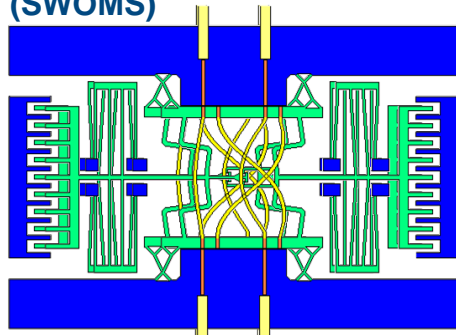


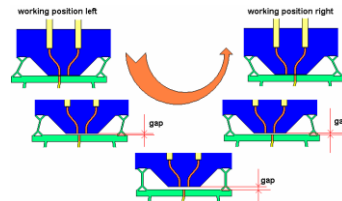
# 2X2 waveguide switch

## Self-latching Waveguides Optical MEMS Switch (SWOMS)



Legend: ■ Fixed parts ■ Moving parts ■ optic fiber  
— waveguide attaching to substrate — unattached w

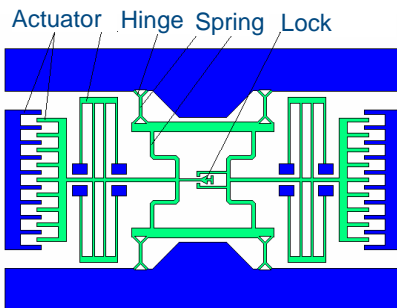
- 2×2 switch
- Latching
- Air gap-elimination



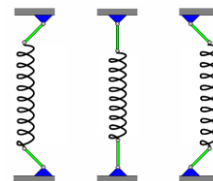
Liu HB., Chollet F., "Moving Polymer Waveguides and Latching Actuator for 2X2 MEMS Optical Switch", IEEE/ASME Journal of MEMS, doi:10.1109/JMEMS.2009.2017073, Vol. 18, No. 3, (2009) : 715-724

# Bi-stable micro-actuator

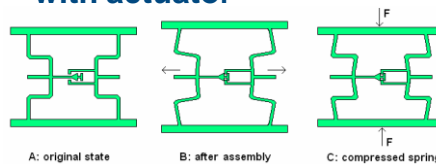
- Spring/hinge structure



Legend: ■ Fixed parts ■ Movable parts



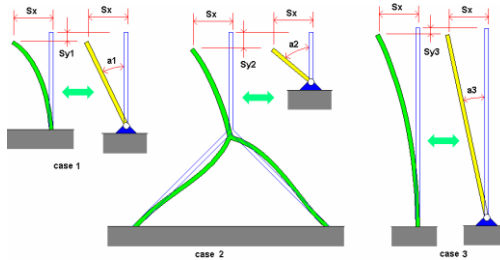
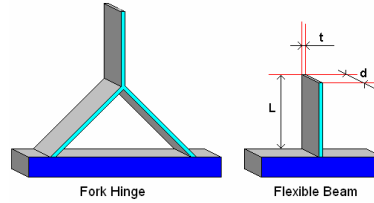
- Compressed state obtained with actuator



A: original state B: after assembly C: compressed spring

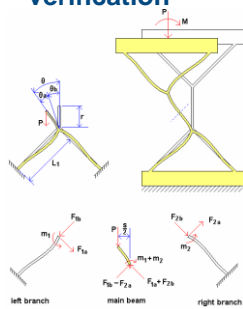
# Fork hinge structure

- No-gap feature needs a quasi-hinge better than a simple beam
- Novel Fork hinge structure
  - ➔ smaller
  - ➔ larger angle
  - ➔ more stable

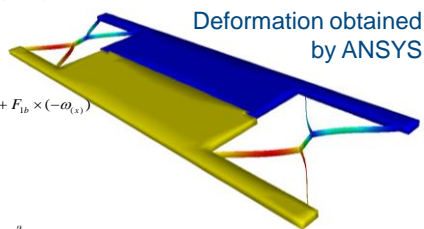


# Actuator design

- Analytical formulation of simplified model and numerical verification



$$\begin{cases} (F_{1b} - F_{2a}) \times \cos 45^\circ = (F_{1a} + F_{2b}) \times \cos 45^\circ \\ (F_{1b} - F_{2a}) \times \sin 45^\circ + (F_{1a} + F_{2b}) \times \sin 45^\circ = P \\ P \times \frac{s}{2} = m_1 + m_2 \\ \frac{d^2 \omega_{(x)}}{dx^2} = \frac{M_{(x)}}{E_{45} I} \\ M_{(x)} = m_1 - F_{1a} \times (L_1 - x) + F_{1b} \times (-\omega_{(x)}) \\ \theta_{(x)} = \frac{d\omega_{(x)}}{dx} \\ \omega_{(0)} = 0 \\ \frac{d\omega_{(0)}}{dx} = 0 \\ \omega_{(L_1)} = \Delta\omega \approx 0 \end{cases}$$



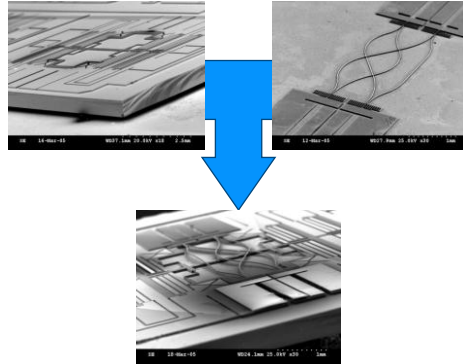
- Error is less than 7% and validate the use of the analytical model for the design

## Switch fabrication

- Switch is an opto-mechanical device and will use hybrid fabrication technique

- silicon actuator
- polymer waveguide
- final assembly

- Allows separate optimization of both structures

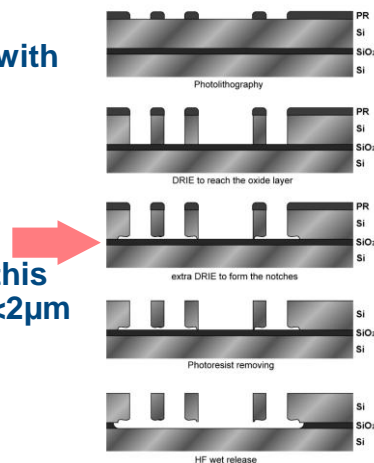


## Actuator fabrication

- Improved SOI/DRIE process with notching release

- PR mask patterning
- DRIE etching
- DRIE notching
- (Wet release)

- High success yield even for this huge system (5x6 mm) with <math><2\mu\text{m}</math> springs

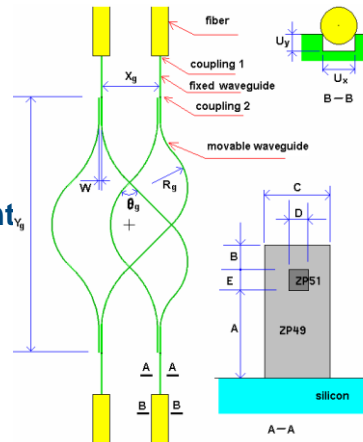
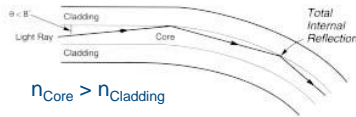


# Deformable polymer waveguide

## ■ Polymer as waveguide

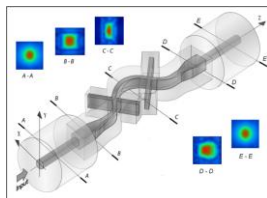
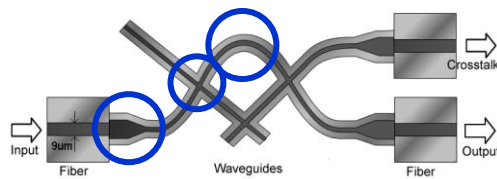
- Transparent
- Wide refractive index range
- Easy to process
- Easy to deform

## ■ Fluorinated polymers present low absorption in the NIR

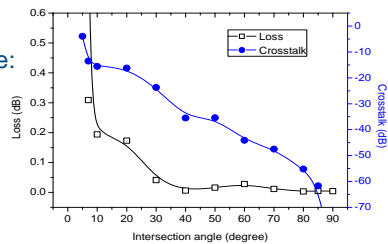


# Waveguide optimization

- Input/output taper dimension
- Intersection angle
- Radius of curvature
- Performed with 2D/3D BPM

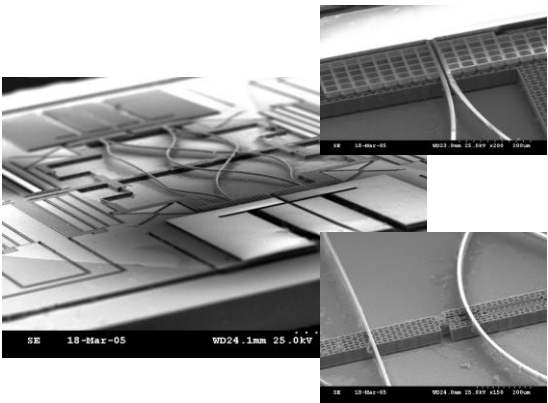
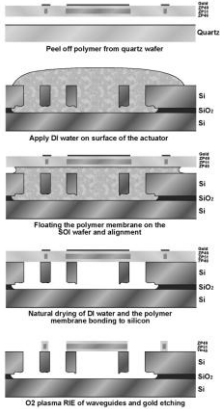


Optimized structure:  
 • loss: 0.12 dB  
 • crosstalk: -49 dB

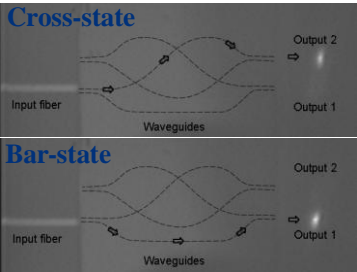
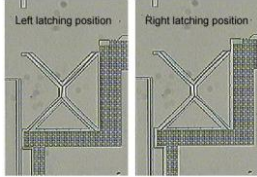
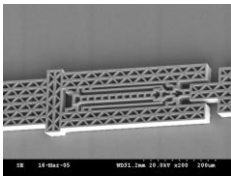


# Switch assembly

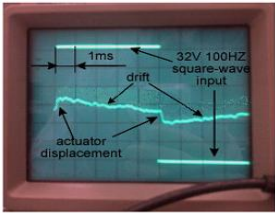
## Water based assembly



# Switch characterization



## Mechanical Test



- Assembly
- Switching
  - $V < 36V$
- Latching
- Switching speed
  - $< 0.5ms$

## Optical Test

- Loss components
  - Scattering 2.88dB/cm
  - Bending 0.25dB/cm
  - Intersection 0.1dB
  - Coupling 0.2dB
- Average 2.6dB