} D^*((\mathbf{s}_1, \mathbf{s}_q), d^*(\mathbf{r}_1, \mathbf{r}_q)) &= \min(d^*(\mathbf{s}_1, \mathbf{s}_q), d^*(\mathbf{r}_1, \mathbf{r}_q)) \\ &= \begin{cases} \min(n - \mathbf{m}_S, n - \mathbf{m}_R) & \text{if } \mathbf{s}_q > \mathbf{s}_1 \text{ and } \mathbf{r}_q > \mathbf{r}_1 \\ n - \mathbf{m}_S & \text{if } \mathbf{s}_q > \mathbf{s}_1 \text{ and } \mathbf{r}_q = \mathbf{r}_1 \\ n - \mathbf{m}_R & \text{if } \mathbf{s}_q = \mathbf{s}_1 \text{ and } \mathbf{r}_q > \mathbf{r}_1 \end{cases} \\ &= \begin{cases} n - \max(\mathbf{m}_S, \mathbf{m}_R) & \text{if } \mathbf{s}_q > \mathbf{s}_1 \text{ and } \mathbf{r}_q > \mathbf{r}_1 \\ n - \mathbf{m}_S & \text{if } \mathbf{s}_q > \mathbf{s}_1 \text{ and } \mathbf{r}_q = \mathbf{r}_1 \\ n - \mathbf{m}_R & \text{if } \mathbf{s}_q = \mathbf{s}_1 \text{ and } \mathbf{r}_q > \mathbf{r}_1 \end{cases} \end{aligned}$$

On the other hand, since $\mathbf{T}_i = \mathcal{NF}(\langle S_i, R_i, \mathcal{M}_i \rangle)$, for $i = 1, \dots, q$, then consider the sequence of tuples

$$\mathcal{S}_q = \langle S_1, R_1, \mathcal{M}_1 \rangle, \dots, \langle S_q, R_q, \mathcal{M}_q \rangle$$

and recall the definition of $\Omega^\#(\mathbf{T}_1, \mathbf{T}_q)$ from Eq. (21) of Definition 94:

$$\Omega^\#(\mathbf{T}_1, \mathbf{T}_q) = \max\{\#_{\mathcal{S}_q}(S_i), \#_{\mathcal{S}_q}(R_i) \mid S_i \in \tilde{\Phi}_\mu(S), R_i \in \tilde{\Phi}_\mu(R), i = 1, \dots, q\}.$$

We distinguish three cases depending on the iteration mappings $\mathbf{s}_1, \mathbf{s}_q, \mathbf{r}_1, \mathbf{r}_q$.

- If $\mathbf{s}_q = \mathbf{s}_1$ then $d^*(\mathbf{s}_1, \mathbf{s}_q) = \infty$, and $\mathbf{r}_q > \mathbf{r}_1$ and hence $d^*(\mathbf{r}_1, \mathbf{r}_q) = n - \mathbf{m}_R$. In this case $\max\{\#_{S_q}(S_i) \mid S_i \in \tilde{\Phi}_\mu(S), i = 1, \dots, q\} \in \{0, 1\}$ and $\max\{\#_{S_q}(R_i) \mid R_i \in \tilde{\Phi}_\mu(R), i = 1, \dots, q\} \geq 1$, and hence $\Omega^\#(\mathbf{T}_1, \mathbf{T}_q) = \max\{\#_{S_q}(R_i) \mid R_i \in \tilde{\Phi}_\mu(R), i = 1, \dots, q\}$. Therefore, in this case showing Eq. (70) amounts to show that

$$n - \max\{\#_{S_q}(R_i) \mid R_i \in \tilde{\Phi}_\mu(R), i = 1, \dots, q\} \in \{n - \mathbf{m}_R, n - \mathbf{m}_R - 1\}, i.e.$$

$$\max\{\#_{S_q}(R_i) \mid R_i \in \tilde{\Phi}_\mu(R), i = 1, \dots, q\} \in \{\mathbf{m}_R, \mathbf{m}_R + 1\}.$$

- If $\mathbf{r}_q = \mathbf{r}_1$ then $d^*(\mathbf{r}_1, \mathbf{r}_q) = \infty$, and $\mathbf{s}_q > \mathbf{s}_1$ and hence $d^*(\mathbf{s}_1, \mathbf{s}_q) = n - \mathbf{m}_S$. With similar reasoning, in this case we need to show that

$$\max\{\#_{S_q}(S_i) \mid S_i \in \tilde{\Phi}_\mu(S), i = 1, \dots, q\} \in \{\mathbf{m}_S, \mathbf{m}_S + 1\}.$$

- If $\mathbf{s}_q > \mathbf{s}_1$ and $\mathbf{r}_q > \mathbf{r}_1$ then $d^*(\mathbf{s}_1, \mathbf{s}_q) = n - \mathbf{m}_S$ and $d^*(\mathbf{r}_1, \mathbf{r}_q) = n - \mathbf{m}_R$. In this case showing Eq. (70) amounts to show

$$n - \max\{\#_{S_q}(S_i), \#_{S_q}(R_i) \mid S_i \in \tilde{\Phi}_\mu(S), R_i \in \tilde{\Phi}_\mu(R), i = 1, \dots, q\} \in$$

$$\{n - \max(\mathbf{m}_S, \mathbf{m}_R), n - \max(\mathbf{m}_S, \mathbf{m}_R) - 1\}.$$

That is,

$$\max\{\#_{S_q}(S_i), \#_{S_q}(R_i) \mid S_i \in \tilde{\Phi}_\mu(S), R_i \in \tilde{\Phi}_\mu(R), i \in [1, q]\} \in \{\max(\mathbf{m}_S, \mathbf{m}_R), \max(\mathbf{m}_S, \mathbf{m}_R) + 1\}.$$

It follows from Item (ii) of Fact 92 that to show Eq. (70) it suffices to show that

$$\begin{cases} \max\{\#_{S_q}(S_i) \mid S_i \in \tilde{\Phi}_\mu(S), i = 1, \dots, q\} & \in \{\mathbf{m}_S, \mathbf{m}_S + 1\} \\ \max\{\#_{S_q}(R_j) \mid R_j \in \tilde{\Phi}_\mu(R), j = 1, \dots, q\} & \in \{\mathbf{m}_R, \mathbf{m}_R + 1\}. \end{cases}$$

Summing up these three cases, to show Eq. (70) it suffices to assume that $\mathbf{s}_q > \mathbf{s}_1$ and to show

$$\max\{\#_{S_q}(S_i) \mid S_i \in \tilde{\Phi}_\mu(S), i = 1, \dots, q\} \in \{\mathbf{m}_S, \mathbf{m}_S + 1\} \quad (71)$$

Let $\xi \in \tilde{\Phi}_\mu(S) \cap \{S_1, \dots, S_q\}$ be a fixed-point T_μ -strategy. Indeed, ξ appears $\#_{S_q}(\xi)$ times in S_q and let \tilde{q} be the greatest $i \in \{1, \dots, q\}$ such that $\xi = S_i$. Since ξ is by definition a fixed-point T_μ -strategy, then it can be written as $\xi = \mu X_{\tilde{v}}. \tilde{S}(X_{\tilde{v}})$, for some $\tilde{v} \in \{1, \dots, s\}$ and for some T_μ -strategy $\tilde{S}(X_{\tilde{v}}) \in \tilde{\Phi}(S)$. To show Eq. (71), it suffices to show that either

(i) $\tilde{q} = q$ and in this case $\#_{S_q}(\xi) = \alpha_{\tilde{v}}^q + 1$, or

(ii) $\tilde{q} \neq q$ and in this case $\#_{S_q}(\xi) = \alpha_{\tilde{v}}^q$.

The proof is by induction on q . For the base case $q = 1$, we claim that S_1 is a fixed-point T_μ -strategy because otherwise $\mathbf{s}_1 = \mathbf{s}_2$ which contradicts the assumption $\mathbf{s}_2 > \mathbf{s}_1$. Hence let $S_1 = \xi$. Recall that $\mathbf{s}_1(X_v) = n$ for $v = 1, \dots, s$. In this case it follows from Eq. (63) of Item 2 of Lemma 90 that $\mathbf{s}_2(X_{\tilde{v}}) = \mathbf{s}_1(X_{\tilde{v}}) - 1 = n - 1$ and that $\mathbf{s}_2(X_v) = \mathbf{s}_1(X_v)$ for any $v \in \{1, \dots, s\} \setminus \{\tilde{v}\}$. That is, $\alpha_{\tilde{v}}^2 = 1$, and $\alpha_v^2 = 0$ for any $v \neq \tilde{v}$.

(i) If $S_2 = \xi$, i.e. $\tilde{q} = q = 2$, then $\#_{S_q}(\xi) = 2 = \alpha_{\tilde{v}}^2 + 1$.

(ii) If $S_2 \neq \xi$, i.e. $\tilde{q} = 1 \neq q = 2$, then in this case $\#_{S_q}(\xi) = 1 = \alpha_{\tilde{v}}^2$.

For the induction step assume that the claim holds for q and let us prove it for $q + 1$.

(1) If $S_q = \xi$, then by the induction hypothesis $\#_{S_q}(\xi) = \alpha_{\tilde{v}}^q + 1$. Besides, from Eq. (63) of Item 2 of Lemma 90 we have that $\alpha_{\tilde{v}}^{q+1} = \alpha_{\tilde{v}}^q + 1$.

(i) If $S_{q+1} = \xi$, i.e. $\tilde{q} = q + 1$, then in this case we have $\#_{S_{q+1}}(\xi) = \#_{S_q}(\xi) + 1 = (\alpha_{\tilde{v}}^q + 1) + 1 = \alpha_{\tilde{v}}^{q+1} + 1$.

(ii) If $S_{q+1} \neq \xi$, i.e. $\tilde{q} = q$, then in this case we have $\#_{S_{q+1}}(\xi) = \#_{S_q}(\xi) = \alpha_{\tilde{v}}^q + 1 = \alpha_{\tilde{v}}^{q+1}$.

(2) If $S_q \neq \xi$, then by the induction hypothesis $\#_{S_q}(\xi) = \alpha_{\tilde{v}}^q$. Besides, from Eq. (63) of Item 2 of Lemma 90 we have that $\alpha_{\tilde{v}}^{q+1} = \alpha_{\tilde{v}}^q$.

(i) If $S_{q+1} = \xi$, i.e. $\tilde{q} = q + 1$, then in this case we have $\#_{S_{q+1}}(\xi) = \#_{S_q}(\xi) + 1 = \alpha_{\tilde{v}}^q + 1 = \alpha_{\tilde{v}}^{q+1} + 1$.

(ii) If $S_{q+1} \neq \xi$, i.e. $\tilde{q} \neq q$ and $\tilde{q} \neq q + 1$, then in this case we have $\#_{S_{q+1}}(\xi) = \#_{S_q}(\xi) = \alpha_{\tilde{v}}^q = \alpha_{\tilde{v}}^{q+1}$.

2. To show Eq. (69), assume that $\xi_m \in \tilde{\Phi}(S)$, the case where $\xi_m \in \tilde{\Phi}(R)$ is similar. Let

$$\mathbf{m} = \min\{\mathbf{s}_m(X) \mid X \in \{X_1, \dots, X_s\}\}.$$

Recall from Eq. (25) of Definition 94 of \mathbf{D}^* that

$$\mathbf{D}^*(\mathbf{T}_m) = \begin{cases} n & \text{if } m = 1 \\ \min\{\mathbf{D}^*(\mathbf{T}_{m-1}), d^*(\mathbf{s}_1, \mathbf{s}_m)\} & \text{if } m > 1. \end{cases}$$

We want to show that $\mathbf{m} \geq \mathbf{D}^*(\mathbf{T}_{m-1})$. If $m = 1$ then $\mathbf{m} = n = \mathbf{D}^*(\mathbf{T}_m)$, hence the claim trivially holds. If $m > 1$ then $\mathbf{D}^*(\mathbf{T}_m) = \min \{ \mathbf{D}^*(\mathbf{T}_{m-1}), d^*(\mathbf{s}_1, \mathbf{s}_m) \}$ and in this case we distinguish two cases depending on \mathbf{s}_m . If $\mathbf{s}_m = \mathbf{s}_1$ then $\mathbf{m} = n$, $\mathbf{D}^*(\mathbf{T}_{m-1}) < n$ and $d^*(\mathbf{s}_1, \mathbf{s}_m) = \infty$, thus $\mathbf{D}^*(\mathbf{T}_m) = \mathbf{D}^*(\mathbf{T}_{m-1}) < n = \mathbf{m}$. Therefore, $\mathbf{m} \geq \mathbf{D}^*(\mathbf{T}_m)$. If $\mathbf{s}_m < \mathbf{s}_1$ then in this case $\mathbf{m} = d^*(\mathbf{s}_1, \mathbf{s}_m)$, which is obviously greater or equal to $\min \{ \mathbf{D}^*(\mathbf{T}_{m-1}), d^*(\mathbf{s}_1, \mathbf{s}_m) \}$. \square

Lemma 102. *Let*

$$\mu \hat{Z}_1. \hat{T}_1(\hat{Z}_1) \sqsupset \hat{T}_2$$

be a sequence in $\partial \mathcal{T}$. Define $\hat{T}_1^(Z)$ to be the (unique) T_μ -strategy satisfying*

$$\hat{T}_1^*(\hat{T}_2) = \hat{T}_1(\hat{Z}_1).$$

We have that

$$1 \leq \Pi_Z(\hat{T}_1^*(Z)). \quad (72)$$

Proof. The idea of the proof is to show that either (i) both $\mu \hat{Z}_1. \hat{T}_1(\hat{Z}_1)$ and \hat{T}_2 result from the unification of the same T_μ -strategy with another T_μ -strategy, i.e. $\Omega_\mu(\mu \hat{Z}_1. \hat{T}_1(\hat{Z}_1)) = \Omega_\mu(\hat{T}_2)$ and in this case we know from Lemma 64 that there is at least one jump between the root of $\mu \hat{Z}_1. \hat{T}_1(\hat{Z}_1)$ and \hat{T}_2 . Or, (ii) $\mu \hat{Z}_1. \hat{T}_1(\hat{Z}_1)$ and \hat{T}_2 result from the unification of different T_μ -strategies, i.e. $\Omega_\mu(\mu \hat{Z}_1. \hat{T}_1(\hat{Z}_1)) = \Omega_\mu(\hat{T}_2)$. In this case there must be a T_μ -strategy T that lies in \mathcal{T} between $\mu \hat{Z}_1. \hat{T}_1(\hat{Z}_1)$ and \hat{T}_2 such that $\Omega_\mu(T) = \Omega_\mu(\hat{T}_2)$. Hence there is at least one jump between the root of T and \hat{T}_2 , and therefore there is at least one jump between the root of $\mu \hat{Z}_1. \hat{T}_1(\hat{Z}_1)$ and \hat{T}_2 . We need the two following claims, where Claim 103 is used to prove Claim 104 which will be used to prove this Lemma.

Claim 103. *Consider a sequence $S_m: T_1 \sqsupset \dots \sqsupset T_m$ in \mathcal{T} where T_1 is the root of \mathcal{T} , with $m \geq 1$. For any $q = 1, \dots, m$, if there are two T_μ -strategies M, M' such that $\Omega^\#(T_1, T_q) = \#_{S_q}(M) = \#_{S_q}(M')$ then T_q is not in $\partial \mathcal{T}$.*

Proof. Assume that there are only two T_μ -strategies M and M' such that $\Omega^\#(T_1, T_q) = \#_{S_q}(M) = \#_{S_q}(M')$. The case where there are more than two can be handled similarly. Indeed, there is a T_μ -strategy T_p in S_q on which the number of occurrences of M (resp. or M') has reached the maximum while that of M' (resp. M) did not. More precisely, there is $p < q$ such that either $\Omega^\#(T_1, T_q) = \Omega^\#(T_1, T_p) = \#_{S_q}(M) = \#_{S_q}(M') + 1$ or $\Omega^\#(T_1, T_q) = \Omega^\#(T_1, T_p) = \#_{S_q}(M') = \#_{S_q}(M) + 1$. Assume that the first case holds since the second case can be handled similarly. Recall that $\omega(T_q) = \omega(T_p)$ since $\Omega^\#(T_1, T_q) = \Omega^\#(T_1, T_p)$. Towards a contradiction: assume that T_q is in $\partial \mathcal{T}$. If $T_p \in \partial \mathcal{T}$ then by Item (4) of Remark 101 we have $\omega(T_q) = \omega(T_p) + 1$, which is a contradiction. If T_p is not in $\partial \mathcal{T}$ then by Item (3) of Remark 101 we have $\omega(T_q) = \omega(T_p) + 1$, which is a contradiction. This ends the proof of Claim 103. \square

Claim 104. *Let \hat{T}_1 and \hat{T}_2 be two T_μ -strategies in $\partial \mathcal{T}$ where $\hat{T}_1 \sqsupset \hat{T}_2$. If $\Omega_\mu(\hat{T}_1) \neq \Omega_\mu(\hat{T}_2)$ then the sequence in \mathcal{T} that lies between \hat{T}_1 and \hat{T}_2 is not empty, and there exists a T_μ -strategy T in this sequence such that $\Omega_\mu(T) = \Omega_\mu(\hat{T}_2)$.*

Proof. Assume that $\Omega_\mu(\hat{T}_1) = M_1$ and $\Omega_\mu(\hat{T}_2) = M_2$. Let S_1 (resp. S_2) be the sequence in \mathcal{T} from the root of \mathcal{T} to \hat{T}_1 (resp. to \hat{T}_2). By Item (4) of Remark 101 we have $\#_{S_2}(M_2) = \#_{S_1}(M_1) + 1$. However, either there is at least one T_μ -strategy, say T , in \mathcal{T} in the sequence between \hat{T}_1 and \hat{T}_2 such that $\Omega_\mu(T) = \Omega_\mu(\hat{T}_2)$, or $\#_{S_1}(M_2) = \#_{S_1}(M_1)$. But this second possibility is not possible, since otherwise, by Claim 103 we would have had that \hat{T}_1 is not in $\partial(\mathcal{T})$ which contradicts the assumption of the current claim. This ends the proof of Claim 104. \square

To prove Lemma 102 we distinguish two cases depending whether the sequence in \mathcal{T} that lies between $\mu \hat{Z}_1. \hat{T}_1(\hat{Z}_1)$ and \hat{T}_2 is empty or not. Let S' be such sequence. If S' is empty, then it follows from Claim 104 that $\Omega_\mu(\mu \hat{Z}_1. \hat{T}_1(\hat{Z}_1)) = \Omega_\mu(\hat{T}_2)$. This means that during the unification process, the same T_μ -strategy which is a sub- T_μ -strategy of S or R appeared twice, which implies that there is a position jump between $T_1^*(Z)$ and Z . Or more formally, it follows from Lemma 64 that $1 \leq \Pi_Z(\hat{T}_1^*(Z))$. Otherwise, if the sequence S' is not empty then from Claim 104 it follows that there is a T_μ -strategy ζ in S' such that $\Omega_\mu(\zeta) = \Omega_\mu(\hat{T}_2)$. Since \hat{T}_2 is a sub- T_μ -strategy of ζ , then there is a unique T_μ -strategy $\zeta^*(Z)$ such that $\zeta^*(\hat{T}_2) = \zeta$. Thus by using the same Lemma 64 we deduce that $1 \leq \Pi_Z(\zeta^*)$. But since ζ is a sub- T_μ -strategy of $\hat{T}_1^*(\hat{T}_2)$, then $\zeta^*(Z)$ is a sub- T_μ -strategy of $\hat{T}_1^*(Z)$ and hence $1 \leq \Pi_Z(\hat{T}_1^*(Z))$ as well. This ends the proof of Lemma 102. \square

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